# Lecture 20: Course Summary + **Graphics at Stanford Today**

**Computer Graphics: Rendering, Geometry, and Image Manipulation** Stanford CS248A, Winter 2023

## As accomplished CS248A students you've now learned the basics of drawing shapes, representing surfaces/light/materials, manipulating images, etc...

## (and you have been introduced to core graphics ideas like sampling, anti-aliasing, acceleration data structures, etc.)

What's next?



# Graphics classes (coming quarters) at Stanford

## SPRING

CS348K: "Visual Computing Systems", creating efficient systems for photography, 3D graphics, and modern AI (Fatahalian) - TTh 10:30am CS348E: "Character Animation: Modeling, Simulation, and Control of Human Motion" (Liu) - MW 1:30am CS 348N: "Neural Models for 3D Geometry" (Guibas) - MW 3:00pm CS 231N: "Deep Learning for Computer Vision" (F. Li) - TTh 12:00pm

## FALL

CS248B: "Fundamentals of Computer Graphics: Animation and Simulation " (Liu, James) CS 448B: "Data Visualization" (Agrawala)

## WINTER

CS348C: "Animation and Simulation", deep dive into animation and simulation techniques (James) EE367/CS448i: "Computational Imaging and Display", advanced course on display design (Wetzstein) CS205L: "Continuous Mathematical Methods with an Emphasis on Machine Learning" (Fedkiw)



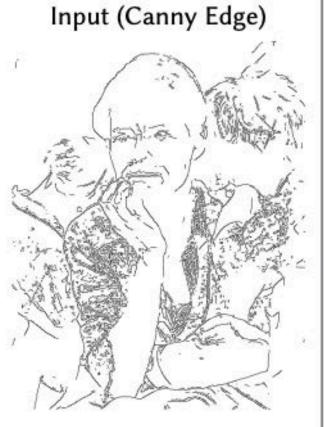
# **Graphics Research at Stanford Today**



# Maneesh Agrawala



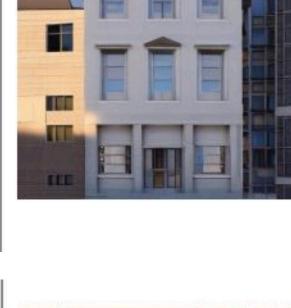
# **ControlNet: more precise ways to control diffusion-based generative Al**



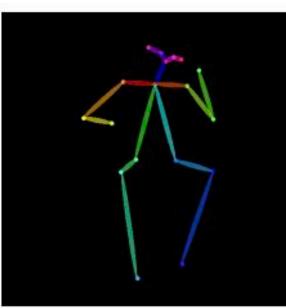
Default













Automatic Prompt



"a man with beard sitting with two children"

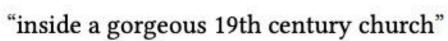
User Prompt



"mother and two boys in a room, masterpiece, artwork"







astronaut









"a building in a city street"





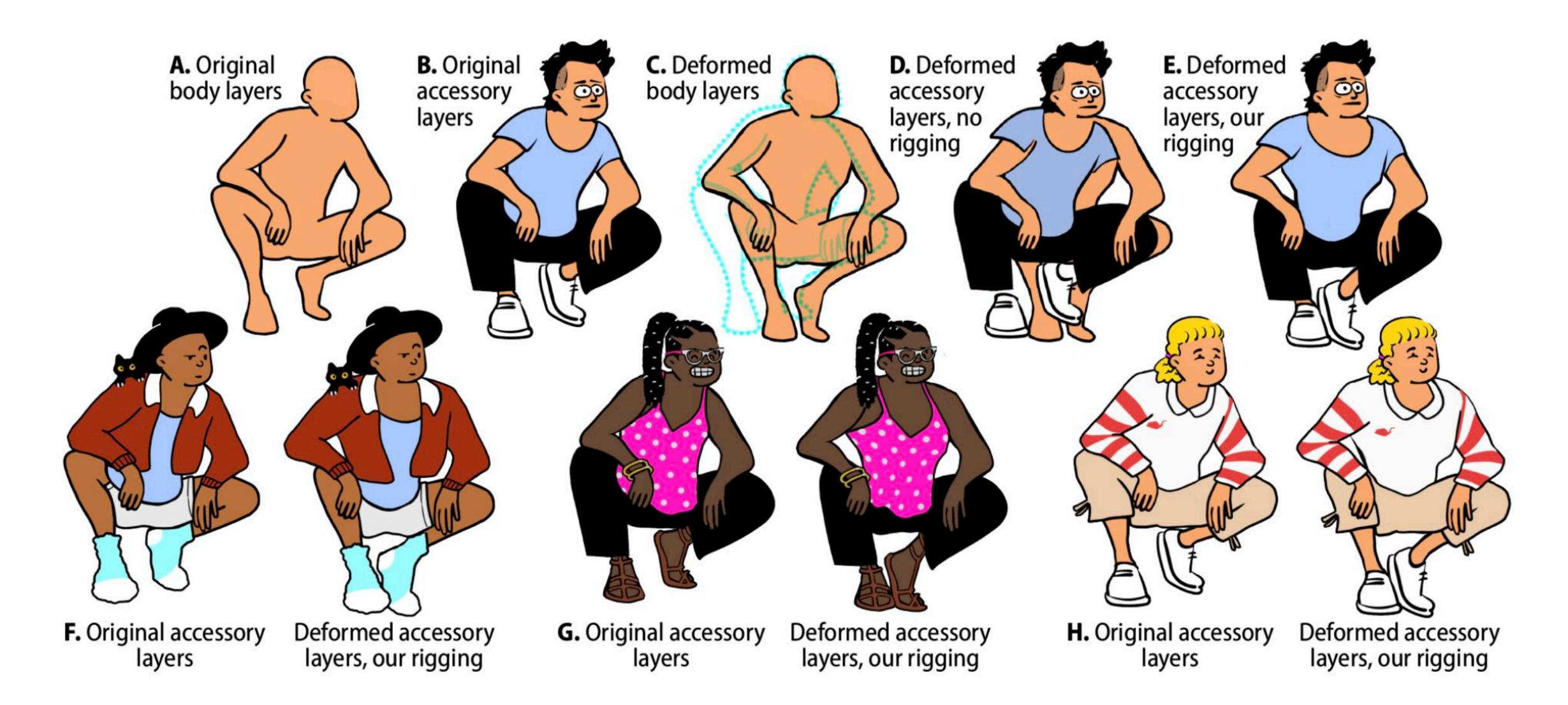








# General theme: intuitive controls for content creation



[Le et al. UIST 21]

# **Ron Fedkiw**



# **Ron Fedkiw**



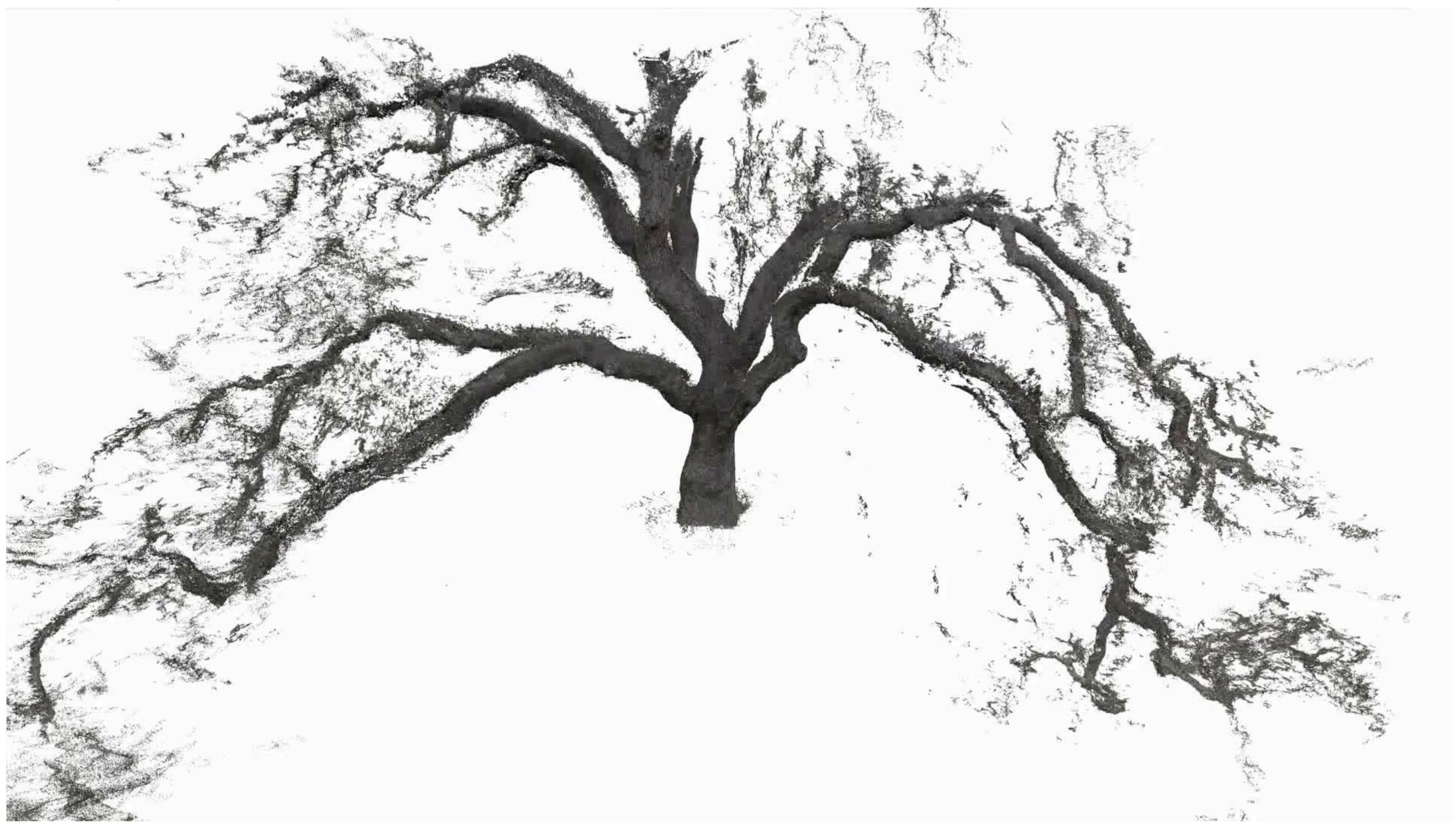
## Left Camera

### Simulation techniques (often) targeted at film and game production Now exploring use of machine learning to augment or improve physical simulations

## **Right Camera**



# **Ron Fedkiw**





# Karen Liu

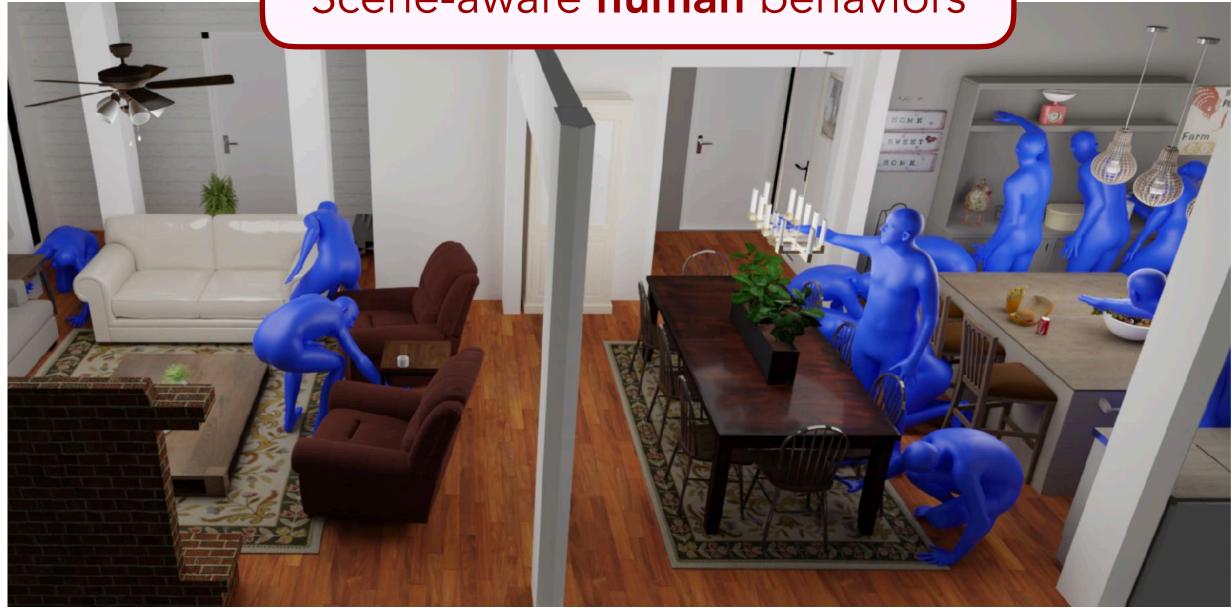


### Human motion synthesis and estimation



### Human-robot interaction

### Scene-aware **human** behaviors



-TIME DE DERINC

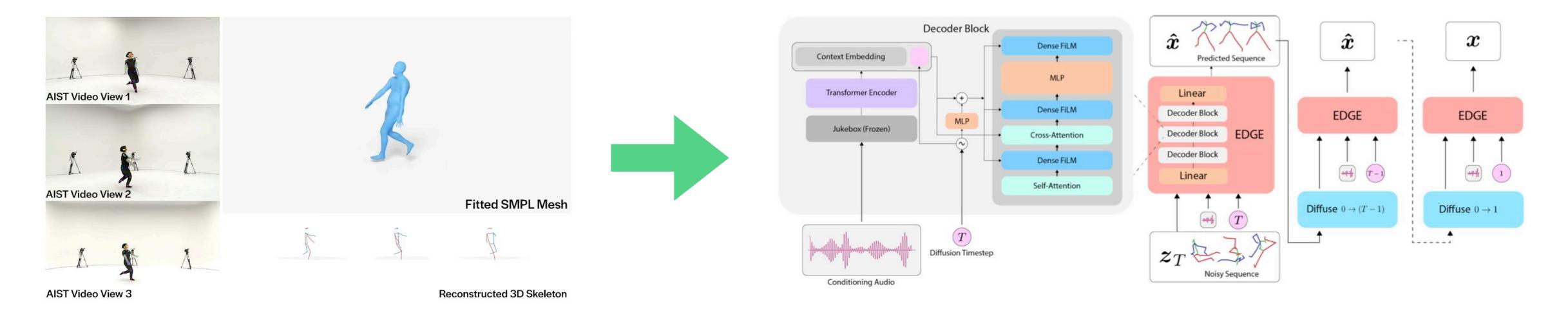


Stanford CS248A, Winter 2023



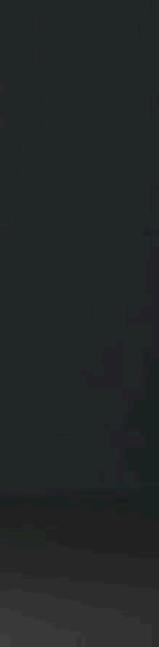




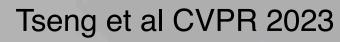


### Human dance dataset

Train an editable generative model to imitate human motor skills and musicality in dance using Diffusion Models



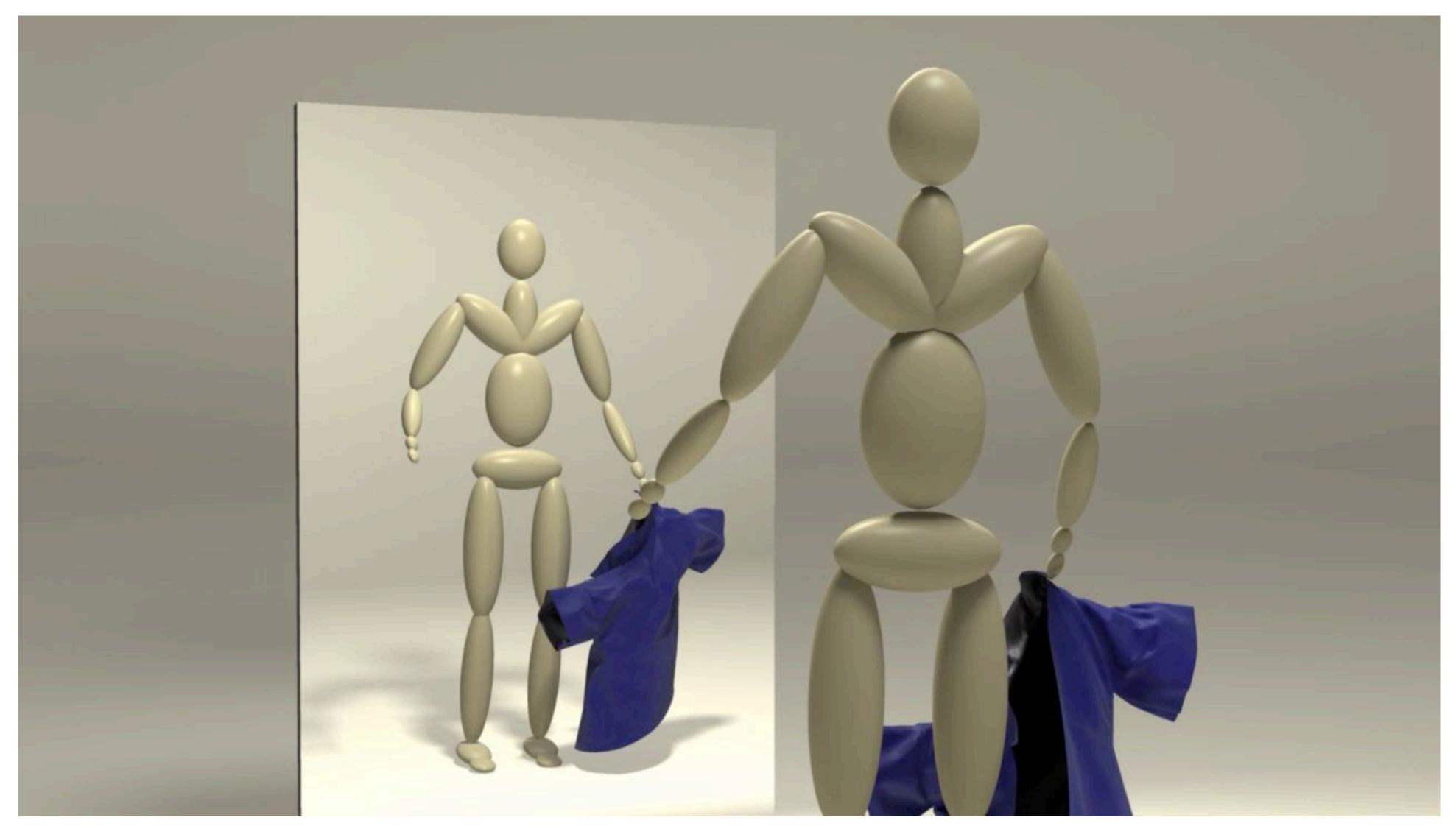






# Karen Liu

## Interests in animation, simulation, and control





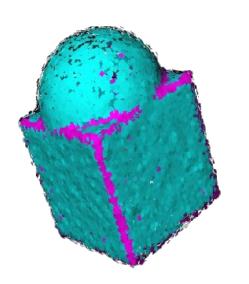
# Leo Guibas



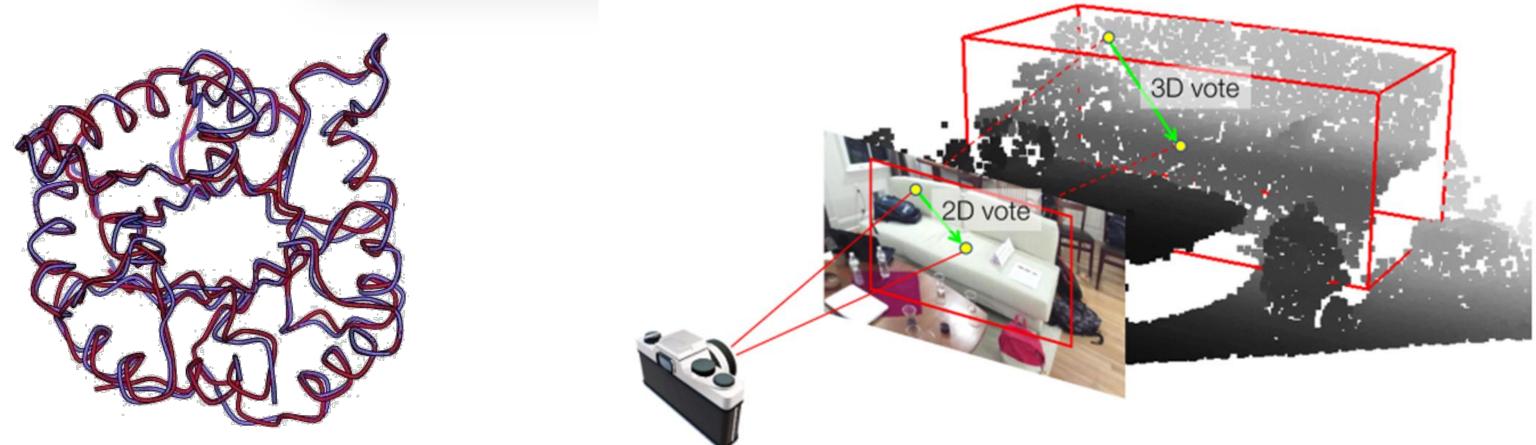
# **Recent Guibas Lab projects**

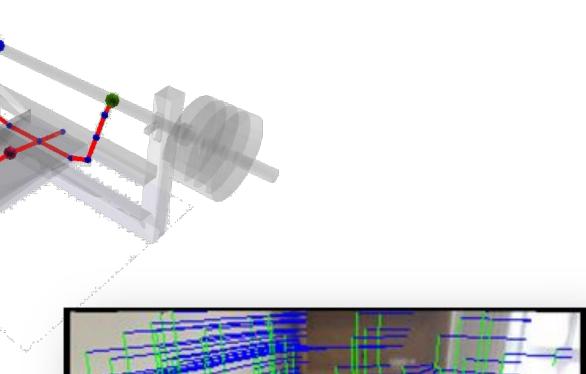
- Computer vision and sensor networks
- Geometric and topological data analysis
- 3D machine learning and 3D representations
- 3D shape/scene analysis and synthesis
- Neural methods for navigation and manipulation
- Affective computing

Algorithmic problems in modeling physical objects and phenomena in vision/graphics/robotics







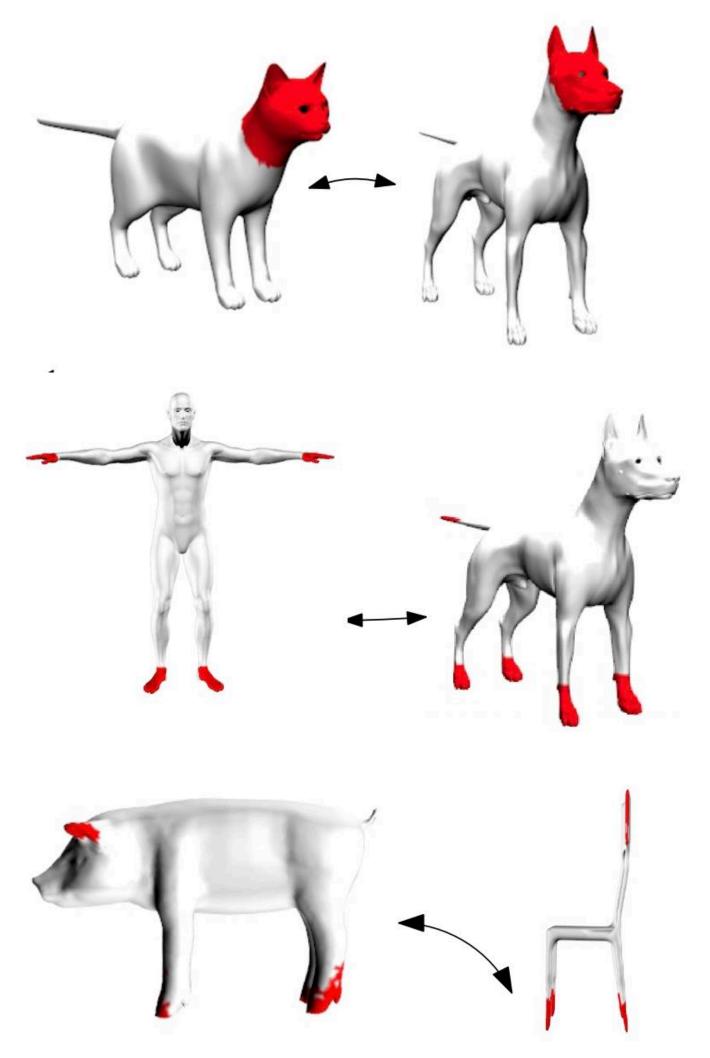




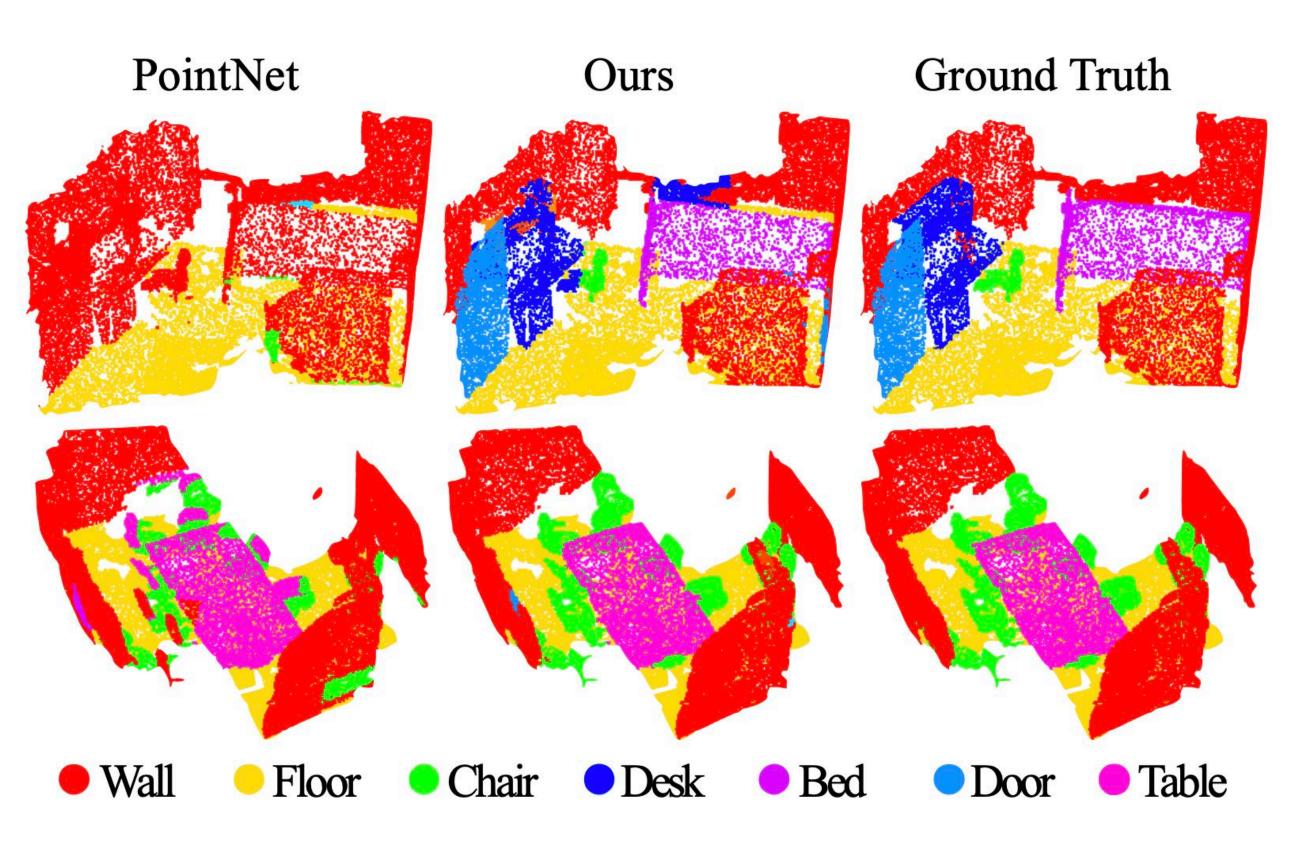




## Leo Guibas Geometry processing and analysis



**Shape Similarity and Correspondence** 



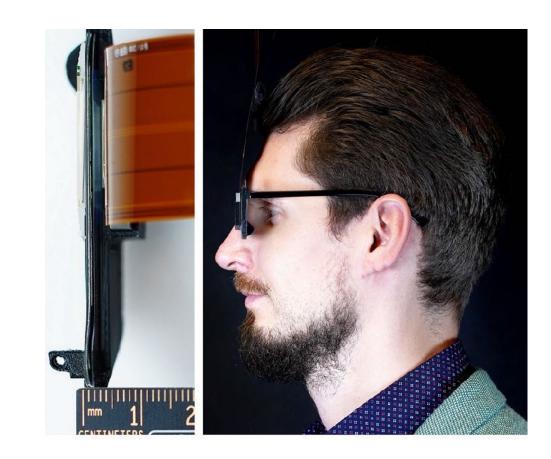
### **PointNet: Deep Learning on Point Clouds**

# **Gordon Wetzstein**

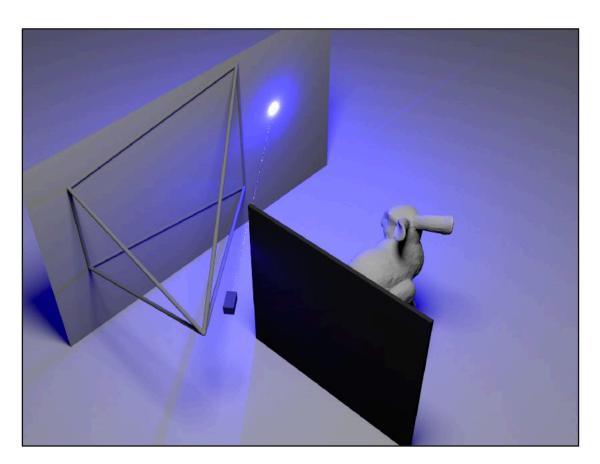


## Stanford Computational Imaging Lab Neural Rendering XR & Wearable Computing

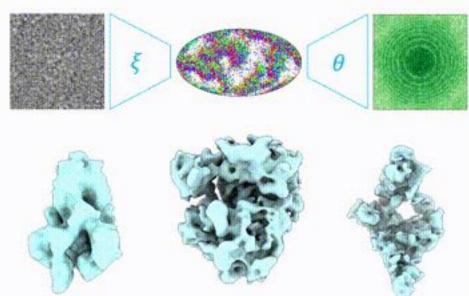


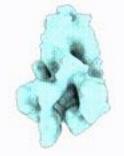


## Single-photon Imaging

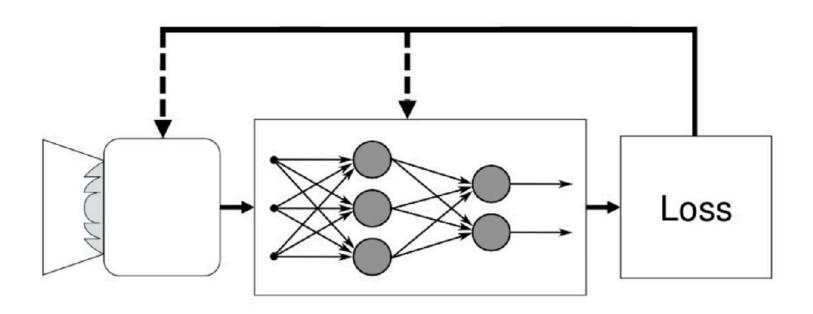


Computational Microscopy

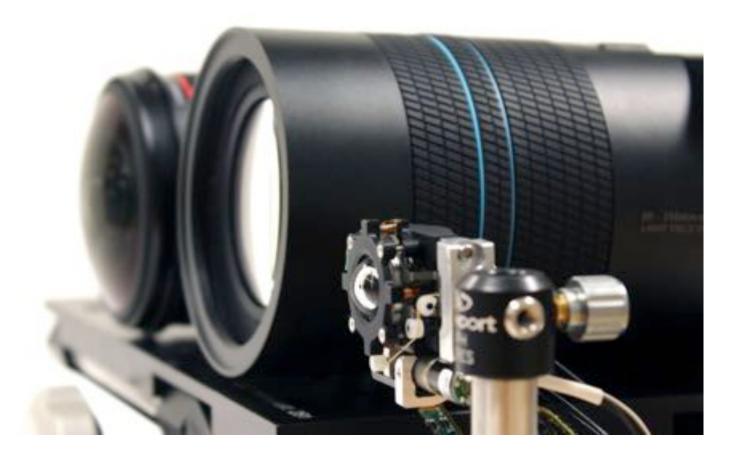




Deep Optics



## Computational Cameras





## Efficient 3D GANs – Latent Code Interpolation



Chan et al. CVPR 2022

# Doug James



## Stanford University





# Jiajun Wu

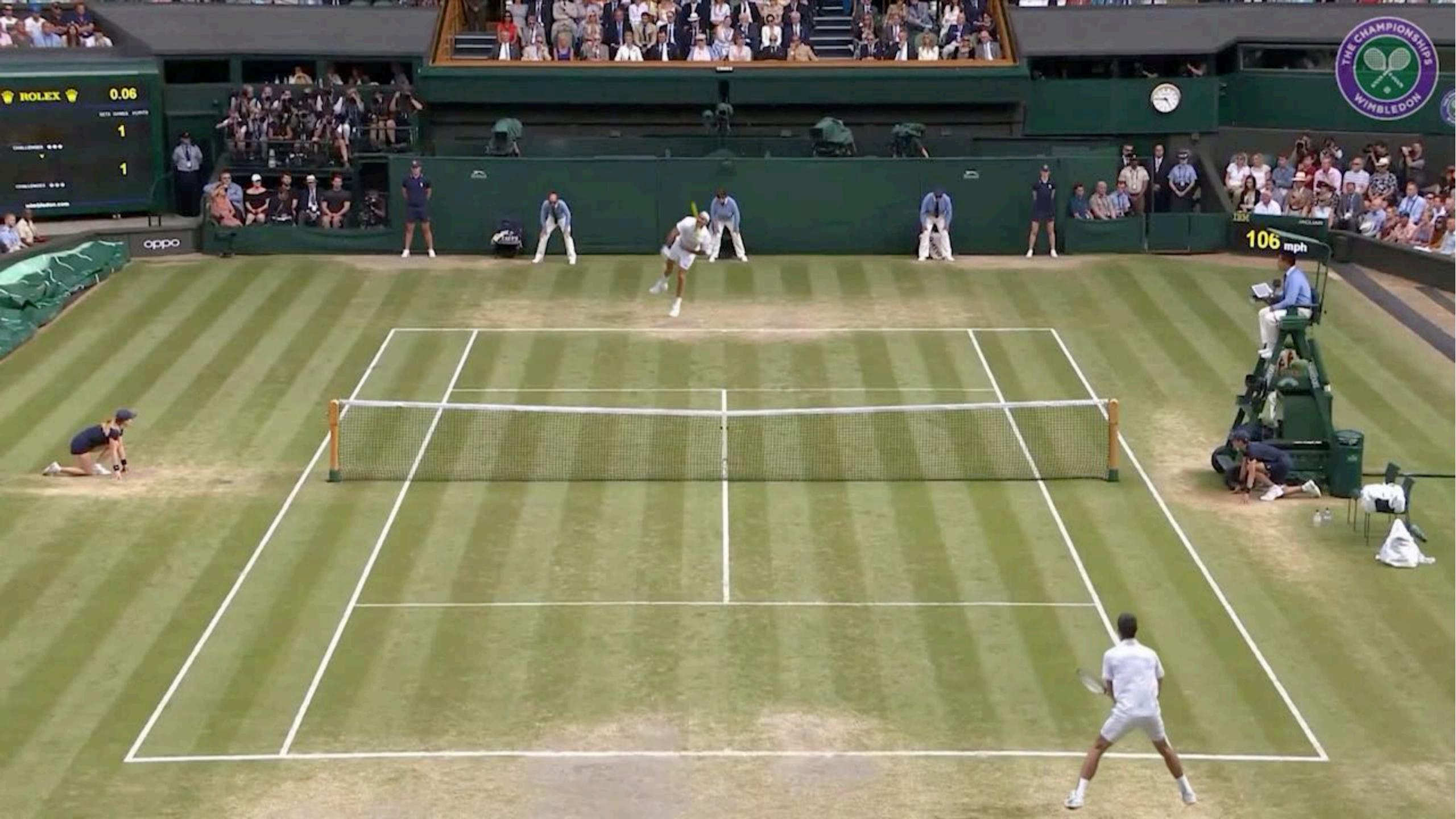


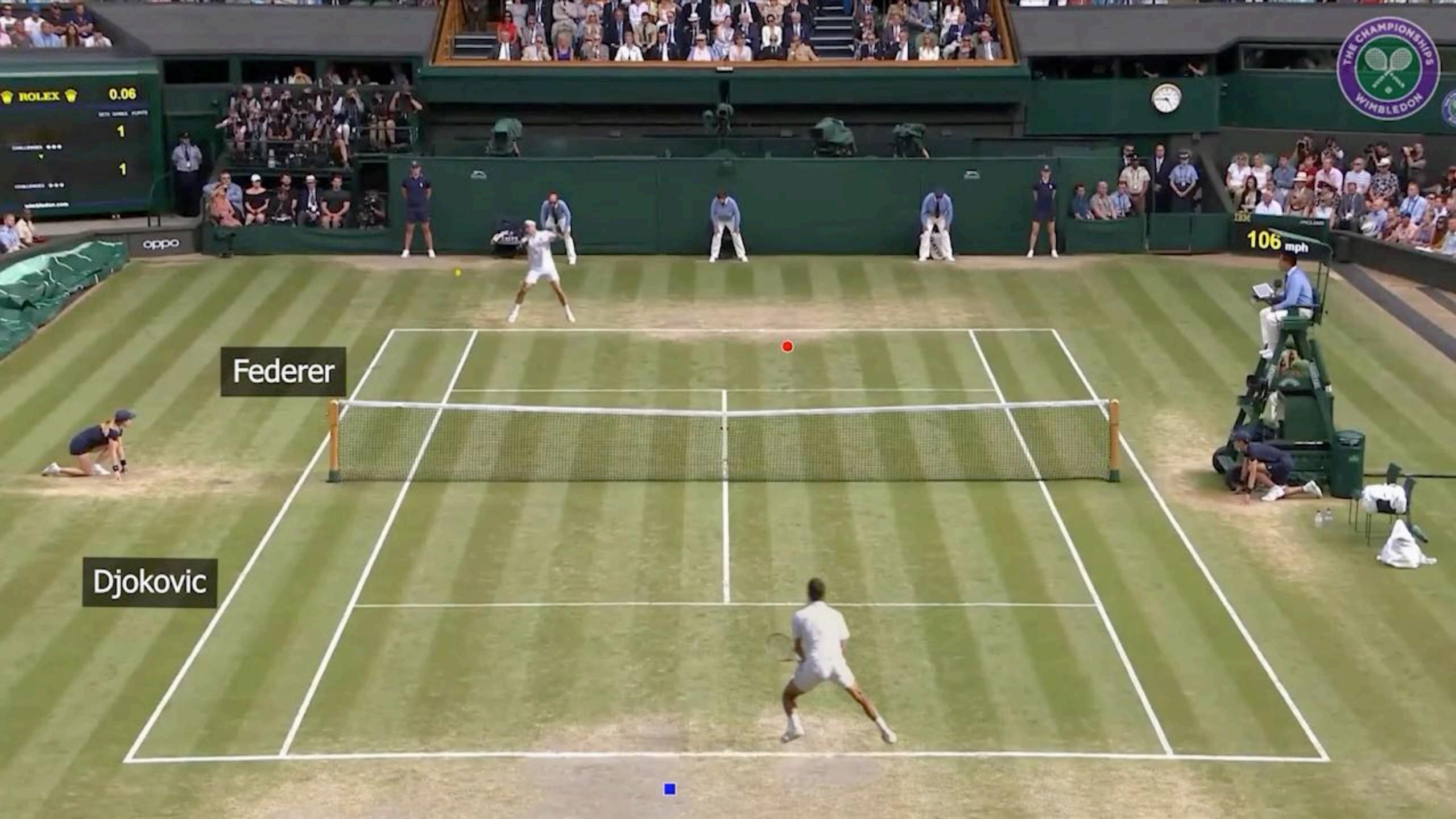
## Stanford University



# Kayvon Fatahalian (me)









# Example getting-started-in-the-lab project idea

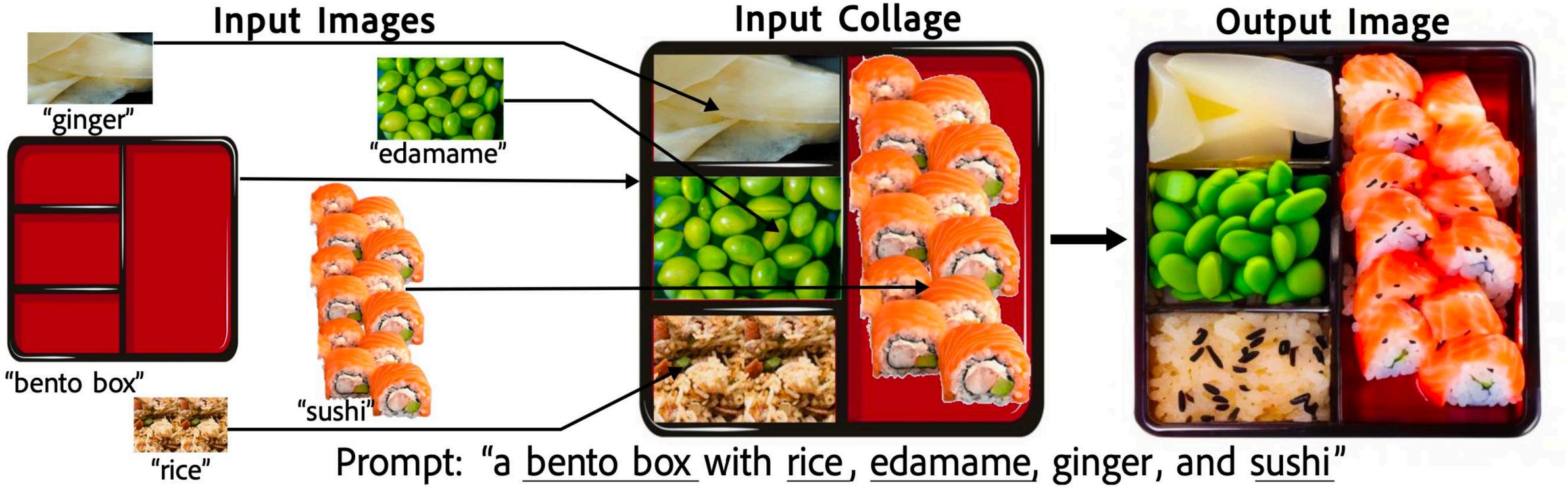
- Take the technology shown on the previous slide and make an interactive "Wimbledon point creator" where folks can visit a web site, click where they want the ball to go, and then download a resulting video.
  - I bet it would be a hit if you could get it done and online before Wimbledon 2023



# **Controlling generative AI by making collages**

User creates a collage with standard graphics tools Collage defines what should be in the image, where it goes, and what it should look like

Generative AI turns the collage into a "plausible" realistic image



# **High Interest in AI Agents Across Disciplines**

## **Game-Playing Agents**



Dota 2



### **Google Research Football**

**OpenAl Hide & Seek** 



### Habitat Rearrangement Challenge



### Autonomous Vehicles (Carla, NV Drive Sim)



## **Robotics**

### **ProcTHOR**

## **Game Development &** Debugging



**Unity ML-Agents** 



Automated QA & Design (EA SEED)









# **Generating Simulated Experience is Computationally Demanding: Slow & Expensive Training!**

## **OpenAl Five**



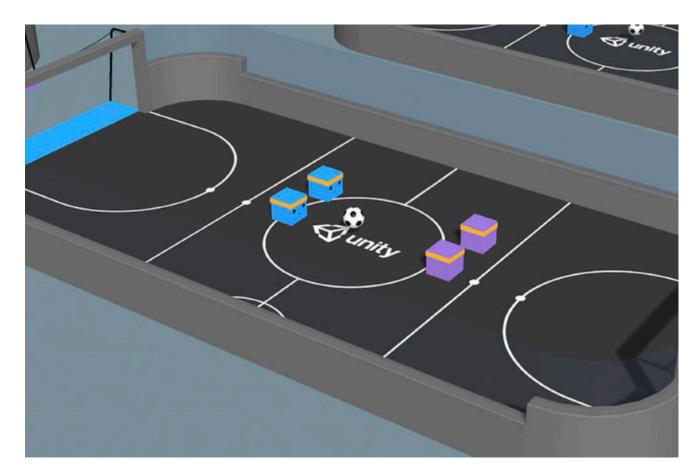


Rapid: 100k+ CPUs, months of training

## Habitat 2.0

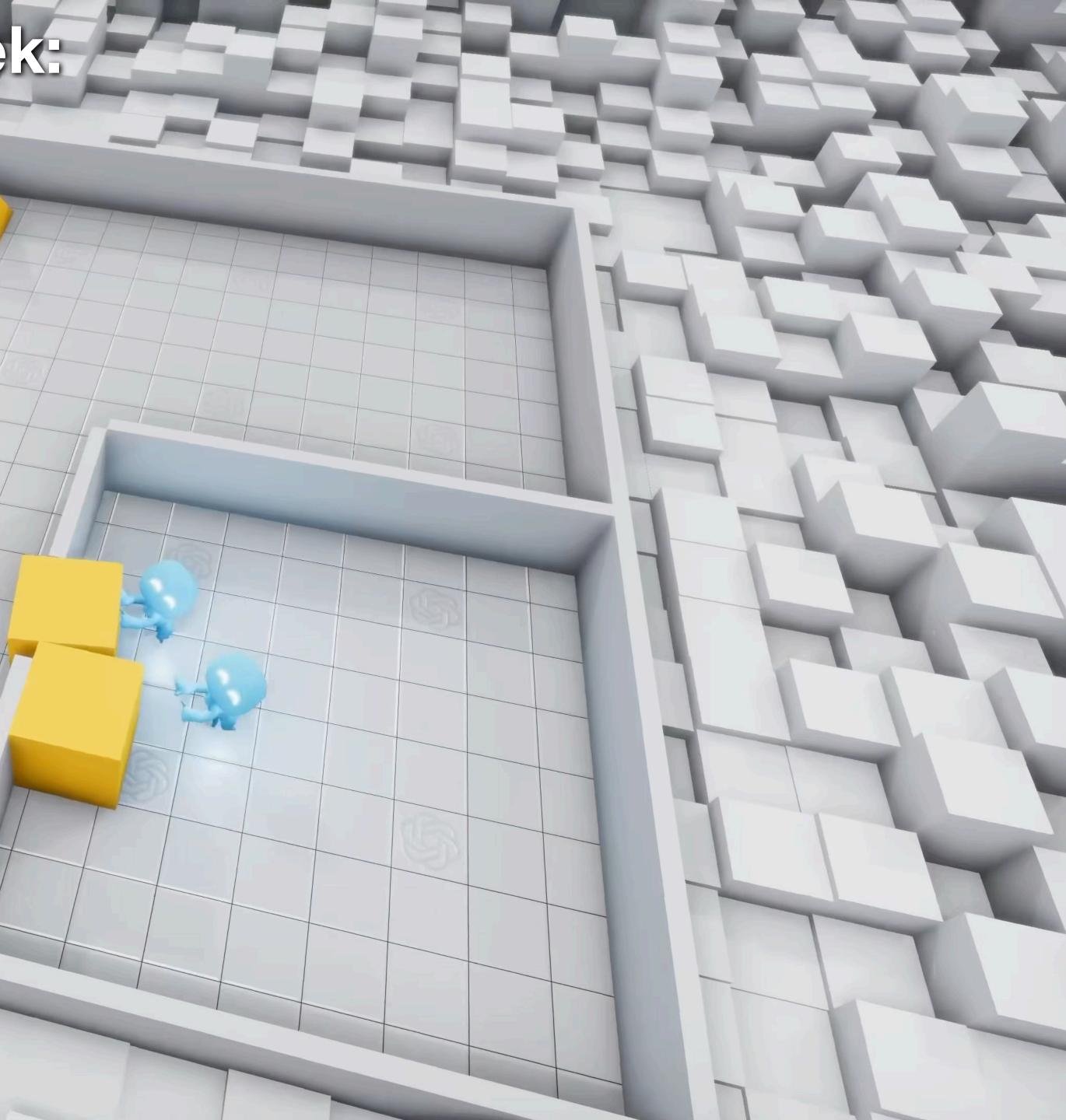
25000 FPS on 8 GPUs, Months to Learn Rearrangement

## **Unity ML-Agents**



**Thoughput Limited by Scaling Strategy** 

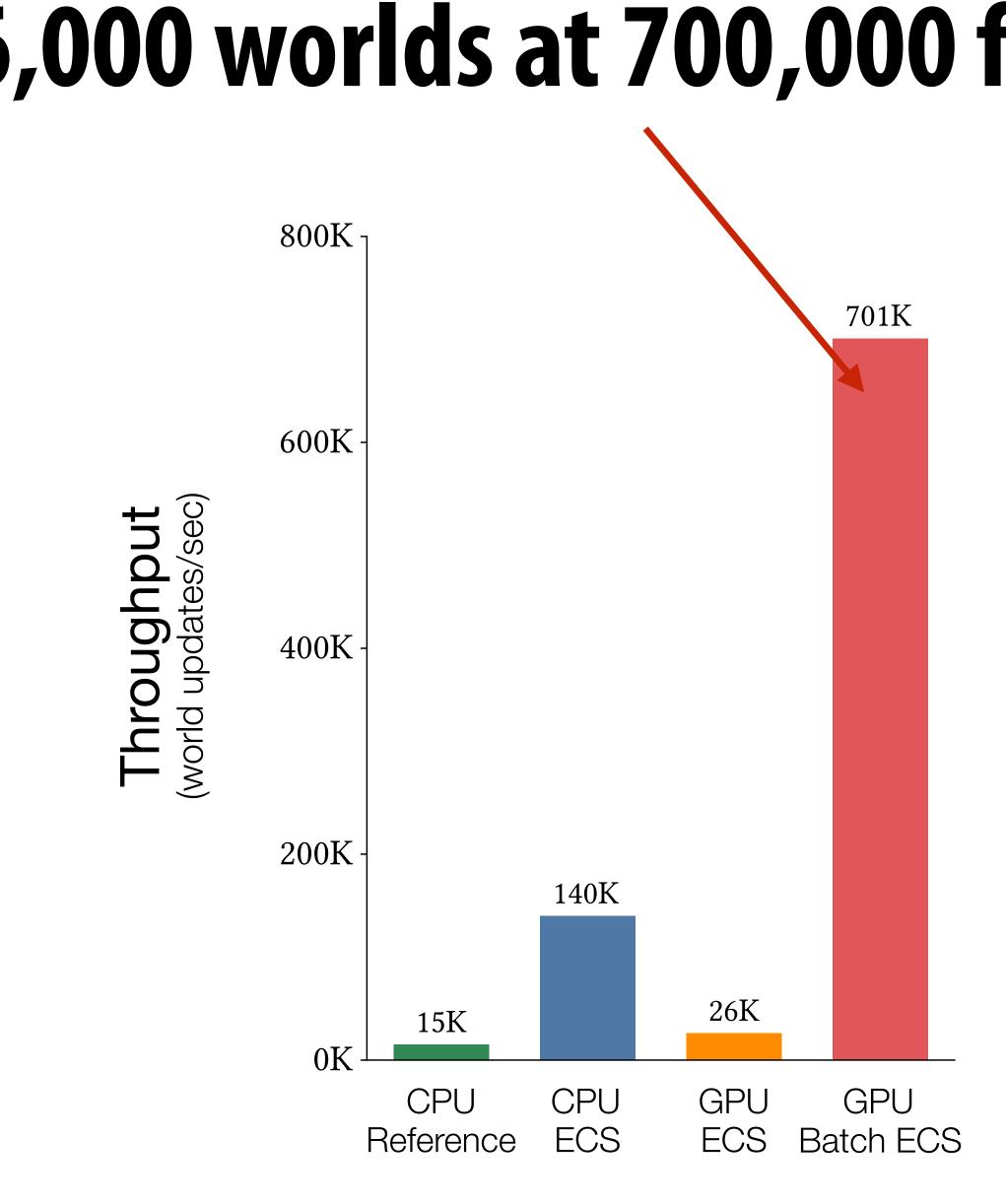
# Example: OpenAl Hide & Seek:



# What if we redesigned a game engine for running billions of independent training runs? How fast could you go?



# Simulating 16,000 worlds at 700,000 fps



## Hide & Seek





### What if up to two instructions can be performed at once?

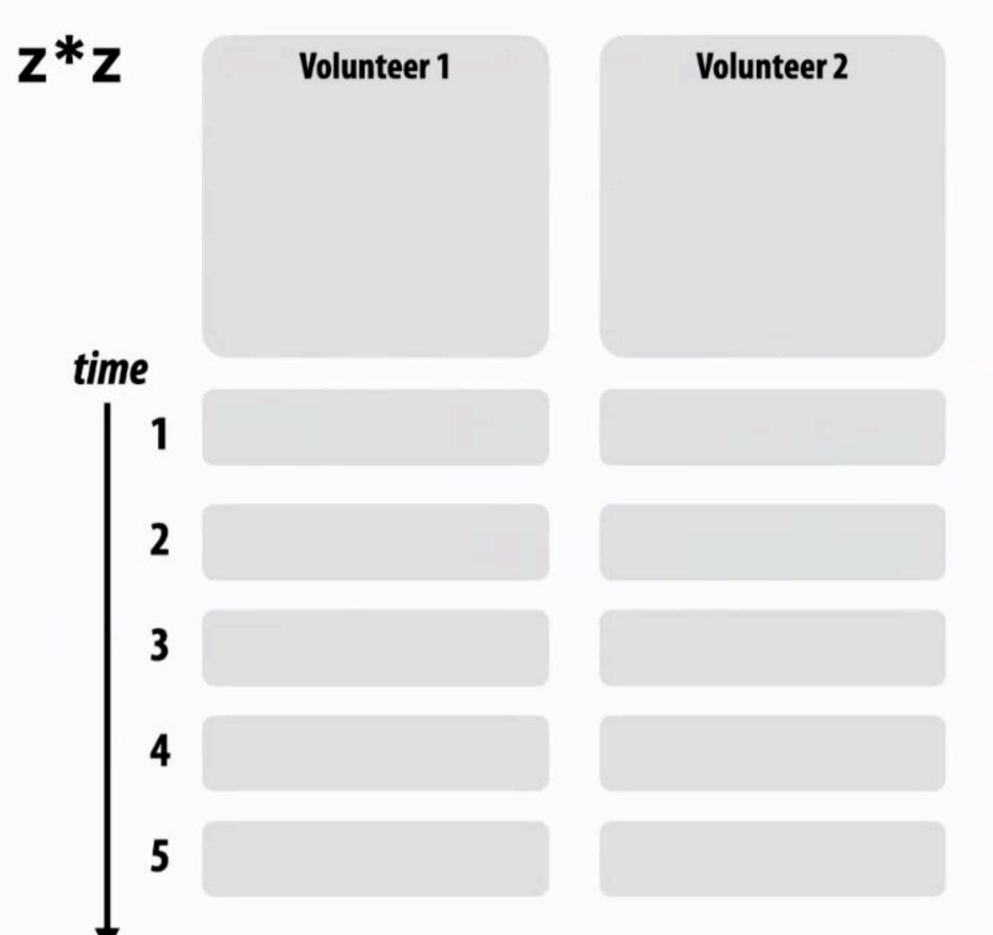
 $a = x^*x + y^*y + z^*z$ 

Assume register R0 = x, R1 = y, R2 = z

1	mul	RØ,	RØ,	RØ
2	mul	R1,	R1,	R1
3	mul	R2,	R2,	R2
4	add	RØ,	RØ,	R1
5	add	R3,	RØ,	R2

R3 now stores value of program variable 'a'









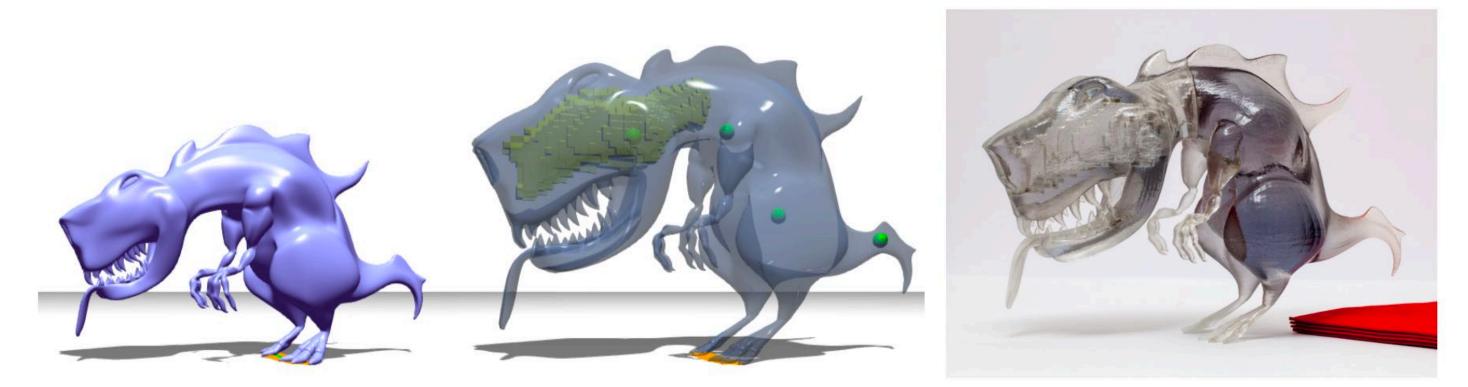
### Other popular research topics in computer graphics...



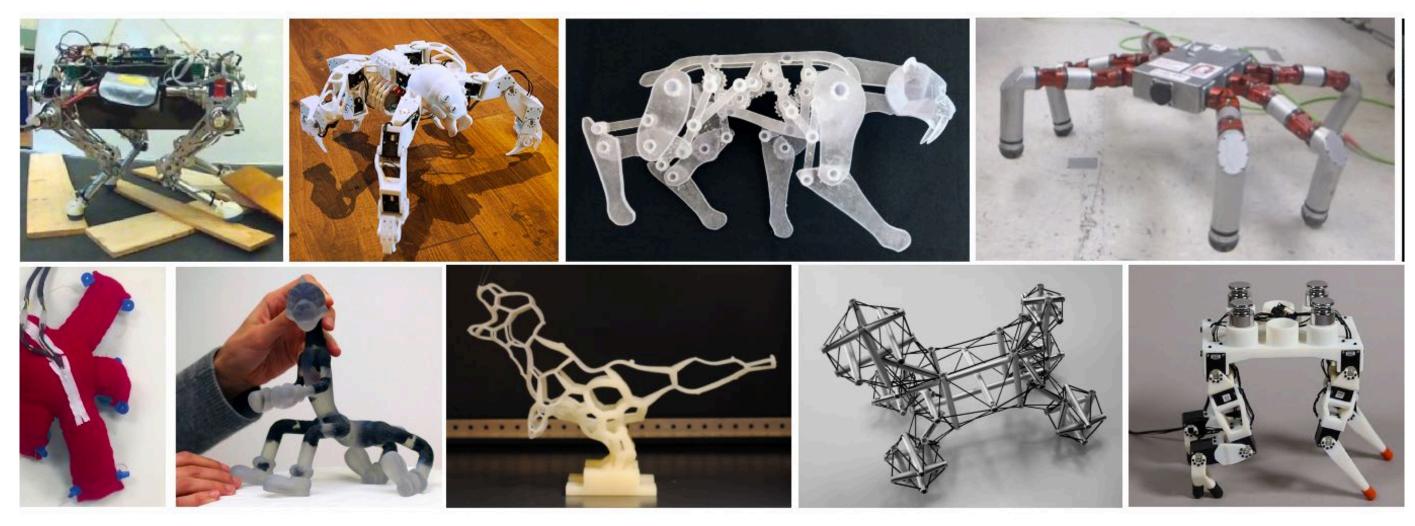
## **Creating physically plausible models**

- Via 3D printing, fabrication
- Creatures that locomotes, furniture that stands, etc.





### Fabricate models that are balanced to stand



### Fabricate robots that can balance and move



# **Computational photography**Using computation (and increasingly machine learning) to make more aesthetic photographs,

### Using computation (and increasingly machine learning) to simulate behavior of more complex lenses, etc.



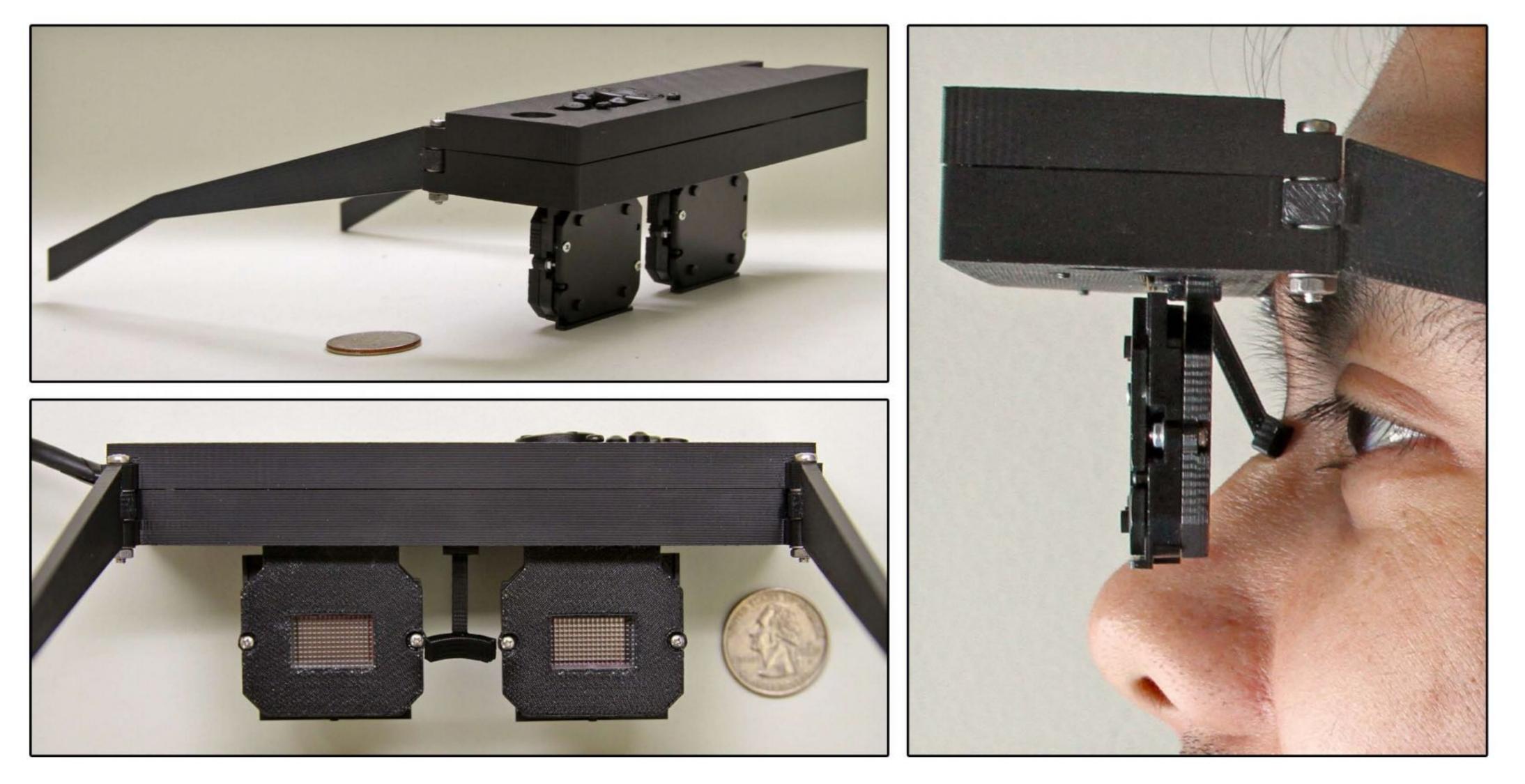
### **Google Pixel 2 Portrait mode**

Image credit: Google / Matt Jones (<u>https://ai.googleblog.com/2017/10/portrait-mode-on-pixel-2-and-pixel-2-xl.html</u>)

Stanford CS248A, Winter 2023



## Advanced displays/rendering for VR/AR



Near eye light field display



### A fun resource

### Ke-sen Huang's famous site with all the SIGGRAPH papers! <u>SIGGRAPH 2022</u> papers on the web http://kesen.realtimerendering.com/

Page maintained by Ke-Sen Huang. If you have additions or changes, send an e-mail.

### Information here is provided with the permission of the ACM

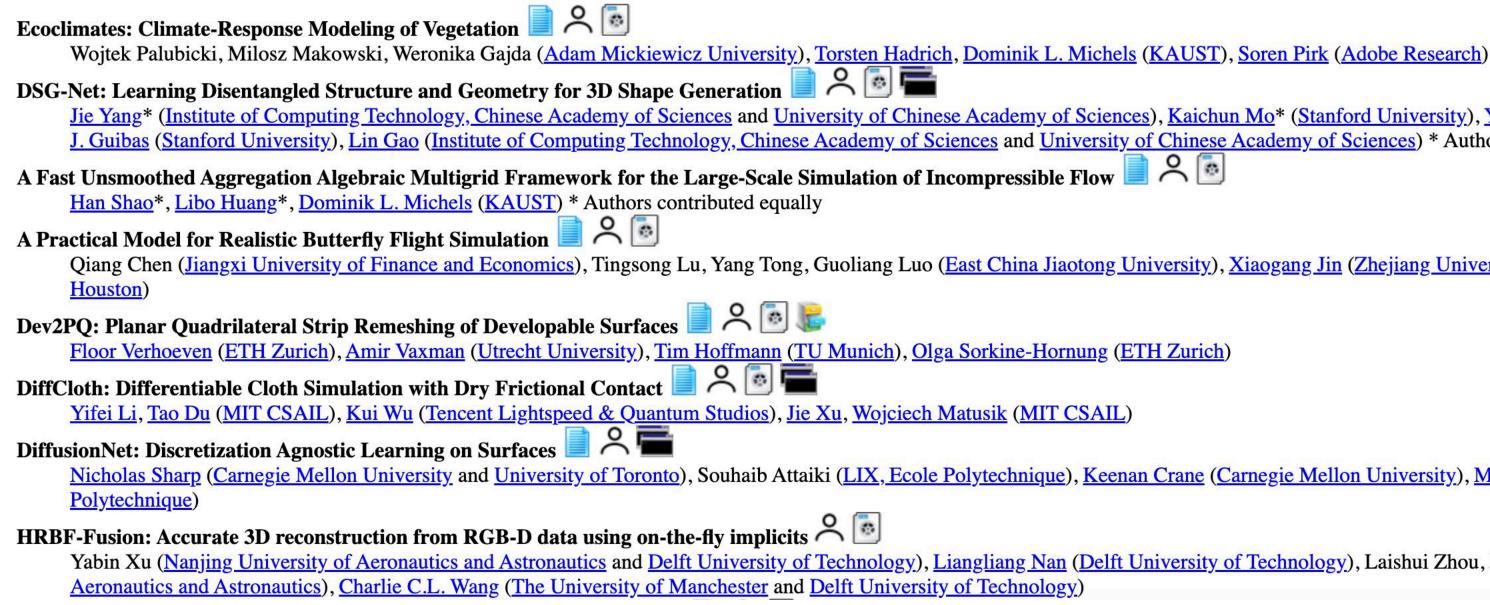
Note that when possible I link to the page containing the link to the actual PDF or PS of the preprint. I prefer this as it gives some context to the paper and avoids possible copyright problems with direct linking. Thus you may need to search on the page to find the actual document.

ACM Digital Library: ACM Transactions on Graphics (TOG) Volume 41, Issue 4 (July 2022) Proceedings of ACM SIGGRAPH 2022



Changelog

### **Conditionally Accepted Papers / TOG Papers**



Jie Yang\* (Institute of Computing Technology, Chinese Academy of Sciences and University of Chinese Academy of Sciences), Kaichun Mo\* (Stanford University), Yu-Kun Lai (Cardiff University), Leonidas J. Guibas (Stanford University), Lin Gao (Institute of Computing Technology, Chinese Academy of Sciences and University of Chinese Academy of Sciences) \* Authors contributed equally 20

Qiang Chen (Jiangxi University of Finance and Economics), Tingsong Lu, Yang Tong, Guoliang Luo (East China Jiaotong University), Xiaogang Jin (Zhejiang University), Zhigang Deng (University of

Nicholas Sharp (Carnegie Mellon University and University of Toronto), Souhaib Attaiki (LIX, Ecole Polytechnique), Keenan Crane (Carnegie Mellon University), Maks Ovsjanikov (LIX, Ecole

Yabin Xu (Nanjing University of Aeronautics and Astronautics and Delft University of Technology), Liangliang Nan (Delft University of Technology), Laishui Zhou, Jun Wang (Nanjing University of

Stanford CS248A, Winter 2023



## Discussion: graphics jobs



### **Discussion: how to get involved in graphics at Stanford**

- Email your graphics professors and ask to talk to them about independent study
- class and did well and want to keep going)
- A common way to get started

- Hack code to contribute to a Ph.D. student's research project

- Although to be honest... the best intro line is ("I took and loved your 300-level graphics



## Why research (or independent study)?

- You will learn way more about a topic than in any class.
- working on. (imagine how much more valuable you are if you can teach them)
- It widens your mind as to what is possible.

You think your undergrad friends are very smart? Come hang out with Stanford Ph.D. students! (you get to work side-by-side with them and with faculty). Imagine what level you might rise to.

It's way more fun to be on the cutting edge. Industry might not even know about what you are



## Maybe you might like research and decide you want to go to grad school

being part of a research team for an extended period of time.

DWIC letter: ("did well in class" letter) What you get when you ask for a letter from a faculty thrown out by the Ph.D. admissions committee at good schools.

- Pragmatic comment: Without question, the number one way to get into a top grad school is to receive a strong letter of recommendation from faculty members. You get that letter only from
- member who you didn't do research with, but got an 'A' in their class. This letter is essentially



### A very good reference **CMU Professor Mor Harchol-Balter's writeup:** "Applying to Ph.D. Programs in Computer Science"

http://www.cs.cmu.edu/~harchol/gradschooltalk.pdf



### Thanks for being a great class!

Good luck finishing projects.

Make sure you have fun, that's the point!



