Lecture 9: Data-Parallel Computing on a Cluster (Spark)

Parallel Computing Stanford CS149, Fall 2024

Last Lecture's Theme: Data Parallel Thinking

Many of you are now likely accustomed to thinking about parallel programming in terms of "what workers do"

Today I would like you to think about describing algorithms in terms of operations on sequences of data

- map
- filter
- fold / reduce
- scan / segmented scan

- groupBy
- join

sort

- partition / flatten

Main idea: high-performance parallel implementations of these operations exist. So programs written in terms of these primitives can often run efficiently on a parallel machine *

* if you can avoid being bandwidth bound

Today's Theme

How do you program with 10,000–100,000 cores?

How do you ensure you don't loose data if some component of the system fails? Programming model: data parallel operations

Make data parallel operations:

- Scalable (100, 000 cores)
- Fault-tolerant (don't loose data when something fails)
- Efficient (optimize system performance with efficient use of memory)
 Focus on low arithmetic intensity data processing applications ⇒ memory
 bandwidth bound

Why Use A Cluster?

Want to process 100TB of log data (1 day @Facebook)

On 1 node: scanning @ 50MB/s = 23 days

On 1000 nodes: scanning @ 50MB/s = 33 min

But, very hard to utilize 1000 or 100,000 nodes!

- Hard to program 16,000 cores
- Something breaks every hour
- Need efficient, reliable and usable framework

Warehouse Size Cluster



Warehouse-Scale Computers (WSC)

Standard architecture:

-Cluster of commodity Linux nodes (multicore x86)

-Private memory \Rightarrow separate address spaces & separate OS

-Ethernet network \Rightarrow >10–40Gb today

Cheap?

-Built from commodity processors, networks & storage

-1000s of nodes for < \$10M

- WSC network is customized and expensive

-Use a supercomputer networking ideas to provide high bandwidth across the datacenter

How to organize computations on this architecture?

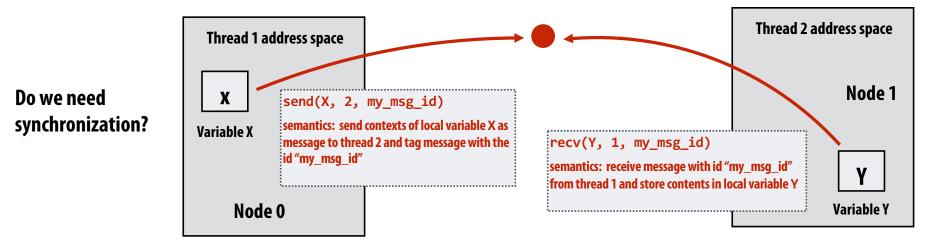
-Mask issues such as load balancing and failures

Message passing model (abstraction)

Distributed memory communication without shared memory

Threads operate within their own private address spaces Threads communicate by sending/receiving messages

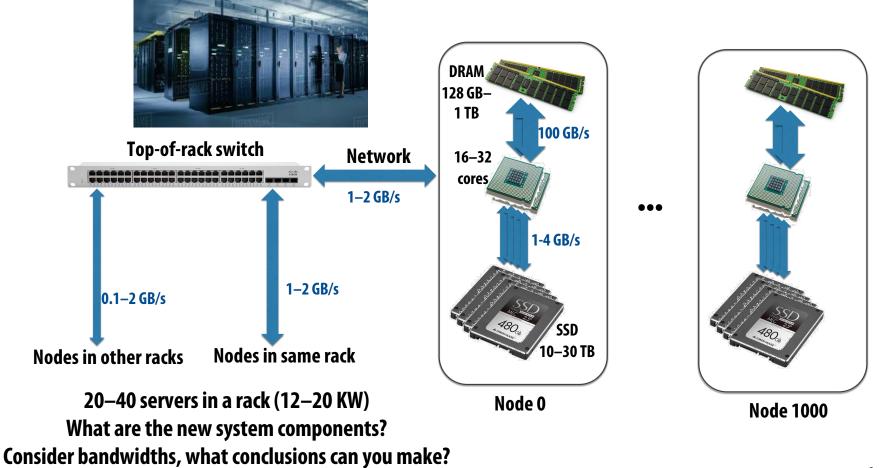
- send: specifies recipient, buffer to be transmitted, and optional message identifier ("tag")
- receive: sender, specifies buffer to store data, and optional message identifier
- Sending messages is the only way to exchange data between threads 1 and 2



(Communication operations shown in red)

Illustration adopted from Culler, Singh, Gupta

Warehouse-Scale Cluster Node (Server)



Computer Component Reliability

Component	MTTF (Mean Time to Failure)	
CPU (Central Processing Unit)	10 - 20 years	
Memory (RAM)	5 - 20 years	
SSD (Solid State Drive)	5 - 10 years	
HDD (Hard Disk Drive)	3 - 5 years	
Power Supply Unit (PSU)	5 - 10 years	
Motherboard	10 - 20 years	
GPU (Graphics Processing Unit)	5 - 10 years	
Cooling Fans	2 - 5 years	

Computer System Reliability

System MTTF =
$$\frac{1}{\sum_{i=1}^{n} \frac{1}{MTTF_i}}$$

Component	1 unit MTTF	10,000 units MTTF
CPU (Central Processing Unit)	10 - 20 years	15.0 hours
Memory (RAM)	5 - 20 years	11.0 hours
SSD (Solid State Drive)	5 - 10 years	10.0 hours
HDD (Hard Disk Drive)	3 - 5 years	3.75 hours
Power Supply Unit (PSU)	5 - 10 years	7.5 hours
Motherboard	10 - 20 years	15.0 hours
GPU (Graphics Processing Unit)	5 - 10 years	7.5 hours
Cooling Fans	2 - 5 years	3.5 hours

Storage Systems

First order problem: if nodes can fail, how can we store data persistently?

Answer: Distributed File System

- Provides global file namespace
- Google GFS, Hadoop HDFS

Typical usage pattern

- Huge files (100s of GB to TB)
- Data is rarely updated in place
- Reads and appends are most common (e.g. log files)

Distributed File System (GFS)

Chunk servers

- a.k.a. DataNodes in HDFS
- File is split into contiguous chunks (usually 64–256 MB)
- Each chunk replicated (usually 2x or 3x)
- Try to keep replicas in different racks

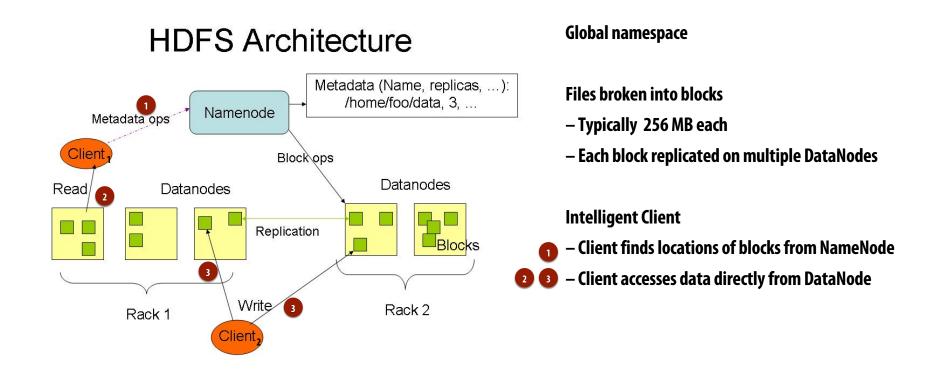
Master node

- a.k.a. NameNode in HDFS
- Stores metadata; usually replicated

Client library for file access

- Talks to master to find chunk (data) servers
- Connects directly to chunk servers to access data

Hadoop Distributed File System (HDFS)



Let's say CS149 gets very popular...

A log of page views on the course web site

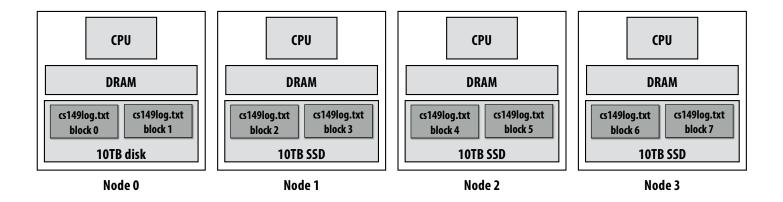
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The log of page views gets quite large...

Assume cs149log.txt is a large file, stored in a distributed file system, like HDFS

Below: cluster of 4 nodes, each node with a 10 TB SSD Contents of cs149log.txt are distributed evenly in blocks across the cluster



Imagine your professors want to know a bit more about the glut of students visiting the CS149 web site...

For example: "What type of mobile phone are all these students using?"

How about using message passing to write this application M P I = Message Passing Interface

Мар

Higher order function (function that takes a function as an argument)

Applies side-effect free unary function $f :: a \rightarrow b$ to all elements of input sequence, to produce output sequence of the same length

In a functional language (e.g., Haskell)

```
- map :: (a -> b) -> seq a -> seq b
```

In C++:

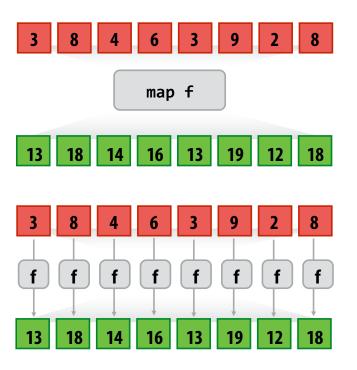
(++

int f(int x) { return x + 10; }

int a[] = {3, 8, 4, 6, 3, 9, 2, 8}; int b[8]; std::transform(a, a+8, b, f);

Haskell

a = [3, 8, 4, 6, 3, 9, 2, 8] f x = x + 10 b = map f a



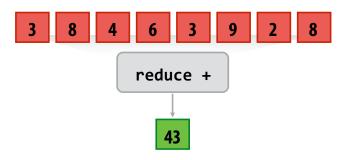
Reduce

Apply binary operation f to each element and an accumulated value

f :: (b,a) -> b reduce :: ((b,a) -> b) -> seq a -> b

E.g., in Scala:

def reduce[A](f: (B, A) => B, 1: List[A]): B



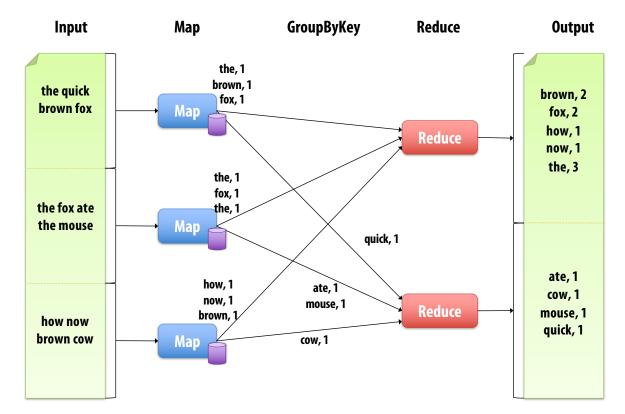
MapReduce Programming Model

```
// called once per line in input file by runtime
// input: string (line of input file)
// output: adds (user_agent, 1) entry to list
void mapper(string line, multimap<string,string>& results) {
   string user_agent = parse_requester_user_agent(line);
   if (is mobile client(user agent))
     results.add(user_agent, 1);
}
// called once per unique key (user agent) in results
// values is a list of values associated with the given key
void reducer(string key, list<string> values, int& result) {
    int sum = 0;
    for (v in values)
       sum += v;
    result = sum;
}
// iterator over lines of text file
LineByLineReader input("hdfs://cs149log.txt");
// stores output
Writer output("hdfs://...");
// do stuff
```

```
runMapReduceJob(mapper, reducer, input, output);
```

(The code above computes the count of page views by each type of mobile phone)

Let's design an implementation of runMapReduceJob



MapReduce Dataflow for Word Count

Should be called MapGroupByKeyReduce

Step 1: Running the mapper function

// called once per line in file

void mapper(string line, multimap<string,string>& results) { string user_agent = parse_requester_user_agent(line);

```
if (is mobile client(user agent))
```

```
results.add(user_agent, 1);
```

}

// called once per unique key in results

void reducer(string key, list<string> values, int& result) { int sum = 0;for (v in values) sum += v: result = sum;

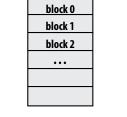
}

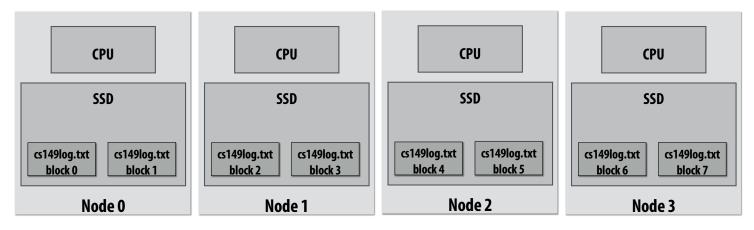
LineByLineReader input("hdfs://cs149log.txt"); Writer output("hdfs://..."); runMapReduceJob(mapper, reducer, input, output);

Step 1: run mapper function on all lines of file Question: How to assign work to nodes?

Idea 1: use work queue for list of input blocks to process takes next available block

Idea 2: data distribution based assignment: Each node processes lines Dynamic assignment: free node in blocks of input file that are stored locally





Steps 2 and 3: gathering data, running the reducer

```
// called once per line in file
```

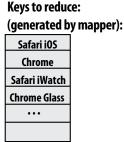
```
void mapper(string line, map<string,string> results) {
   string user_agent = parse_requester_user_agent(line);
   if (is_mobile_client(user_agent))
      results.add(user_agent, 1);
}
```

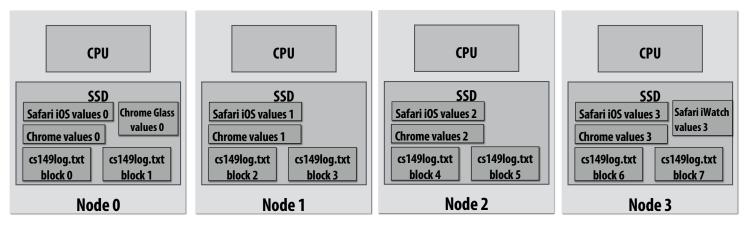
```
// called once per unique key in results
```

```
void reducer(string key, list<string> values, int& result) {
    int sum = 0;
    for (v in values)
        sum += v;
    result = sum;
}
```

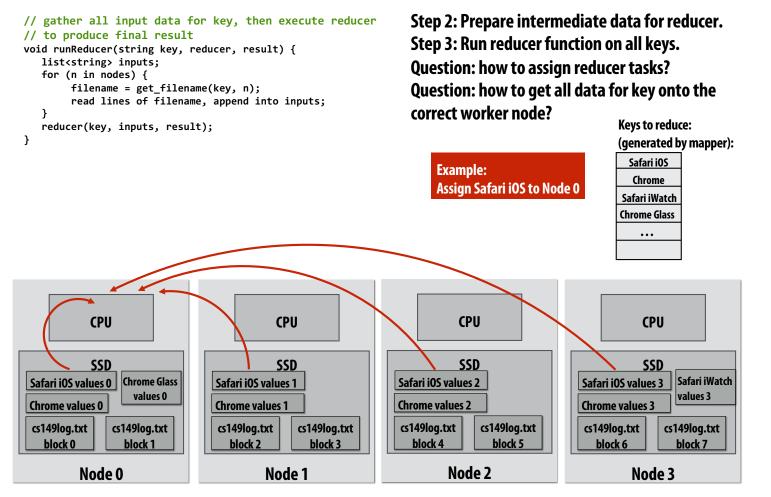
```
LineByLineReader input("hdfs://cs149log.txt");
Writer output("hdfs://..");
runMapReduceJob(mapper, reducer, input, output);
```

Step 2: Prepare intermediate data for reducer Step 3: Run reducer function on all keys Question 1: how to assign reducer tasks? Question 2: how to get all data for key onto the correct reduce worker node?

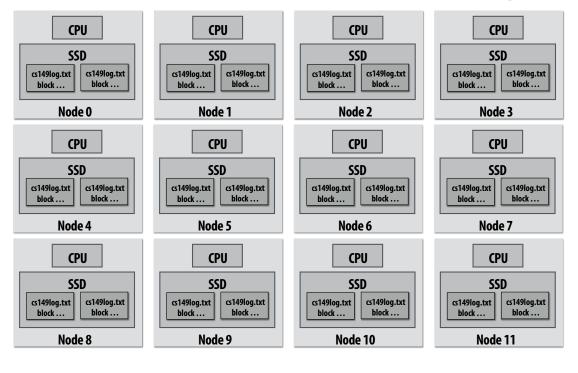




Steps 2 and 3: gathering data, running the reducer

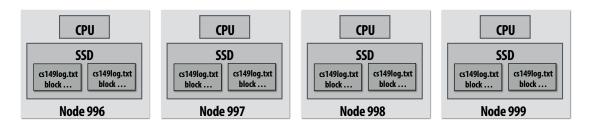


Additional implementation challenges at scale



Nodes may fail during program execution

Some nodes may run slower than others (due to different amounts of work, heterogeneity in the cluster, etc..)



Job scheduler responsibilities

Exploit data locality: "move computation to the data"

- Run mapper jobs on nodes that contain input blocks
- Run reducer jobs on nodes that already have most of data for a certain key

Handling node failures

- Scheduler detects job failures and reruns job on new machines
 - This is possible since inputs reside in persistent storage (distributed file system)
 - Scheduler duplicates jobs on multiple machines (reduce overall processing latency incurred by node failures)

Handling slow machines

- Scheduler duplicates jobs on multiple machines

MapReduce Benefits

By providing a data-parallel model, MapReduce greatly simplified cluster programming:

- Automatic division of job into map and reduce tasks
- Locality-aware scheduling
- Load balancing
- Recovery from failures & stragglers

But... the story doesn't end here!

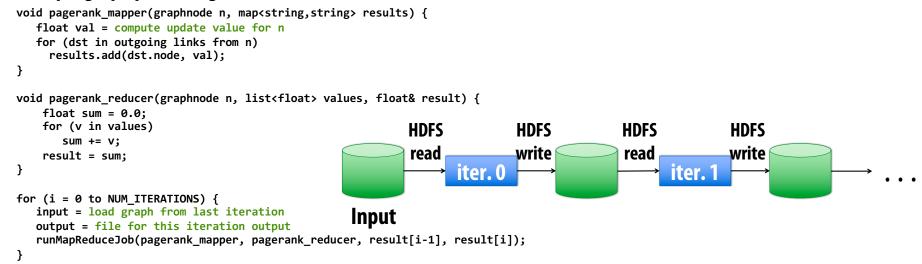
runMapReduceJob problems?

Permits only a very simple program structure

- Programs must be structured as: map, followed by reduce by key
- See DryadLINQ for generalization to DAGs

Iterative algorithms must load from disk each iteration

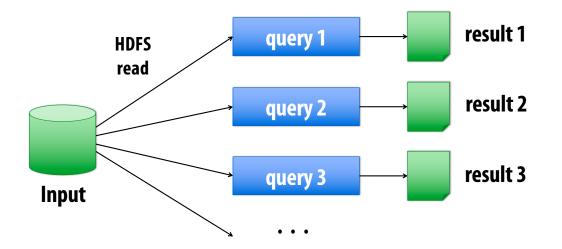
- Example graph processing:



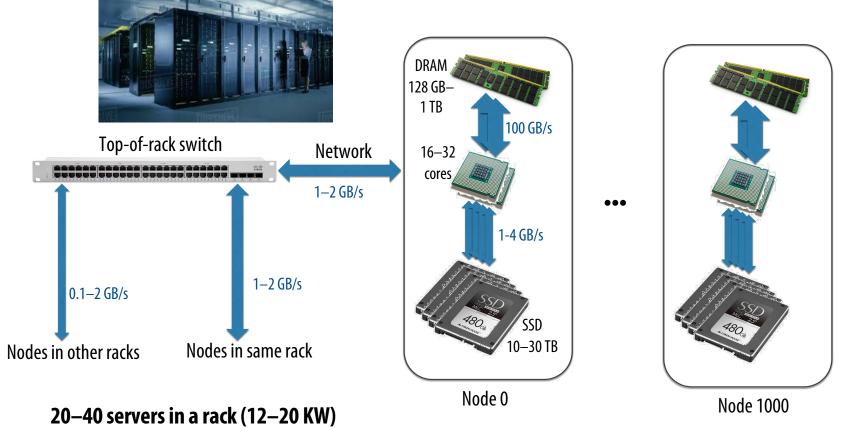
MapReduce Limitations

MapReduce greatly simplified "big data" analysis But users quickly needed more:

- More complex, multi-stage applications (e.g. iterative machine learning & graph processing)
- More interactive ad-hoc queries



Warehouse-Scale Cluster Node (Server)



20–40 servers in a rack (12–20 KW) Consider bandwidths, what conclusions can you make?

2009: Application Trends

Despite huge amounts of data, many working sets in big data clusters fit in memory

Memory (GB)	Facebook (% jobs)	Microsoft (% jobs)	Yahoo! (% jobs)
8	69	38	66
16	74	51	81
32	96	82	97.5
64	97	98	99.5
128	98.8	99.4	99.8
192	99.5	100	100
256	99.6	100	100

*G Ananthanarayanan, A. Ghodsi, S. Shenker, I. Stoica, "Disk-Locality in Datacenter Computing Considered Irrelevant", HotOS 2011

Stanford CS149, Fall 2024 32



in-memory, fault-tolerant distributed computing

http://spark.apache.org/

[Zaharia et al. NSDI 2012]

Goals

Programming model for cluster-scale computations where there is significant reuse of intermediate datasets

- Iterative machine learning and graph algorithms
- Interactive data mining: load large dataset into aggregate memory of cluster and then perform multiple ad-hoc queries

Don't want incur inefficiency of writing intermediates to persistent distributed file system (want to keep it in memory)

Challenge: efficiently implementing fault tolerance for large-scale distributed in-memory computations

Fault tolerance for in-memory calculations

Replicate all computations

- Expensive solution: decreases peak throughput

Checkpoint and rollback

- Periodically save state of program to persistent storage
- Restart from last checkpoint on node failure

Maintain log of updates (commands and data)

- High overhead for maintaining logs

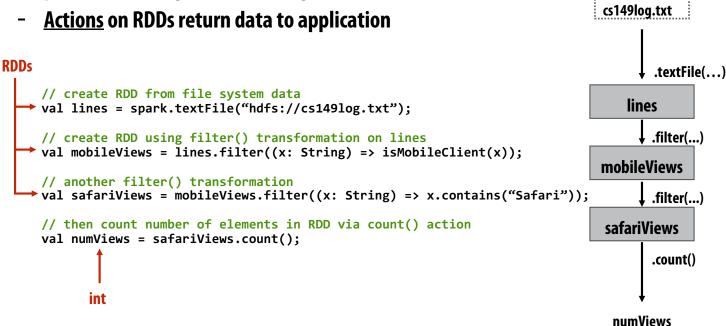
Recall map-reduce solutions:

- Checkpoints after each map/reduce step by writing results to file system
- Scheduler's list of outstanding (but not yet complete) jobs is a log
- Functional structure of programs allows for restart at granularity of a single mapper or reducer invocation (don't have to restart entire program)

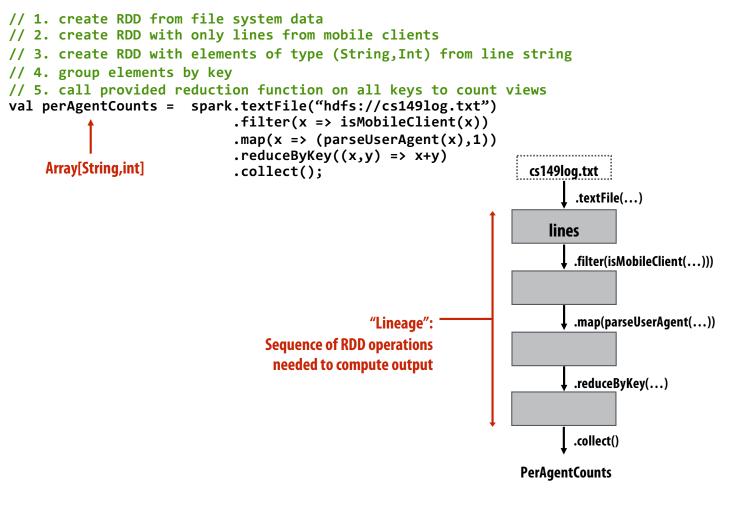
Resilient Distributed Dataset (RDD)

Spark's key programming <u>abstraction</u>:

- Read-only ordered collection of records (immutable)
- RDDs can only be created by deterministic <u>transformations</u> on data in persistent storage or on existing RDDs



Repeating the MapReduce Example



RDD transformations and actions

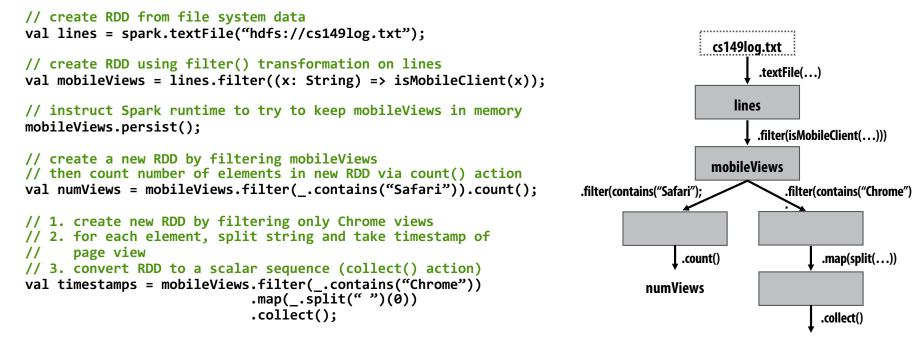
Transformations: (data parallel operators taking an input RDD to a new RDD)

		•
$map(f: T \Rightarrow U)$:	$RDD[T] \Rightarrow RDD[U]$
$filter(f: T \Rightarrow Bool)$:	$RDD[T] \Rightarrow RDD[T]$
$flatMap(f: T \Rightarrow Seq[U])$:	$RDD[T] \Rightarrow RDD[U]$
<pre>sample(fraction : Float)</pre>	:	$RDD[T] \Rightarrow RDD[T]$ (Deterministic sampling)
groupByKey()	:	$RDD[(K, V)] \Rightarrow RDD[(K, Seq[V])]$
$reduceByKey(f:(V,V) \Rightarrow V)$:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$
union()	:	$(RDD[T], RDD[T]) \Rightarrow RDD[T]$
join()	:	$(RDD[(K, V)], RDD[(K, W)]) \Rightarrow RDD[(K, (V, W))]$
cogroup()	:	$(RDD[(K, V)], RDD[(K, W)]) \Rightarrow RDD[(K, (Seq[V], Seq[W]))]$
crossProduct()	:	$(\text{RDD}[\text{T}], \text{RDD}[\text{U}]) \Rightarrow \text{RDD}[(\text{T}, \text{U})]$
$mapValues(f : V \Rightarrow W)$:	$RDD[(K, V)] \Rightarrow RDD[(K, W)]$ (Preserves partitioning)
<i>sort</i> (<i>c</i> : Comparator[K])	:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$
<i>partitionBy</i> (<i>p</i> : Partitioner[K])	:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$

Actions: (provide data back to the "host" application)

count()	:	$RDD[T] \Rightarrow Long$
collect()	:	$RDD[T] \Rightarrow Seq[T]$
$reduce(f:(\mathbf{T},\mathbf{T})\Rightarrow\mathbf{T})$:	$RDD[T] \Rightarrow T$
lookup(k: K)	:	$RDD[(K, V)] \Rightarrow Seq[V]$ (On hash/range partitioned RDDs)
<pre>save(path : String)</pre>	:	Outputs RDD to a storage system, e.g., HDFS

Another Spark Program



timestamps

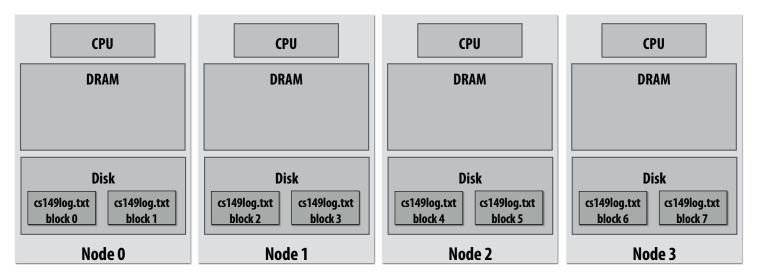
.persist():

- Inform Spark this RDD's contents should be retained in memory after an action
- .persist(RELIABLE) = store contents in durable storage (like a checkpoint)

How do we implement RDDs? In particular, how should they be stored?

```
val lines = spark.textFile("hdfs://cs149log.txt");
val lower = lines.map(_.toLower());
val mobileViews = lower.filter(x => isMobileClient(x));
val howMany = mobileViews.count();
```

Question: should we think of RDD's like arrays?

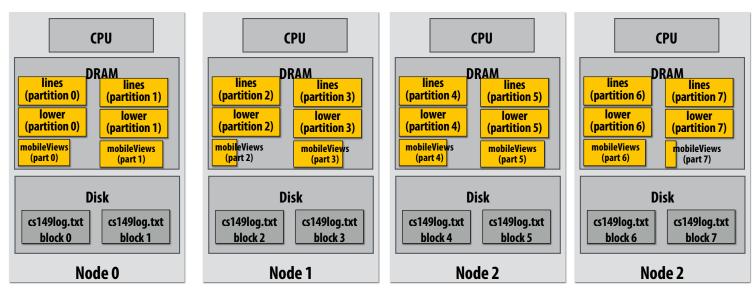


How do we implement RDDs? In particular, how should they be stored?

Parallel Performance = Parallelism + Locality

```
val lines = spark.textFile("hdfs://cs149log.txt");
val lower = lines.map(_.toLower());
val mobileViews = lower.filter(x => isMobileClient(x));
val howMany = mobileViews.count();
```

In-memory representation would be huge! (larger than original file on disk)



Implementing sequence of RDD ops efficiently

```
val lines = spark.textFile("hdfs://cs149log.txt");
val lower = lines.map(_.toLower());
val mobileViews = lower.filter(x => isMobileClient(x));
val howMany = mobileViews.count();
```

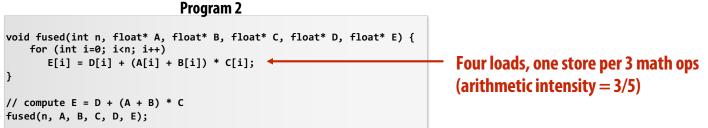
Recall "loop fusion" examples

The following code stores only a line of the log file in memory, and only reads input data from disk once ("streaming" solution)

```
int count = 0;
while (inputFile.eof()) {
    string line = inputFile.readLine();
    string lower = line.toLower;
    if (isMobileClient(lower))
        count++;
}
```

Review: which program performs better?

Program 1 void add(int n, float* A, float* B, float* C) { Two loads, one store per math op for (int i=0; i<n; i++)</pre> C[i] = A[i] + B[i];(arithmetic intensity = 1/3) } void mul(int n, float* A, float* B, float* C) { Two loads, one store per math op for (int i=0; i<n; i++)</pre> (arithmetic intensity = 1/3) C[i] = A[i] * B[i];} float* A, *B, *C, *D, *E, *tmp1, *tmp2; // assume arrays are allocated here // compute E = D + ((A + B) * C)add(n, A, B, tmp1); **Overall arithmetic intensity** = 1/3mul(n, tmp1, C, tmp2); add(n, tmp2, D, E);



The transformation of the code in program 1 to the code in program 2 is called "loop fusion"

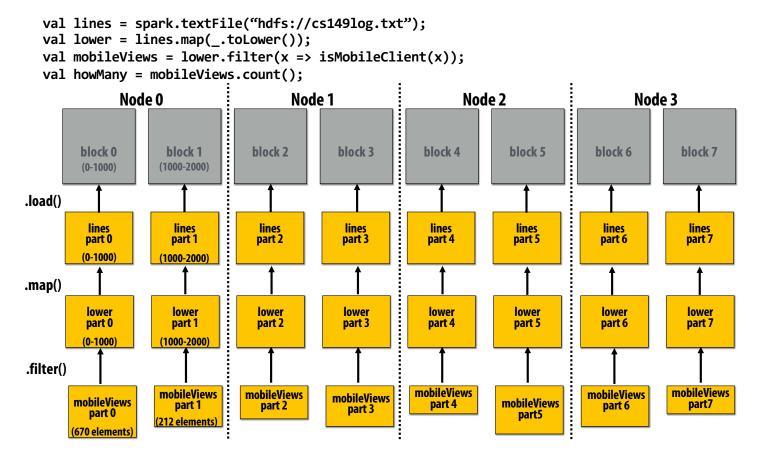
The previous example involved globally restructuring the order of computation to improve producer-consumer locality

(improve arithmetic intensity of program)

Fusion with RDDs

Why is it possible to fuse RDD transformations such as map and filter but not possible with transformations such as groupByKey and Sort?

RDD partitioning and dependencies



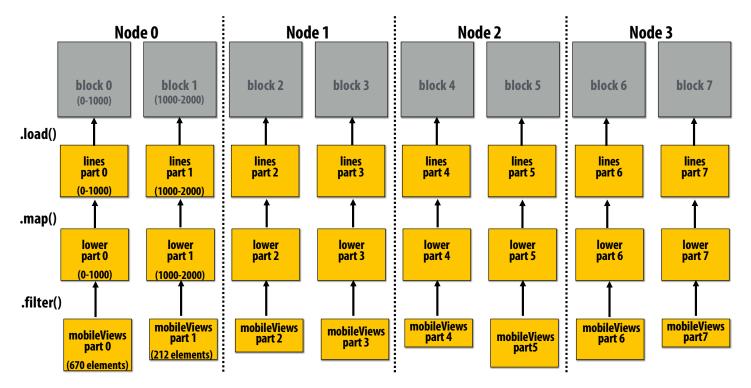
Black lines show dependencies between RDD partitions

Narrow dependencies

```
val lines = spark.textFile("hdfs://cs149log.txt");
val lower = lines.map(_.toLower());
val mobileViews = lower.filter(x => isMobileClient(x));
val howMany = mobileViews.count();
```

"Narrow dependencies" = each partition of parent RDD referenced by at most one child RDD partition

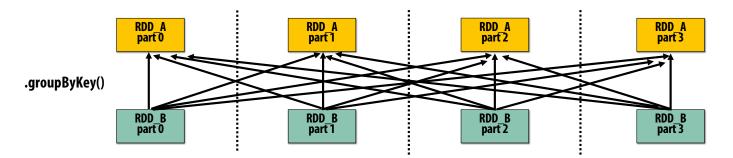
- Allows for fusing of operations (here: can apply map and then filter all at once on input element)
- In this example: no communication between nodes of cluster (communication of one int at end to perform count() reduction)



Wide dependencies

groupByKey: $RDD[(K,V)] \rightarrow RDD[(K,Seq[V])]$

"Make a new RDD where each element is a sequence containing all values from the parent RDD with the same key."



Wide dependencies = each partition of parent RDD referenced by multiple child RDD partitions Challenges:

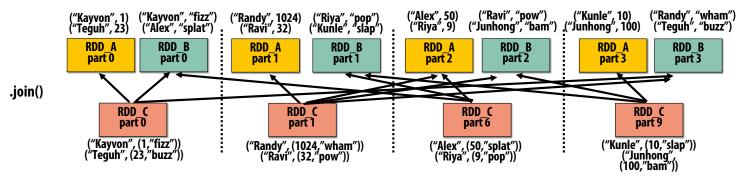
- Must compute all of RDD_A before computing RDD_B
 - Example: groupByKey() may induce all-to-all communication as shown above
- May trigger significant recomputation of ancestor lineage upon node failure (I will address resilience in a few slides)

Cost of operations depends on partitioning

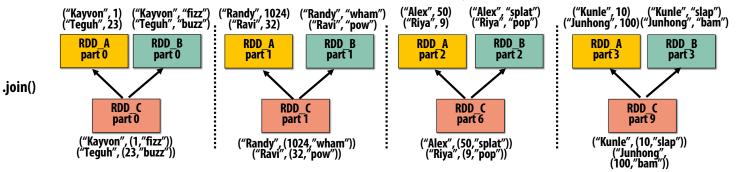
join: $RDD[(K,V)], RDD[(K,W)] \rightarrow RDD[(K,(V,W))]$

Assume data in RDD_A and RDD_B are partitioned by key: hash username to partition id

RDD_A and RDD_B have different hash partitions: join creates wide dependencies



RDD_A and RDD_B have same hash partition: join only creates narrow dependencies



PartitionBy() transformation

Inform Spark on how to partition an RDD

- e.g., HashPartitioner, RangePartitioner

```
// create RDD from file system data
val lines = spark.textFile("hdfs://cs149log.txt");
val clientInfo = spark.textFile("<u>hdfs://client</u>ssupported.txt"); // (useragent, "yes"/"no")
```

```
// create RDD using filter() transformation on lines
val mobileViews = lines.filter(x => isMobileClient(x)).map(x => parseUserAgent(x));
```

```
// HashPartitioner maps keys to integers
val partitioner = spark.HashPartitioner(100);
```

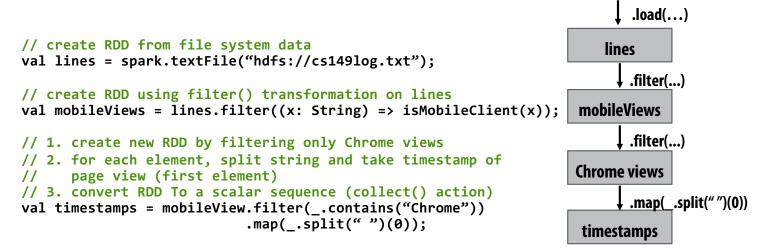
```
// inform Spark of partition
// .persist() also instructs Spark to try to keep dataset in memory
val mobileViewPartitioned = mobileViews.partitionBy(partitioner);
val clientInfoPartitioned = clientInfo.partitionBy(partitioner);
```

```
// join useragents with whether they are supported or not supported
// Note: this join only creates narrow dependencies due to the explicit partitioning above
void joined = mobileViewPartitioned.join(clientInfoPartitioned);
```

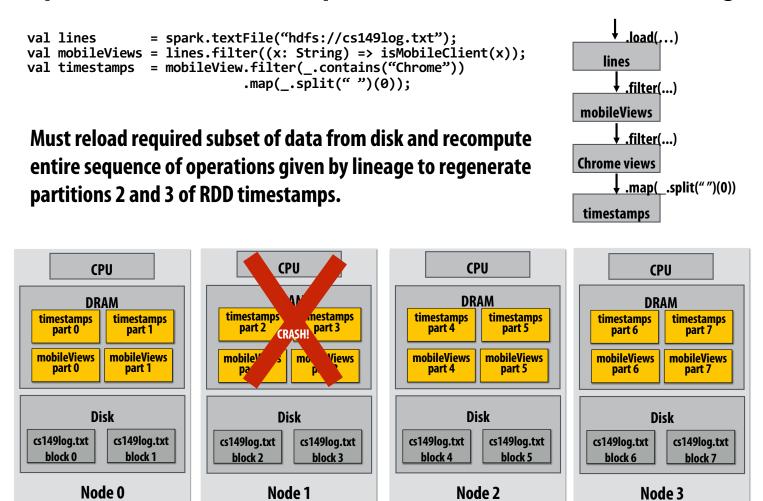
Implementing Resilience via Lineage

RDD transformations are bulk, deterministic, and functional

- Implication: runtime can always reconstruct contents of RDD from its lineage (the sequence of transformations used to create it)
- Lineage is a log of transformations
- Efficient: since the log records bulk data-parallel operations, overhead of logging is low (compared to logging fine-grained operations, like in a database)

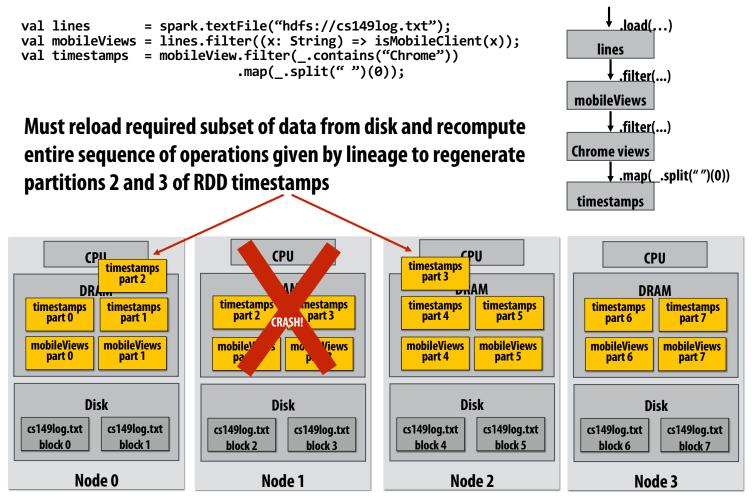


Upon Node Failure: Recompute Lost RDD Partitions from Lineage



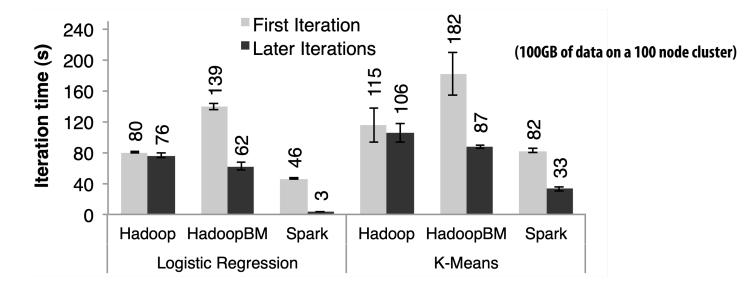
Note: (not shown): file system data is replicated so assume blocks 2 and 3 remain accessible to all nodes

Upon Node Failure: Recompute Lost RDD Partitions from Lineage



Note: (not shown): file system data is replicated so assume blocks 2 and 3 remain accessible to all nodes

Spark performance



HadoopBM = Hadoop Binary In-Memory (convert text input to binary, store in in-memory version of HDFS)

Anything else puzzling here? Q. Wait, the baseline parses text input in each iteration of an iterative algorithm? A. Yes.

HadoopBM's first iteration is slow because it runs an extra Hadoop job to copy binary form of input data to in memory HDFS

Accessing data from HDFS, even if in memory, has high overhead:

- Multiple mem copies in file system + a checksum
- Conversion from serialized form to Java object

Caution: "scale out" is not the entire story

Distributed systems designed for cloud execution address many difficult challenges, and have been instrumental in the explosion of "big-data" computing and large-scale analytics

- Scale-out parallelism to many machines
- Resiliency in the face of failures
- Simplifies complexity of managing clusters of machines

But scale out is not the whole story:

		age nam						
scalable system	cores	twitter	uk-2007-05	name	twitter_rv [11]	uk-20	007-05 [4]	
GraphChi [10]	2	3160s	6972s	nodes	41,652,230	10	5,896,555	i
Stratosphere [6]	16	2250s	-	edges	1,468,365,182	3,73	8,733,648	
X-Stream [17]	16	1488s	-	size	5.76GB		14.72GB	5
Spark [8]	128	857s	1759s					
Giraph [8]	128	596s	1235s					
GraphLab [8]	128	249s	833s					
GraphX [8]	128	419s	462s					
Single thread (SSD)	1	300s	651s					
Single thread (RAM)	1	275s	-	Vert	ex order (SSD)	1	300s	651s
Further optimization of the baseline brought time down to 110s				Vert	ex order (RAM)	1	275s	-
					ert order (SSD)	1	242s	256s
				Hilb	ert order (RAM)	1	110s	-
	prought t	ime aown to						

20 Iterations of Page Rank

["Scalability! At what COST?" McSherry et al. HotOS 2015]

Caution: "Scale Out" is Not the Entire Story

251s

153s

800s

417s

Label Propagation [McSherry et al. HotOS 2015]

scalable system	cores	twitter	uk-2007-05
Stratosphere [6]	16	950s	-
X-Stream [17]	16	1159s	-
Spark [8]	128	1784s	\geq 8000s
Giraph [8]	128	200s	\geq 8000s
GraphLab [8]	128	242s	714s

from McSherry 2015:

GraphX [8]

Single thread (SSD)

"The published work on big data systems has fetishized scalability as the most important feature of a distributed data processing platform. While nearly all such publications detail their system's impressive scalability, few directly evaluate their absolute performance against reasonable benchmarks. To what degree are these systems truly improving performance, as opposed to parallelizing overheads that they themselves introduce?"

128

cost = "Configuration that Outperforms a Single Thread"

Perhaps surprisingly, many published systems have unbounded COST—i.e., no configuration outperforms the best single-threaded implementation—for all of the problems to which they have been applied.

BID Data Suite (1 GPU accelerated node) [Canny and Zhao, KDD 13]

Page Rank

System	Graph VxE	Time(s)	Gflops	Procs	
Hadoop	?x1.1B	198	0.015	50x8	
Spark	40Mx1.5B	97.4	0.03	50x2	
Twister	50Mx1.4B	36	0.09	60x4	
PowerGraph	40Mx1.4B	3.6	0.8	64x8	
BIDMat	60 Mx 1.4 B	6	0.5	$1 \mathrm{x} 8$	
BIDMat+disk	60Mx1.4B	24	0.16	1x8	

Latency Dirichlet Allocation (LDA)

System	Docs/hr	Gflops	Procs
Smola[15]	1.6M	0.5	100x8
PowerGraph	$1.1\mathrm{M}$	0.3	64x16
BIDMach	$3.6\mathrm{M}$	30	1x8x1

Performance improvements to Spark

With increasing DRAM sizes and faster persistent storage (SSD), there is interest in improving the CPU utilization of Spark applications

- Goal: reduce "COST"

Efforts looking at adding efficient code generation to Spark ecosystem (e.g., generate SIMD kernels, target accelerators like GPUs, etc.) to close the gap on single node performance

- RDD storage layouts must change to enable high-performance SIMD processing (e.g., struct of arrays instead of array of structs)
- See Spark's Project Tungsten, Weld [Palkar Cidr '17], IBM's SparkGPU

High-performance computing ideas are influencing design of future performance-oriented distributed systems

- Conversely: the scientific computing community has a lot to learn from the distributed computing community about elasticity and utility computing

Spark summary

Introduces opaque sequence abstraction (RDD) to encapsulate intermediates of cluster computations (previously... frameworks like Hadoop/MapReduce stored intermediates in the file system)

- Observation: "files are a poor abstraction for intermediate variables in largescale data-parallel programs"
- RDDs are read-only, and created by deterministic data-parallel operators
- Lineage tracked and used for locality-aware scheduling and fault-tolerance (allows recomputation of partitions of RDD on failure, rather than restore from checkpoint *)
 - Bulk operations allow overhead of lineage tracking (logging) to be low.

Simple, versatile abstraction upon which many domain-specific distributed computing frameworks are being implemented.

- See Apache Spark project: spark.apache.org

^{*} Note that .persist(RELIABLE) allows programmer to request checkpointing in long lineage situations.

Modern Spark ecosystem

Compelling feature: enables integration/composition of multiple domain-specific frameworks (since all collections implemented under the hood with RDDs and scheduled using Spark scheduler)



names = results.map(lambda p: p.name)

Interleave computation and database guery Can apply transformations to RDDs produced by SQL queries



points = spark.textFile("hdfs://...") .map(parsePoint)

Machine learning library build on top of Spark abstractions.

model = KMeans.train(points, k=10)



GraphLab-like library built on top of Spark abstractions.

```
graph = Graph(vertices, edges)
messages = spark.textFile("hdfs://...")
graph2 = graph.joinVertices(messages) {
  (id, vertex, msg) => ...
7
```