

**Lecture 9:**

# **Generating Supervision**

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**Parallel Computing**  
**Stanford CS348K, Spring 2021**

# Note

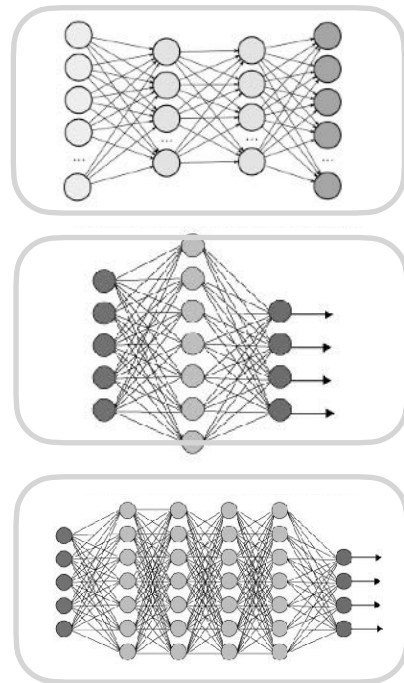
- **Much of this class involved discussing the Snorkel paper(s)**

# Today's theme

- **Data alone is not precious. Today, in many domains large collections of *unlabeled data* are readily accessible**
- **But labels (supervision) for this data is extremely precious**
- **Implication: ML engineers are interested in using any means necessary to acquire sources of supervision**

# Today's problem setup

Given:



**Pre-trained models  
(other tasks)**

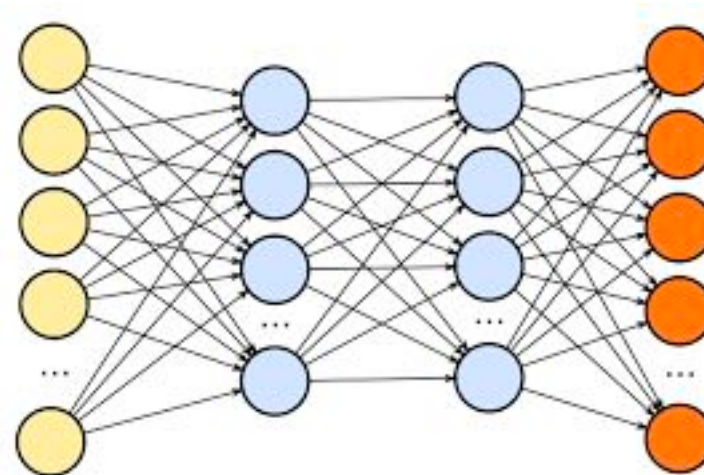


**Huge corpus of unlabeled data  
Perhaps with a sparse set of human labels**



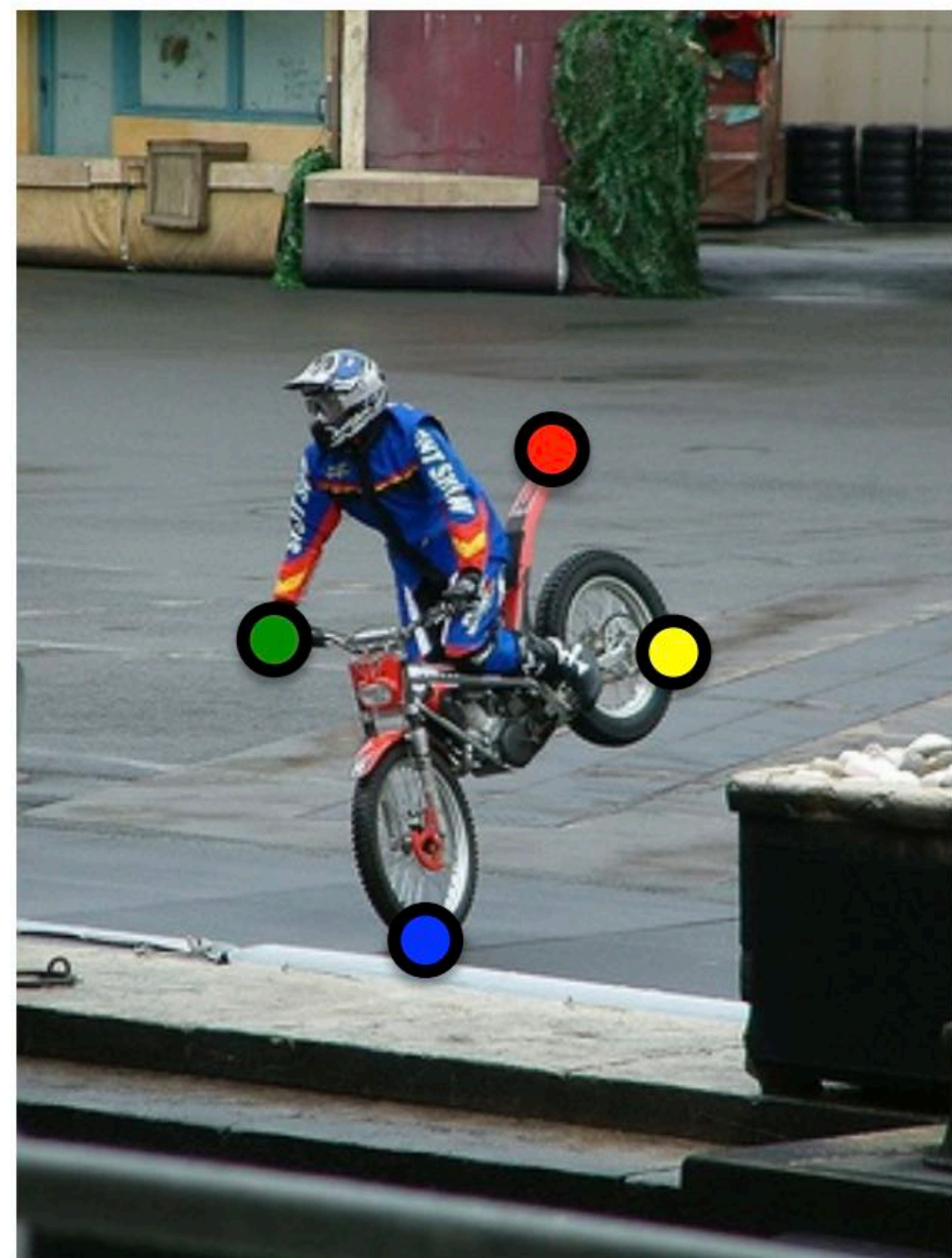
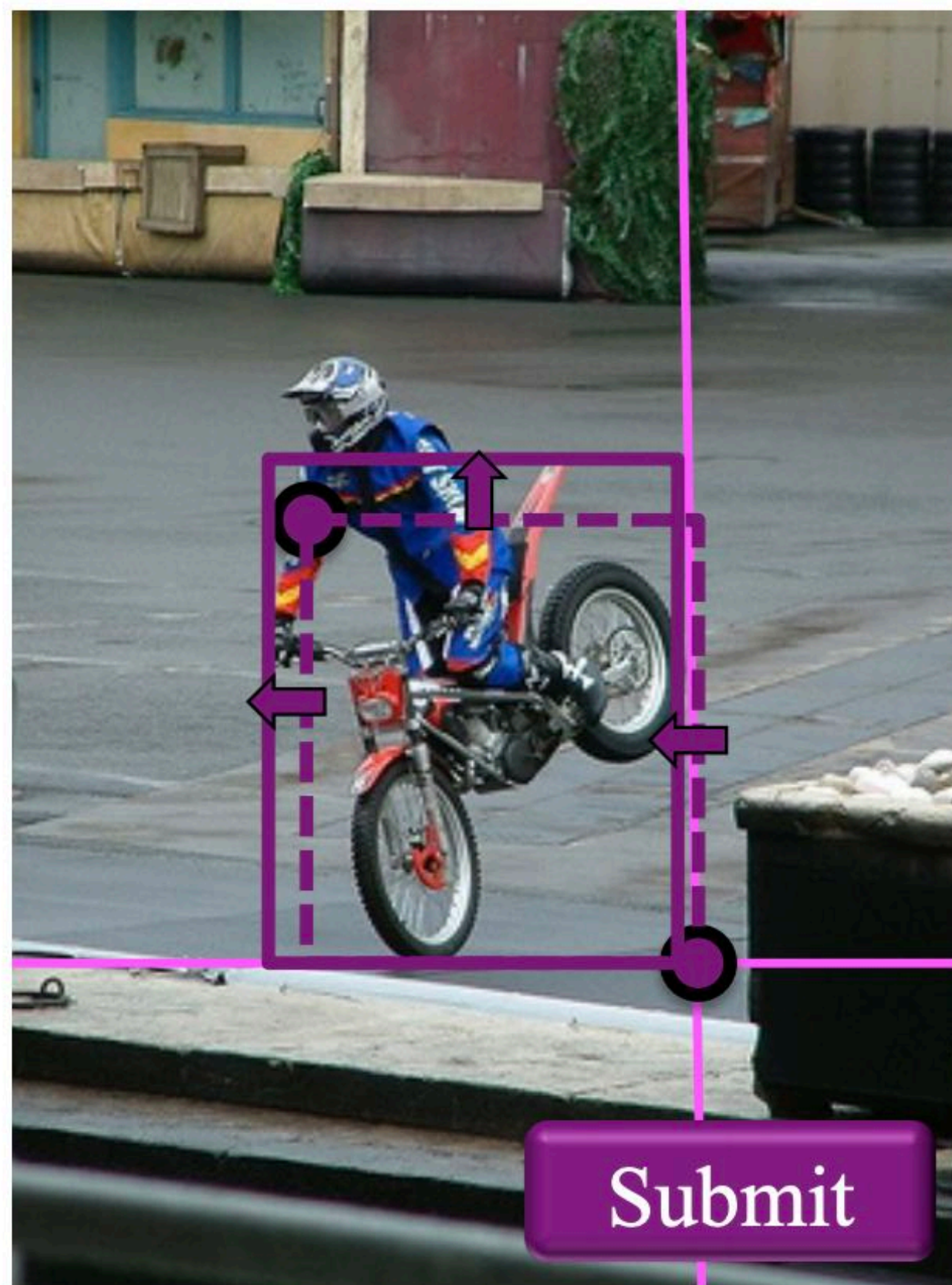
**Abundant  
Compute**

**Goal: generate large amounts of supervision for use in training  
a model for a new task of interest**



# Making human labelers more efficient

- Example: “extreme clicking” is a faster way to define an object bounding box AND IT ALSO gives four points on the object’s silhouette

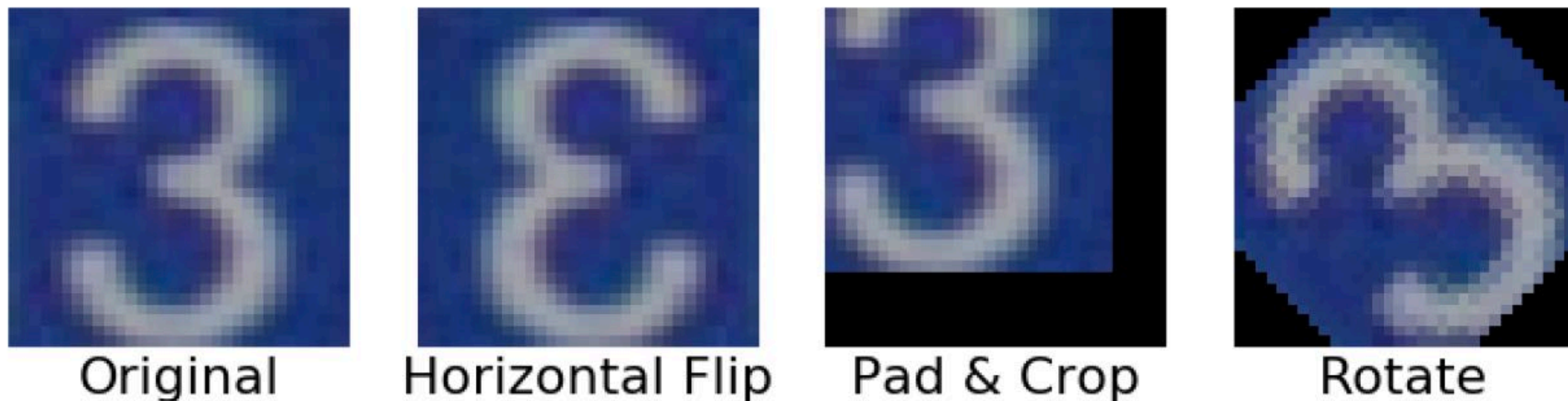


5x faster for humans to label

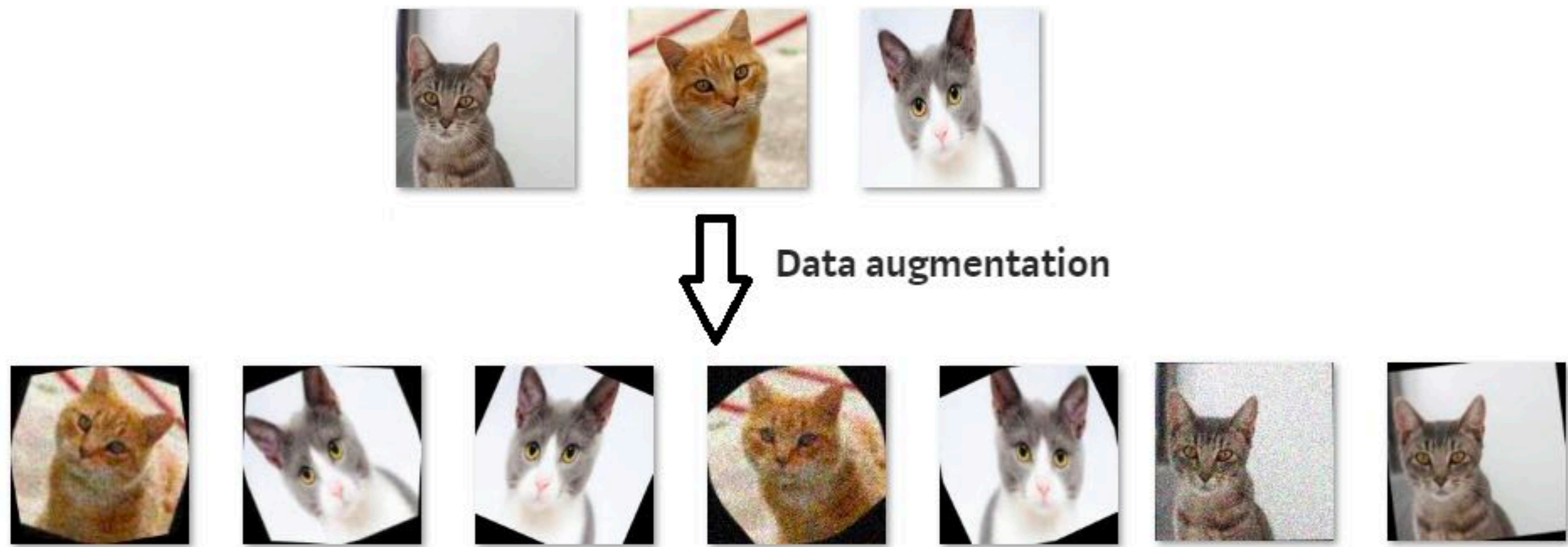
**Amplify sparse human labels:  
Automatically transfer labels from  
labeled data points to “similar”  
unlabeled data points**

# Data augmentation

Apply category-preserving transformations to images to increase size of labeled dataset.



[Image credit: Ho et al. ICML 2019]

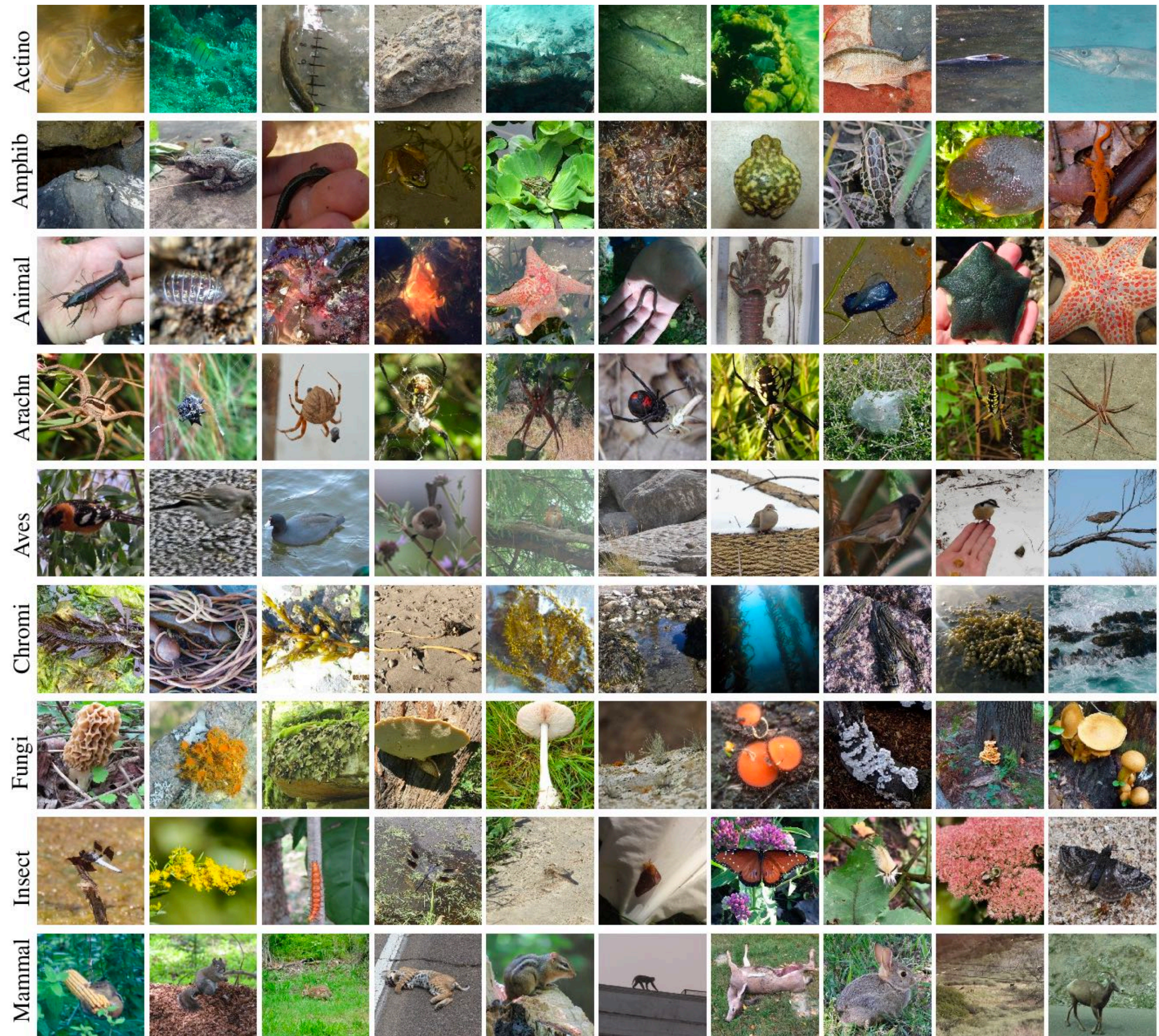


[Source: <https://medium.com/@thimblot/data-augmentation-boost-your-image-dataset-with-few-lines-of-python-155c2dc1baec>]

# Must be mindful of which transformations are label preserving for a task

Example: iNaturalist dataset

Is color change a good data augmentation?





# Label transfer via visual similarity

If I know this image contains a cactus, then visually similar images in my unlabeled collection likely also contain a cactus as well.

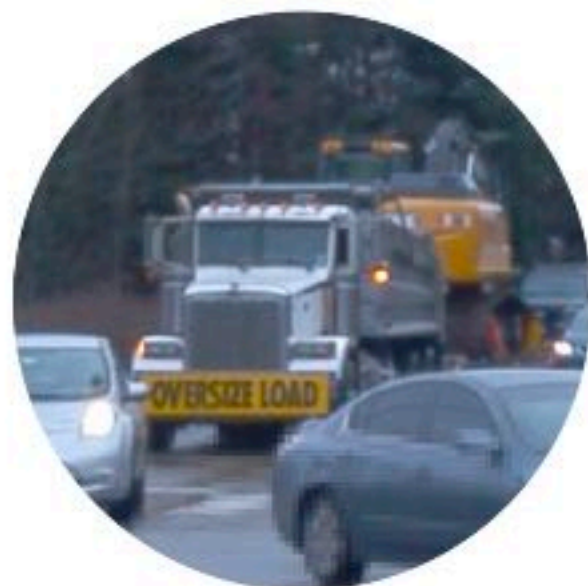


Saguaro cactus

visually similar

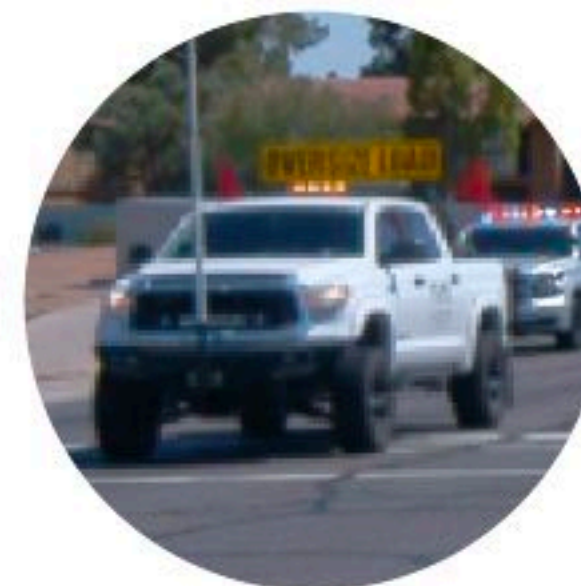


What are good ways to define similar?



"Oversize load"

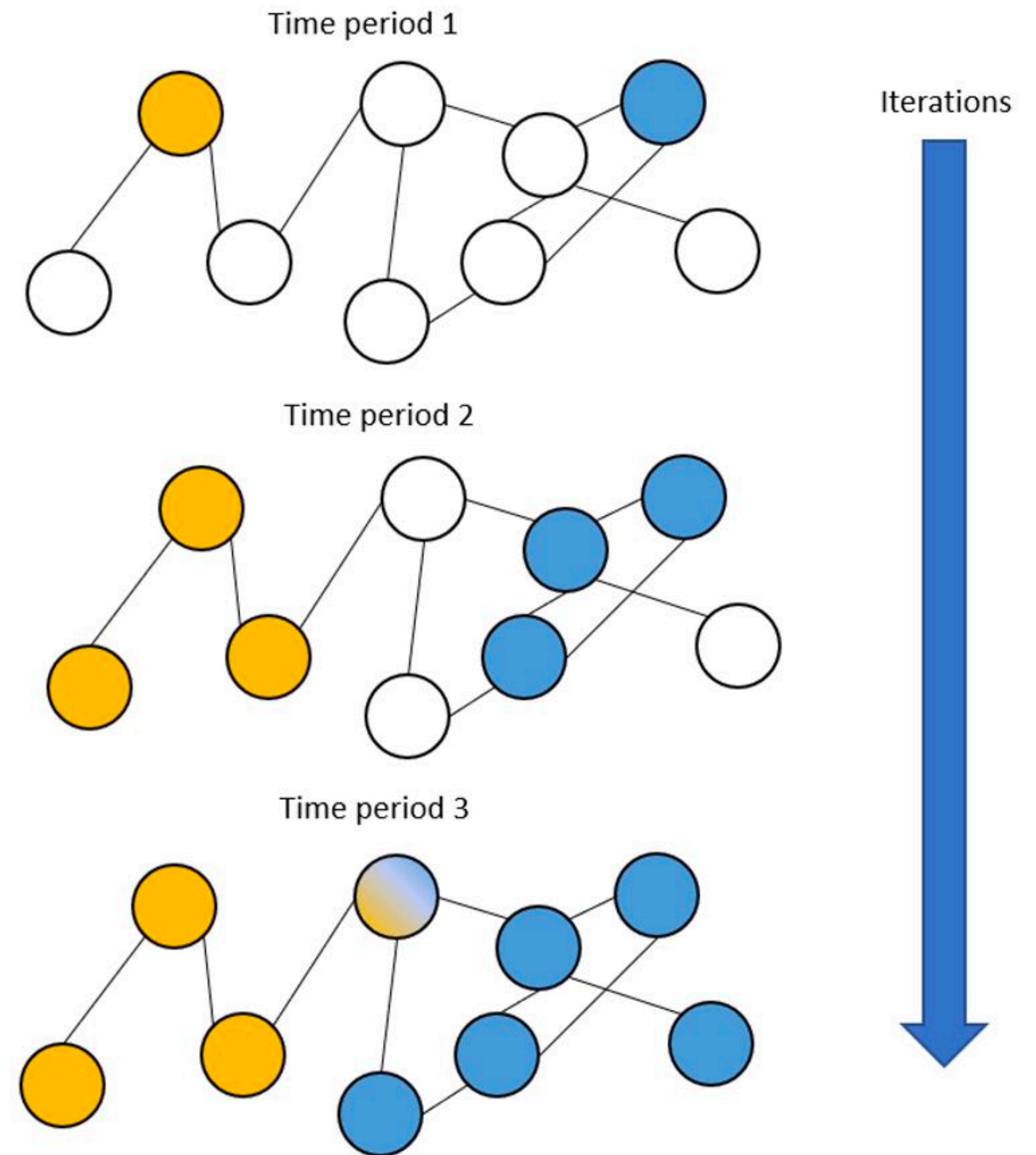
has same text



# Label transfer via label propagation

- **Given graph of unlabeled data points**
  - e.g., nodes = images, edge weights given by visual similarity
- **“Diffuse” sparse labels onto unlabeled nodes**

Label Propagation Algorithm

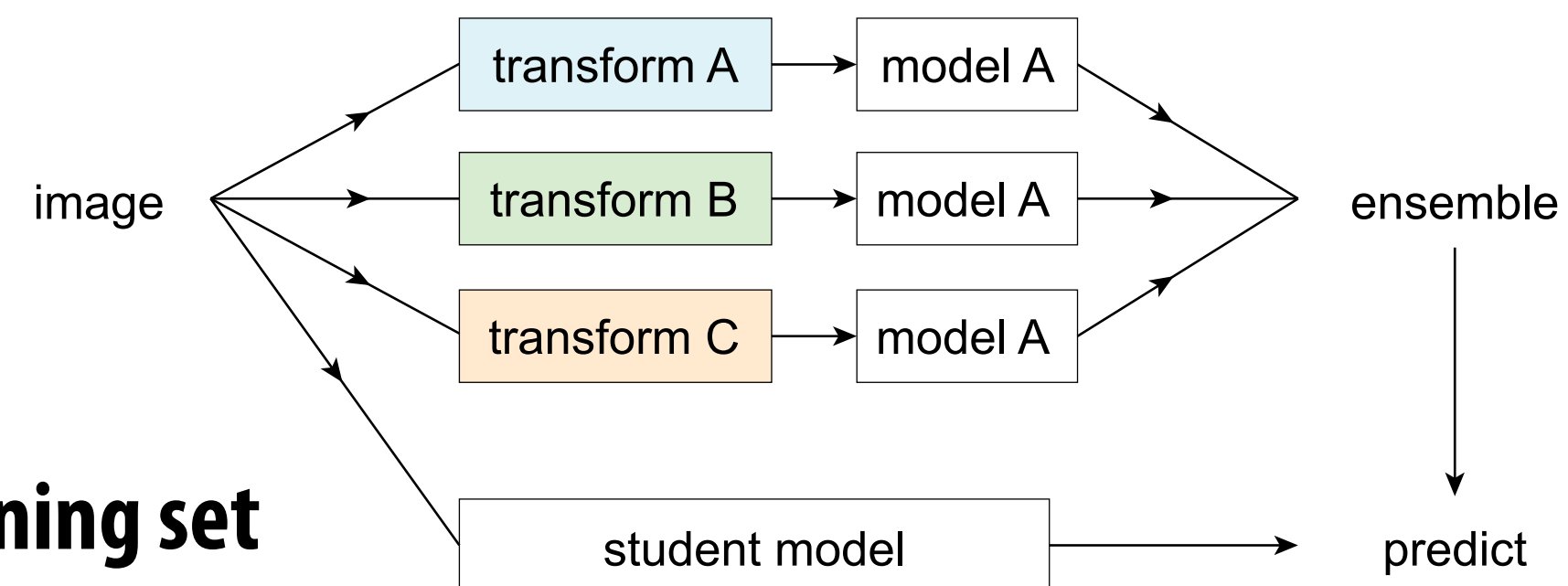


# **Key idea: bringing in additional priors**

**Priors from previous examples:**

- 1. similar images likely have same label (knn, label prop, clustering)**
- 2. Certain transformations will not change the label**

# Using a trained model to supervise itself

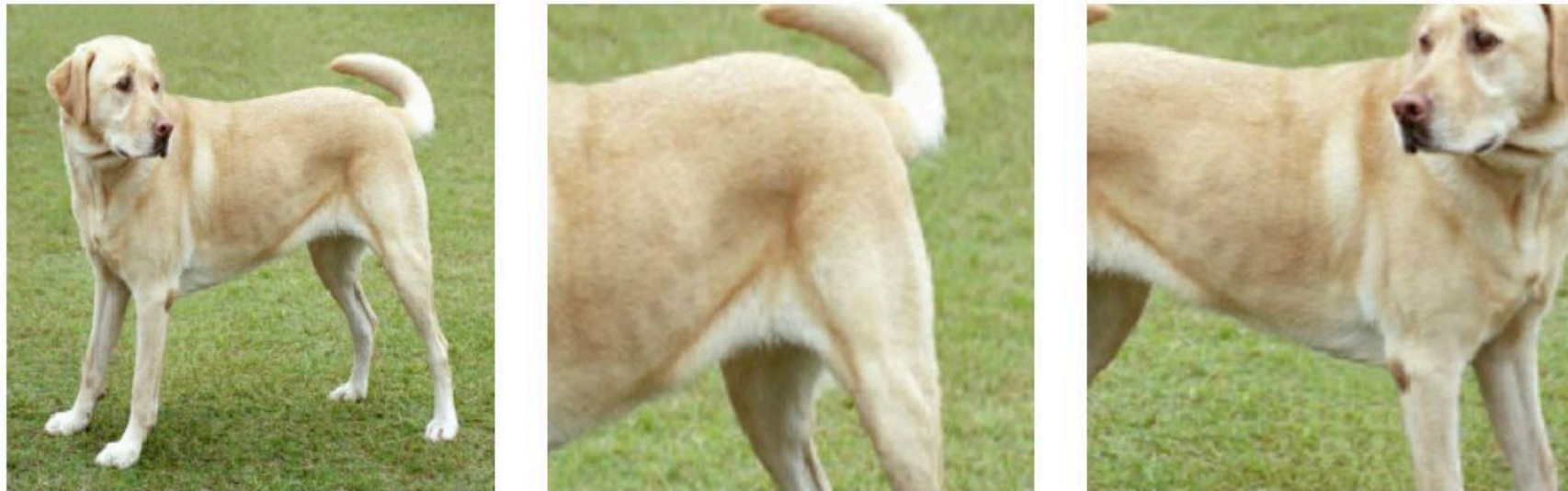


- **Example: omni-supervised learning**
- **Train original model using smaller labeled training set**
- **Evaluate model on different augmentations of unlabeled image**
  - *Ensemble model's predictions to estimate "ground truth" label for image*
- **Re-train model on both labeled images AND estimated labels from ensemble**

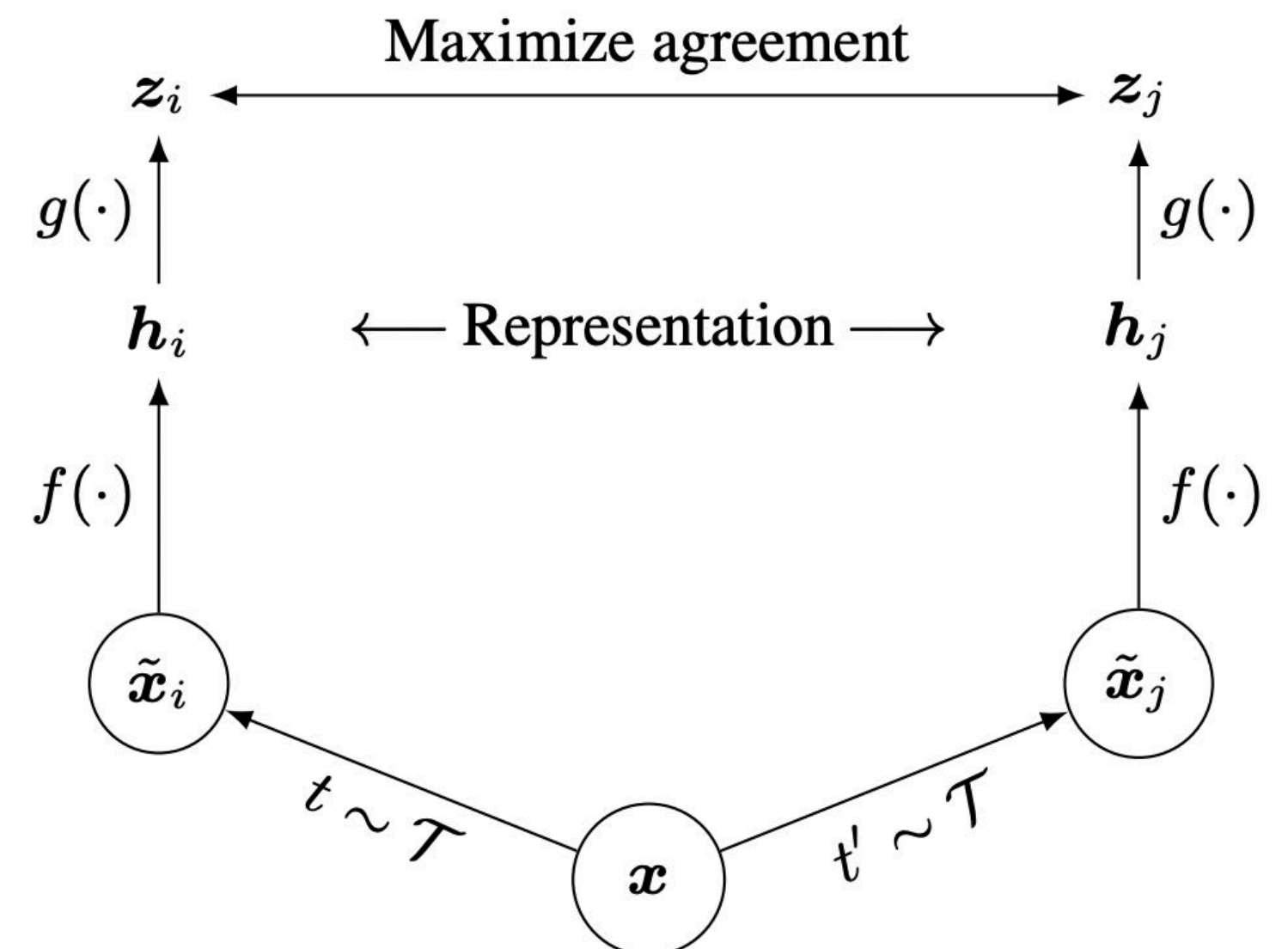
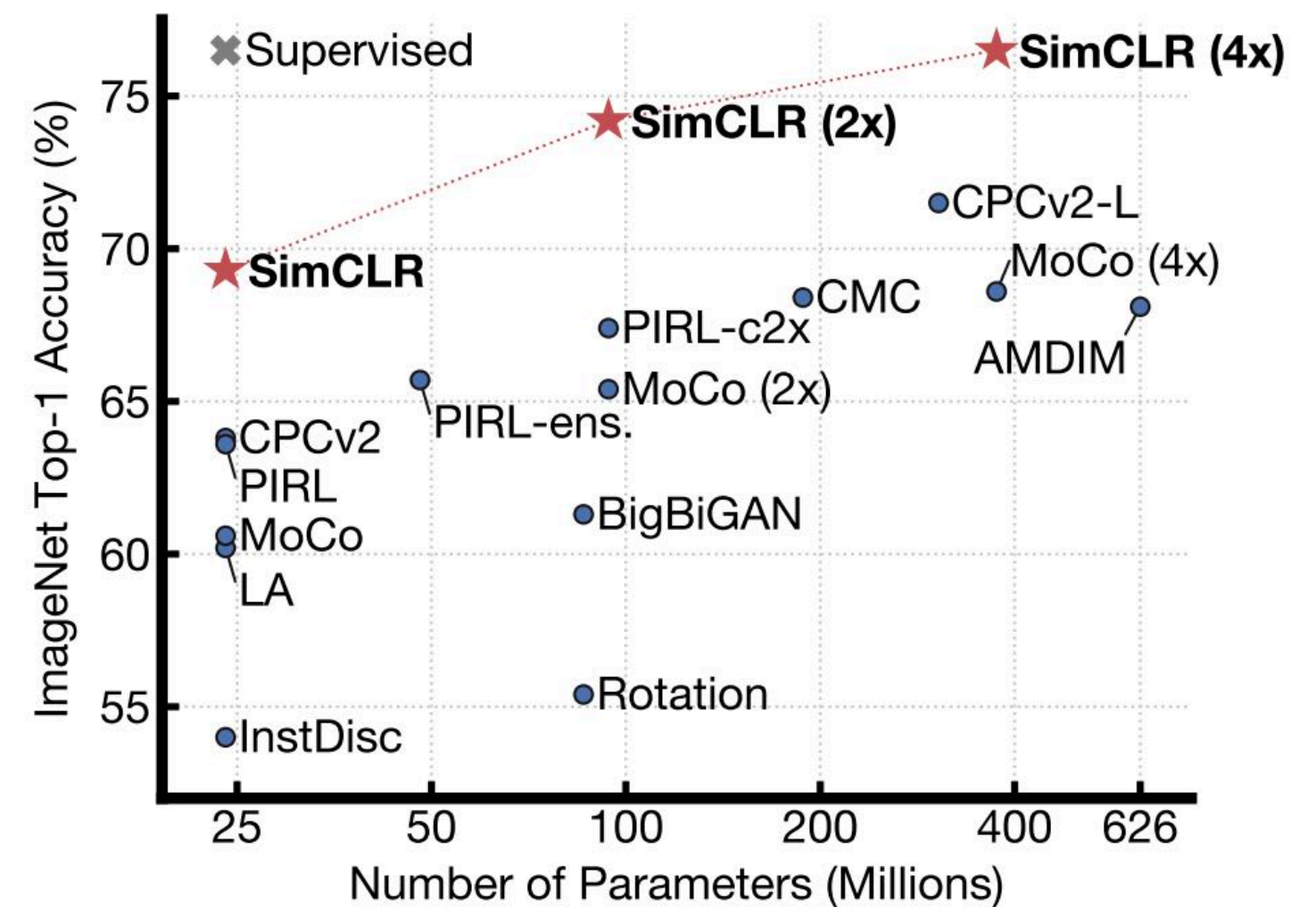
backbone	DD	AP	AP <sub>50</sub>	AP <sub>75</sub>	AP <sub>S</sub>	AP <sub>M</sub>	AP <sub>L</sub>
ResNet-50		37.1	59.1	39.6	20.0	40.0	49.4
ResNet-50	✓	<b>37.9</b>	<b>60.1</b>	<b>40.8</b>	<b>20.3</b>	<b>41.6</b>	<b>50.8</b>
ResNet-101		39.2	61.0	42.3	21.7	42.9	52.3
ResNet-101	✓	<b>40.1</b>	<b>62.1</b>	<b>43.5</b>	<b>21.7</b>	<b>44.3</b>	<b>53.7</b>
ResNeXt-101-32×4		40.1	62.4	43.2	22.6	43.7	53.7
ResNeXt-101-32×4	✓	<b>41.0</b>	<b>63.3</b>	<b>44.4</b>	<b>22.9</b>	<b>45.5</b>	<b>54.8</b>

# Modern trend: unsupervised pre-training

- Unsupervised pre-training at scale (using lots of data and using large models) learns good representations
- e.g. SimCLR, based on contrastive loss
- Give training image  $x$ , apply augmentation  $t(x)$  (crop, resize, flip)



- Train DNN with contrastive loss that encourages projection of different transformations of the same image  $x$  to be close ( $g(f(t(x)))$  close to  $g(f(t'(x)))$ ), transformations of different images to be far.



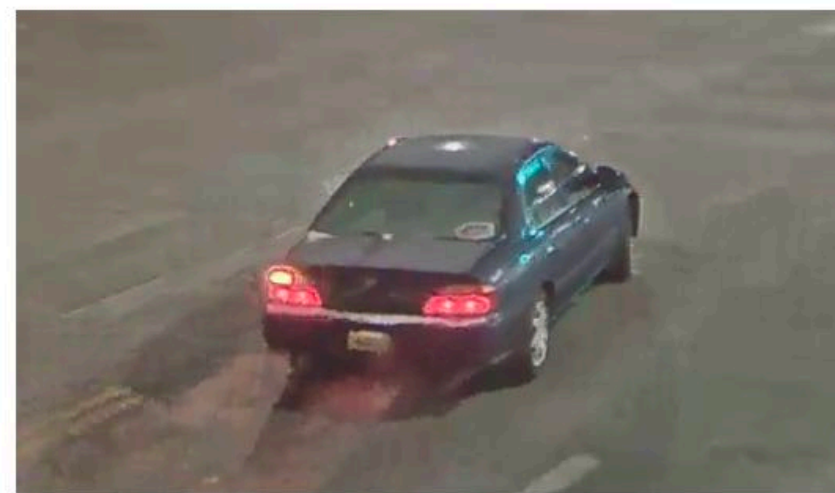
# Providing supervision by writing programs

# Encode external priors in programs

- **Example: temporal consistency prior: the state of world should not change significantly from frame to frame**



Frame 1



Frame 2

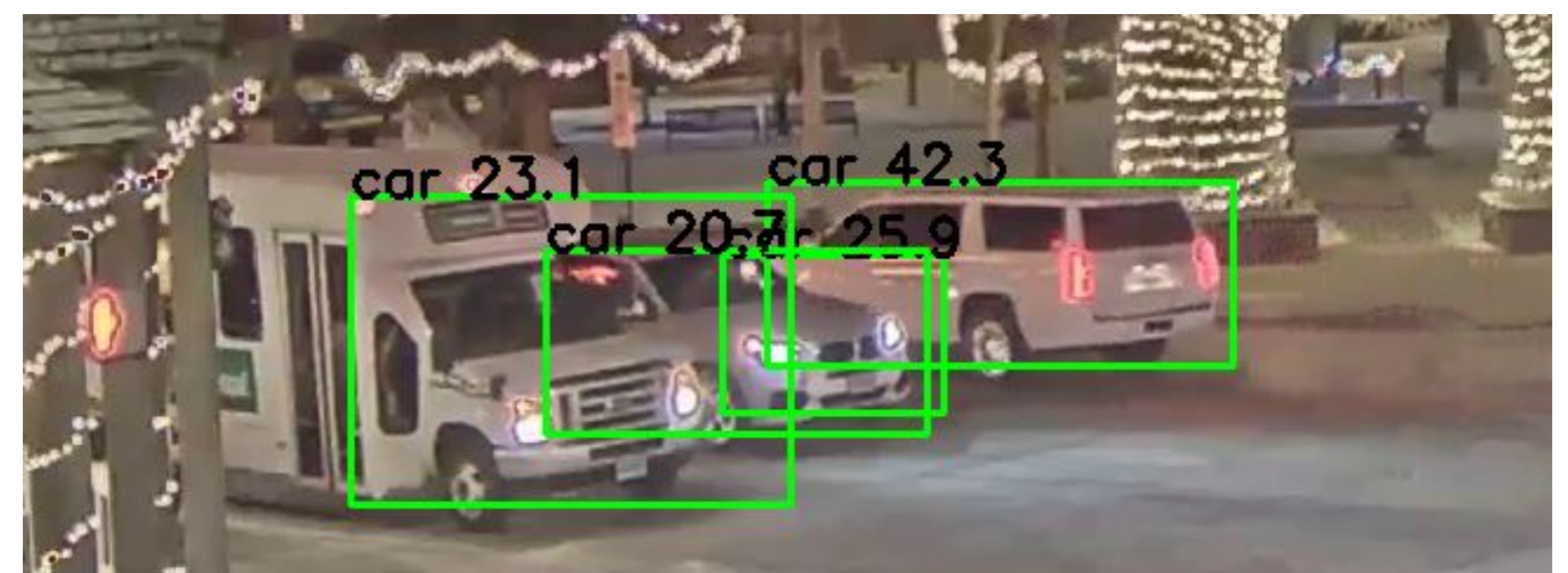


Frame 3

- **Example: domain-knowledge prior: objects like cars cannot overlap in space**



(a) Example error 1.



(b) Example error 2.

# DB queries as concept “detectors”

(find elements in database matching this predicate)



⋮

⋮

⋮

Video Collection

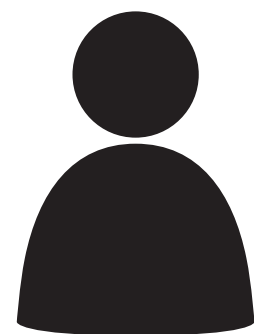
Basic Annotations



Face Detections

3:15–3:16: BERNIE...  
 5:18–5:20: THANK YOU...  
 9:15–9:17: TODAY IN...

Captions



Analyst

```
def bernie_and_jake(faces):
    bernie = faces
        .filter(face.name == "Bernie")
    jake = faces
        .filter(face.name == "Jake")

    bernie_and_jake = bernie
        .join(jake,
            predicate = time_overlaps,
            merge_op = span)

    return bernie_and_jake
```



# Three-person panels

(three faces, bounding boxes greater than 30% of screen height, in horizontal alignment)



**Today's discussion:  
using weak supervision via "data programming"**

# **Many, many ways to find, generate, and operationalize supervision**

- **Multiple-modalities of data, knowledge in prior models, weak sources of supervision, return to basic heuristics, etc.**
- **It does seem like better platform and system support would be helpful here! (more next class)**