

**Lecture 9:**

# **Generating Behaviors: AI Agents for Virtual Worlds**

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**Visual Computing Systems  
Stanford CS348K, Spring 2025**

**Why is there interest in creating agents that  
Can successfully perform tasks in virtual worlds?**

# **Application area 1: robotics**

**Train in simulation to learn behaviors that work in the real world.**

# Train embodied agents in simulation prior to deploying them in the real world

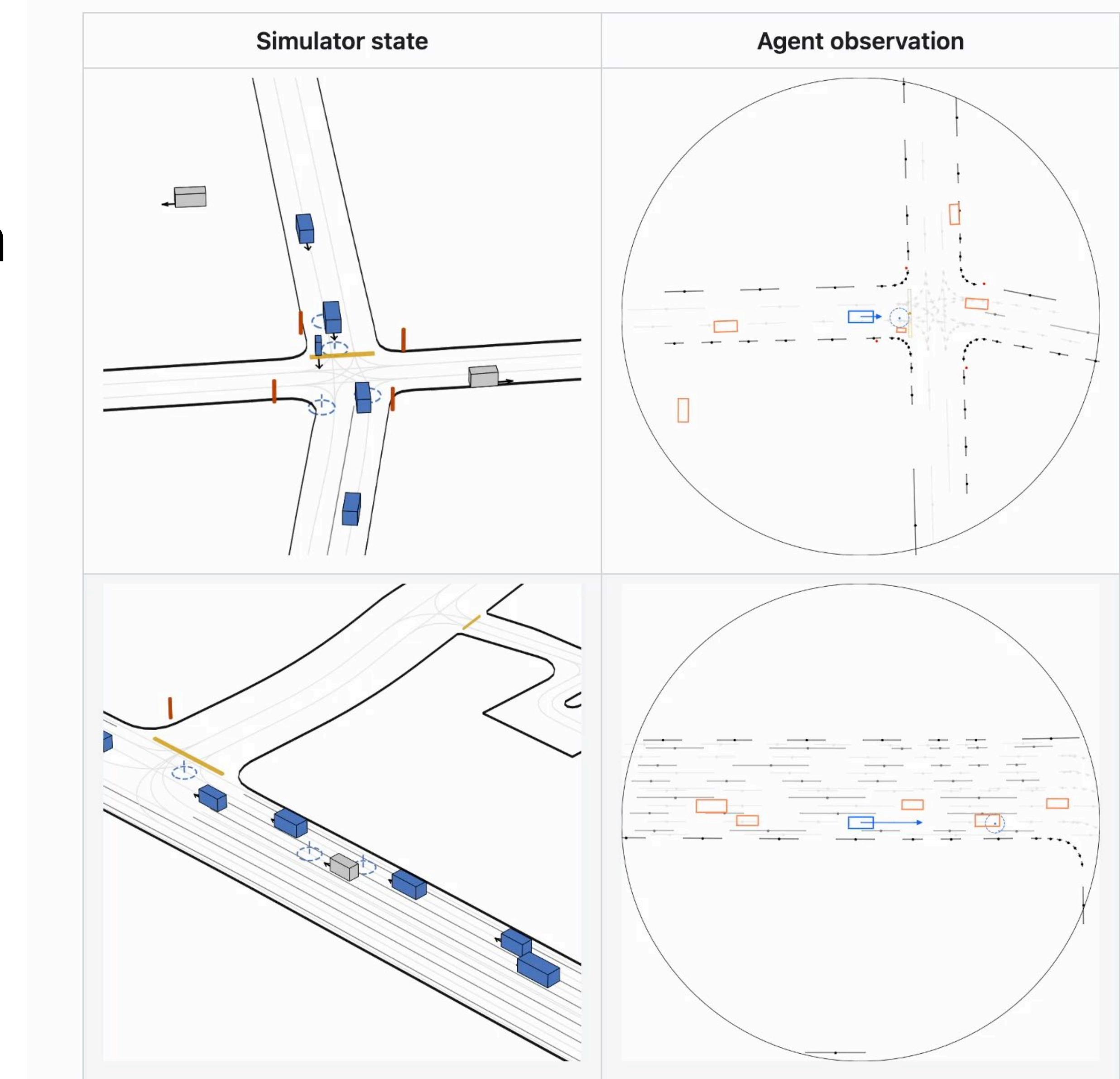
Using the virtual world as a proxy for the real world.

Example task: navigating an autonomous vehicle



# Simulation need not be “photorealistic”

- Choose to simulate at level of detail needed for task at hand
  - e.g., separate needs of world perception from planning



# Train embodied agents in simulation prior to deploying them in the real world

Using the virtual world as a proxy for the real world.

Example task: navigating the home and manipulating items in the home.



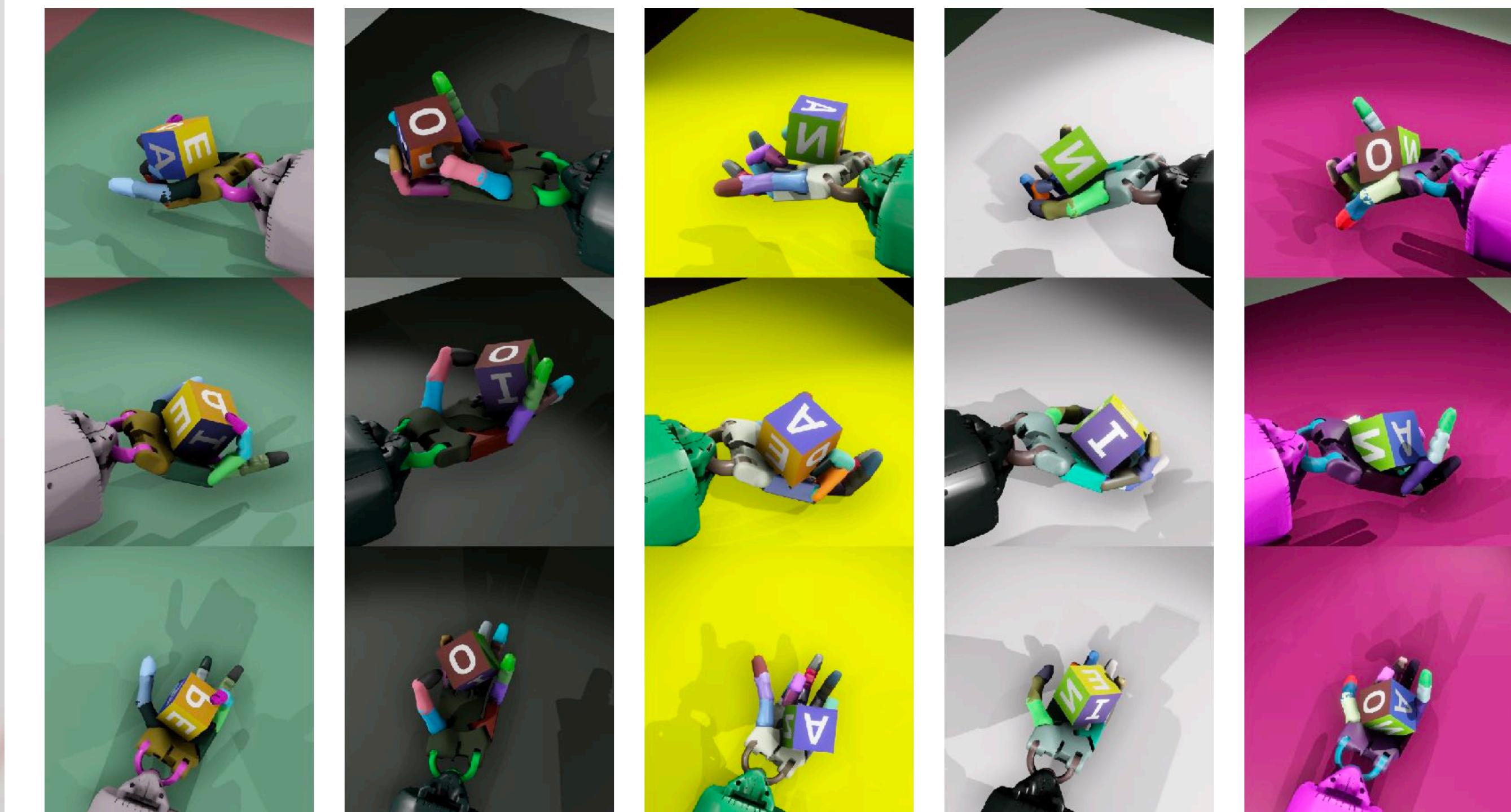
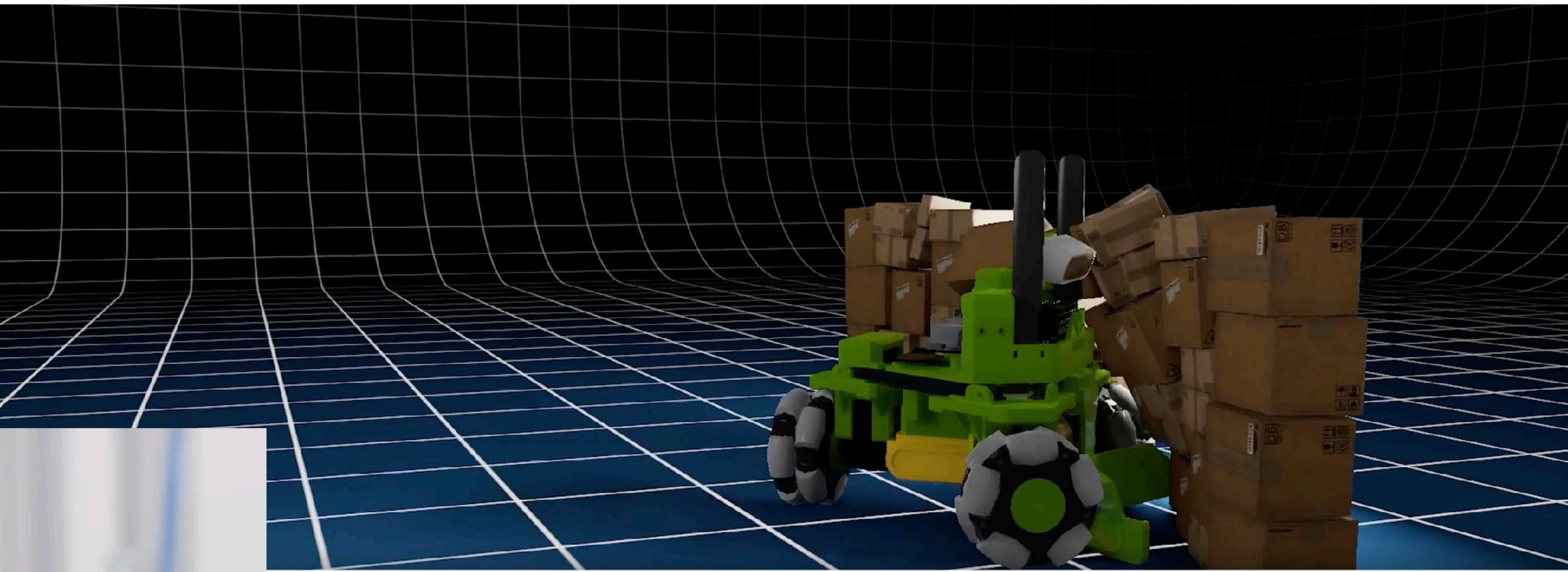
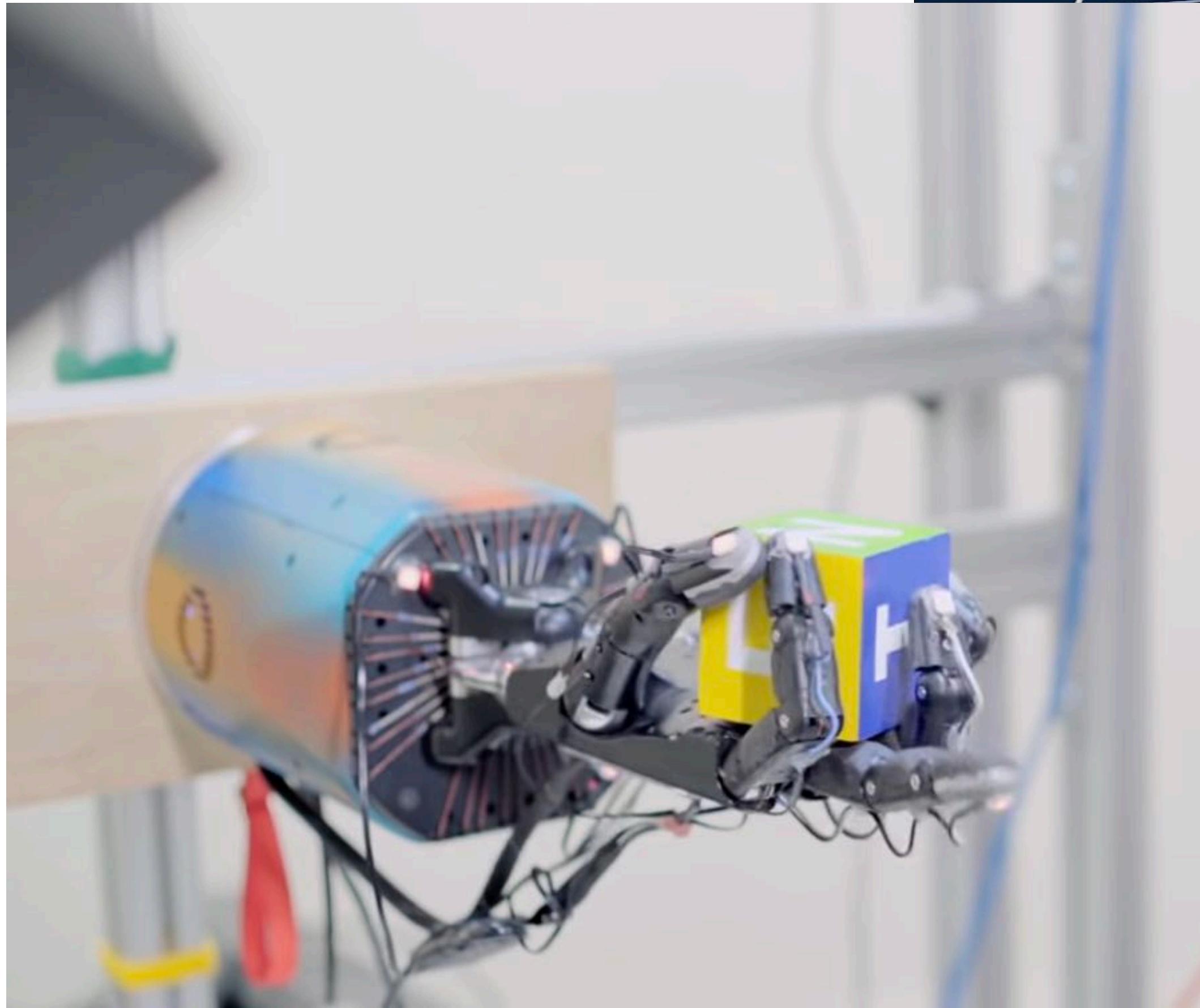
Szot et al, NeurIPS 2021



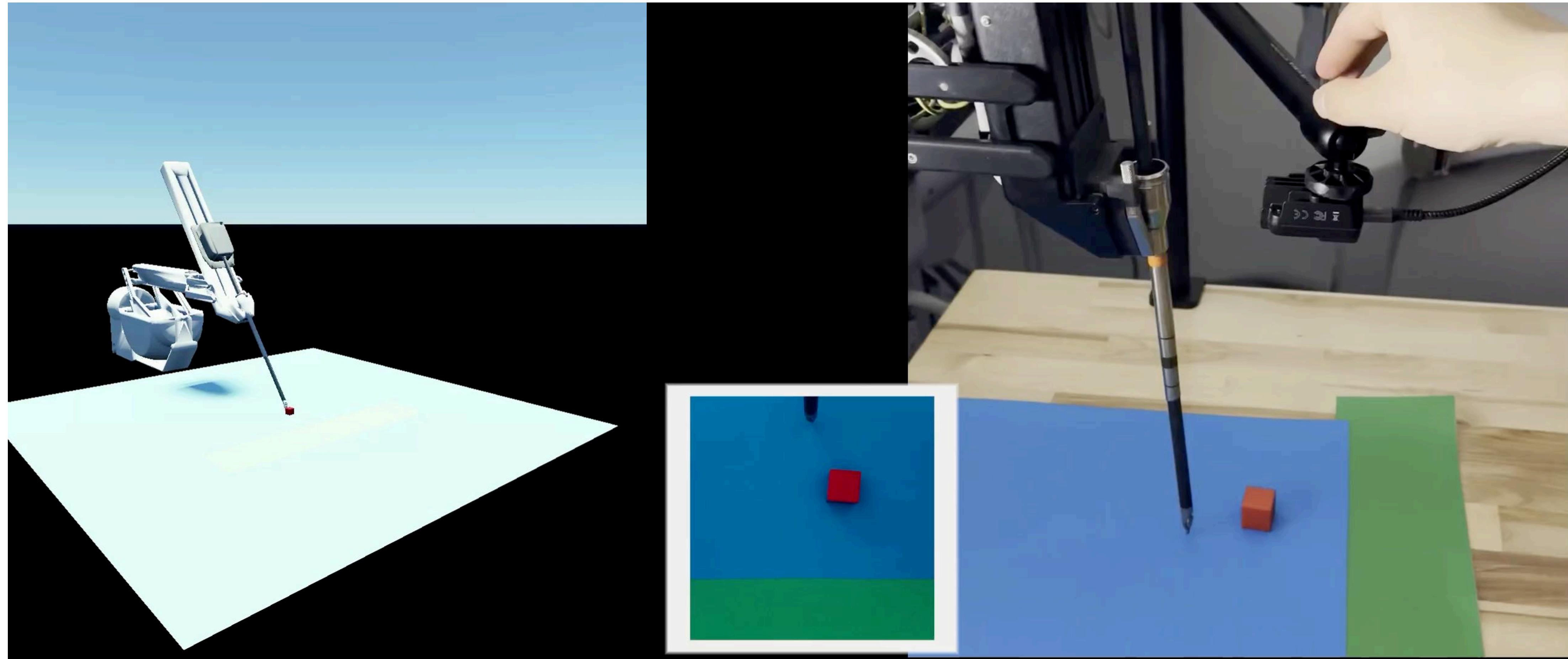
Stanford CS348K, Spring 2025

# Dexterous manipulation

Example task: precise manipulation of objects



# Simple sim-to-real transfer with domain randomization



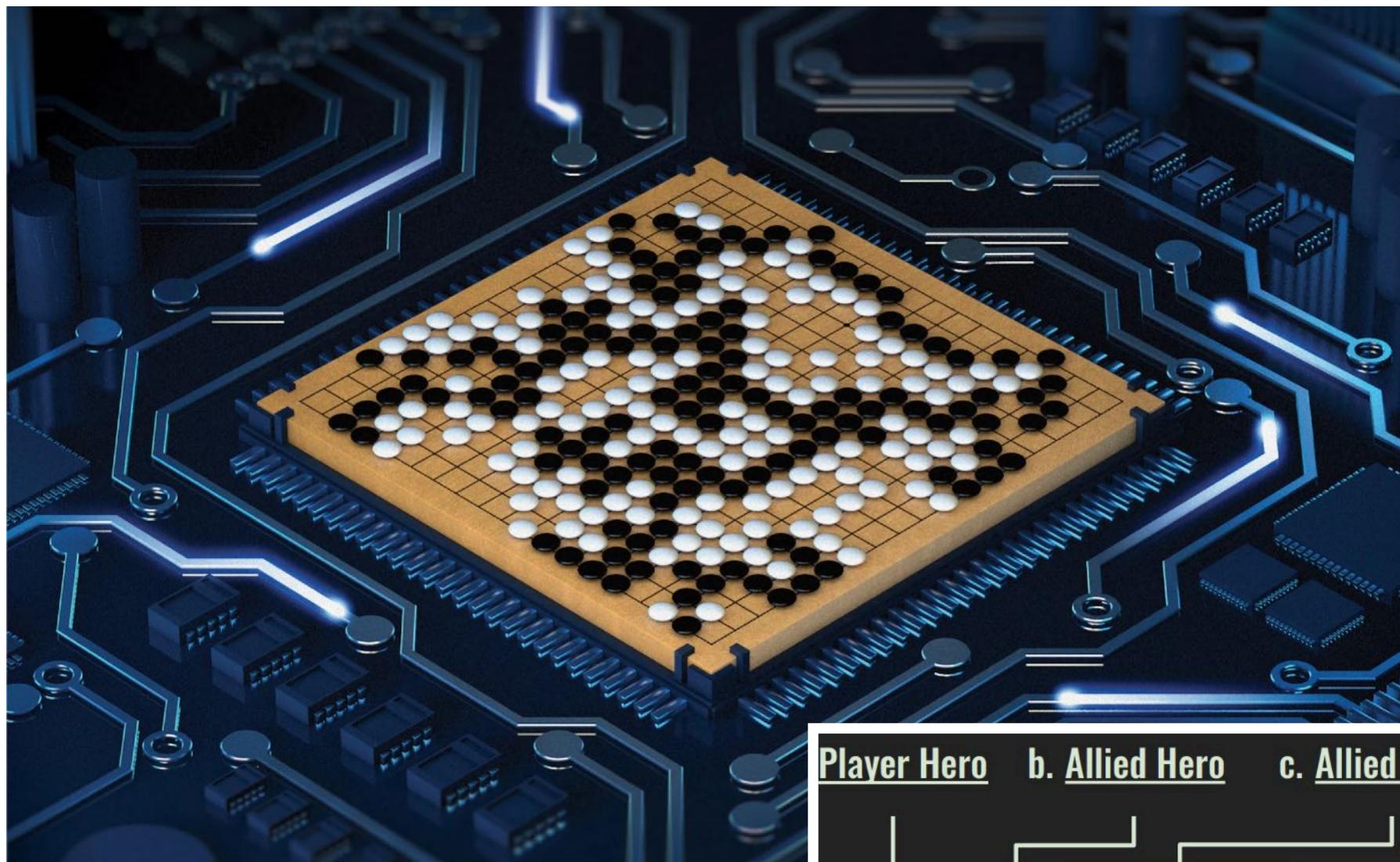
## **Application area 2: video game agents**

**Train agents to function as autonomous game players**

**(Both in pursuit of better bots, and as a pure science exercise)**

# Mid-to-late 2010's: pursuit of superhuman performance via large-scale deep RL

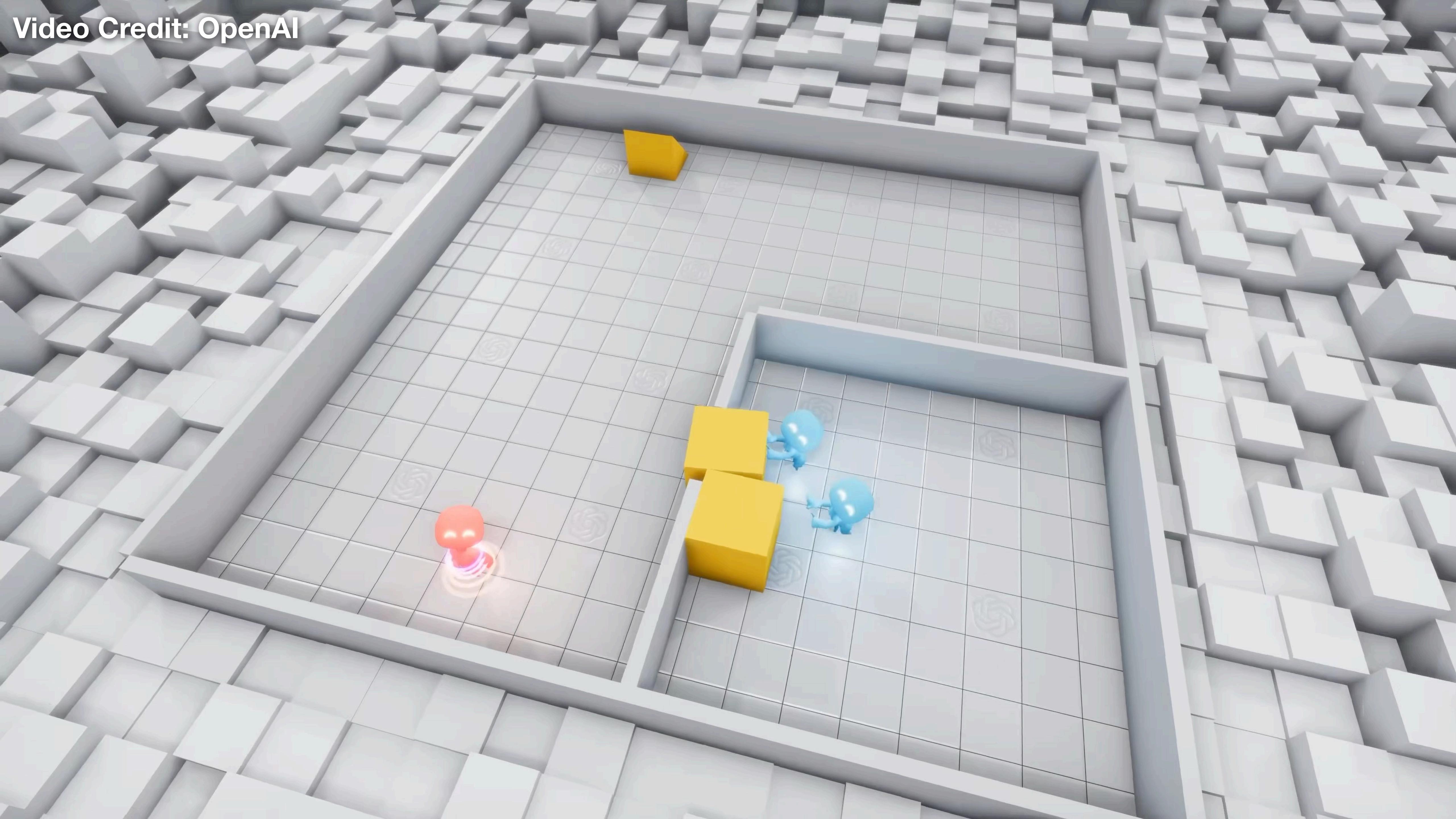
## DeepMind AlphaGo



Demonstrations of large-scale use of reinforcement learning to learn “creative” play and expert levels skills



Video Credit: OpenAI



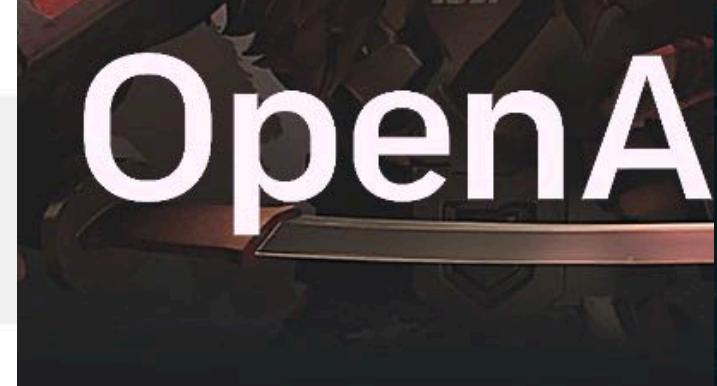
Random incoming ball + Random target



Practice in simulation...

# Scale of experience collected: OpenAI's "OpenAI 5" Dota 2 bot

OPENAI FIVE	
CPUs	128,000 preemptible CPU cores on GCP
GPUs	256 P100 GPUs on GCP
Experience collected	~180 years per day (~900 years per day counting each hero separately)
Size of observation	~36.8 kB
Observations per second of gameplay	7.5
Batch size	1,048,576 observations
Batches per minute	~60



# Cam play uses of virtual characters in interactive experiences

- Virtual teammates in team-based games
- Narrative elements
- Coaches, etc.



Learning to race in Tran Truism Sport  
[Wurman et al. 2022]

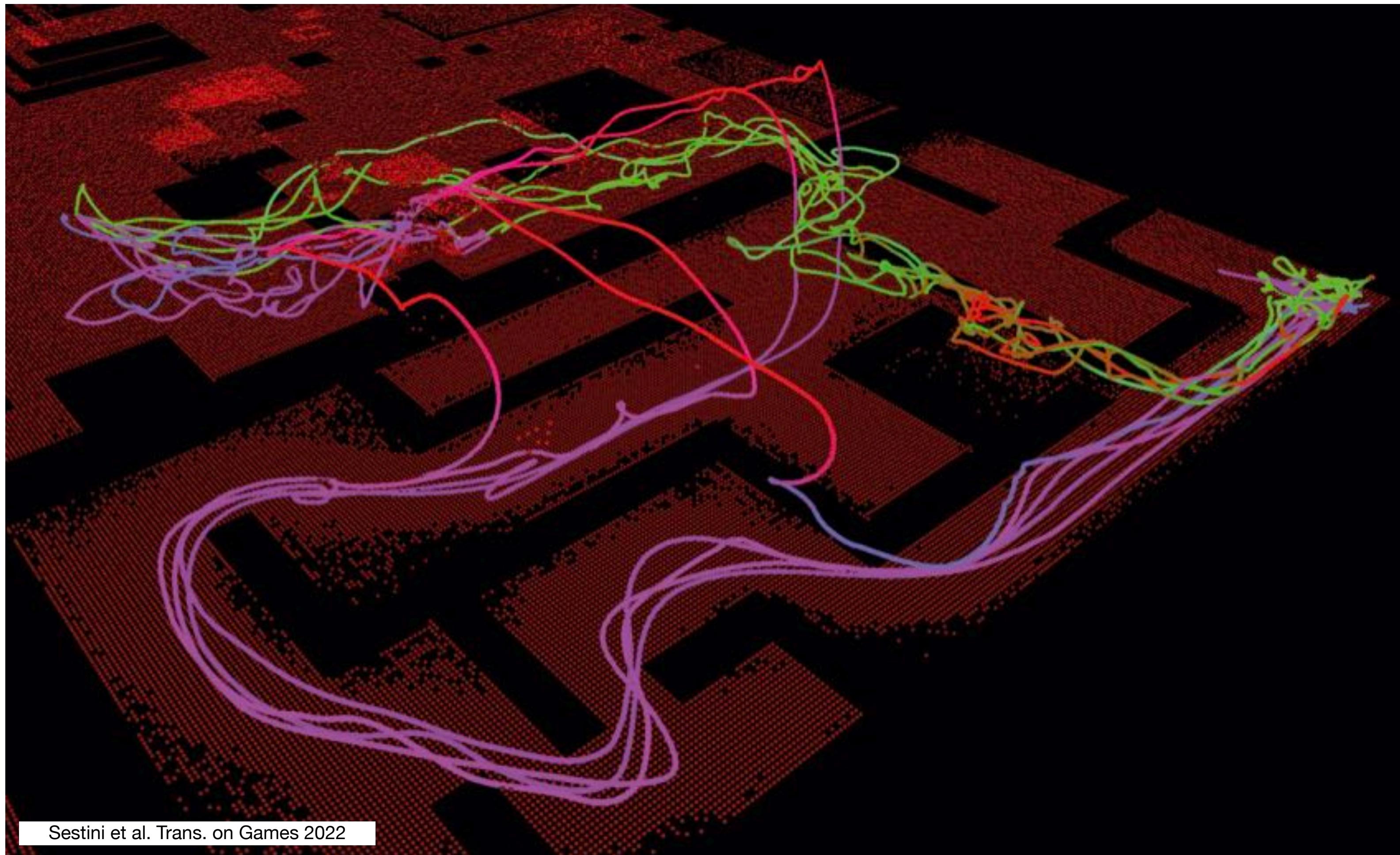


# **Application area 3: video game “verifiers”**

**Using agents as proxy play testers to aid game design**

# As proxies for predicting future behavior of real humans

- Feedback on game design
- Game testing



**Where can a player get to on a map?**

**What sections are not reachable?**

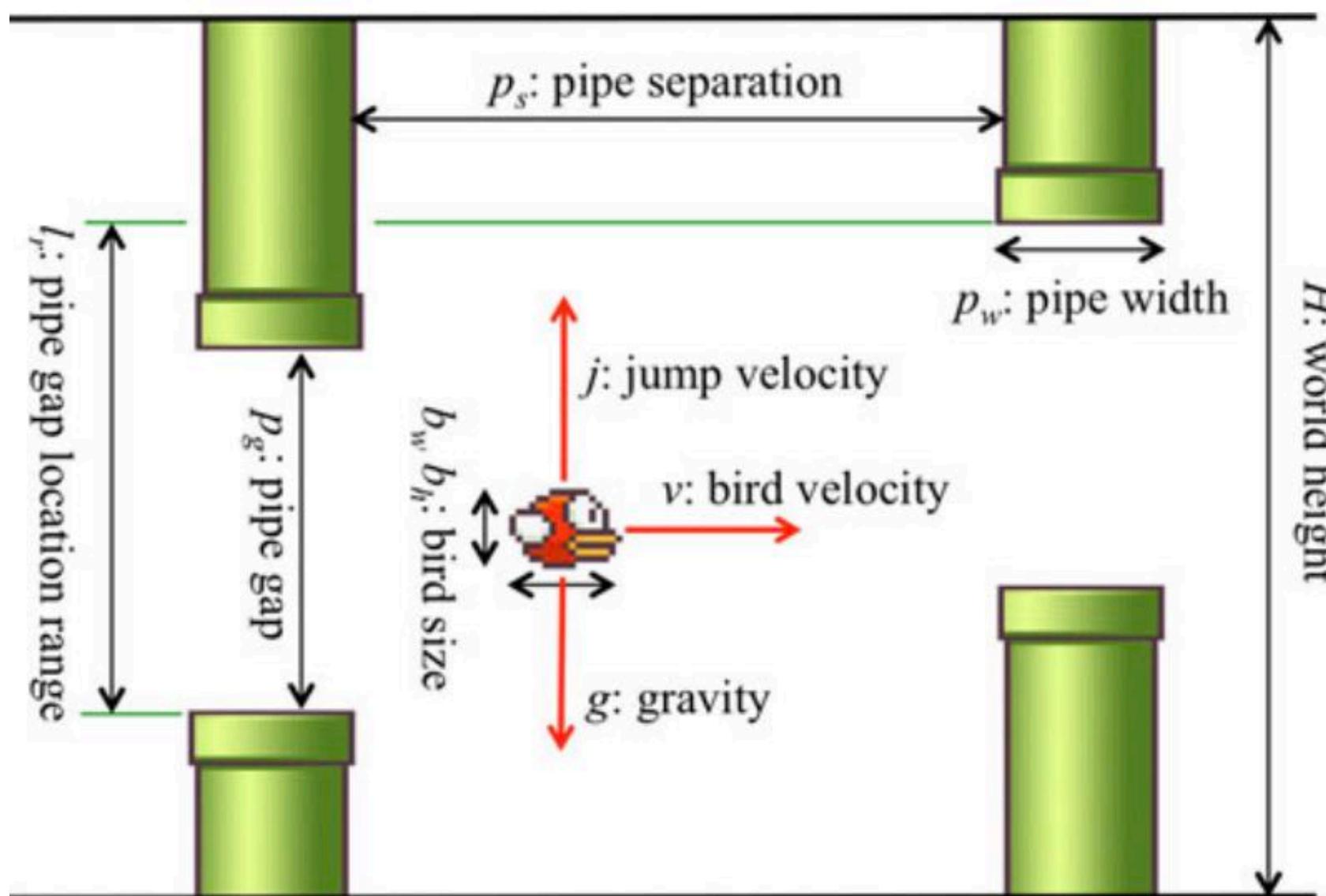
**What sections are reachable but  
should not be?**

**How long does it take to get there?**

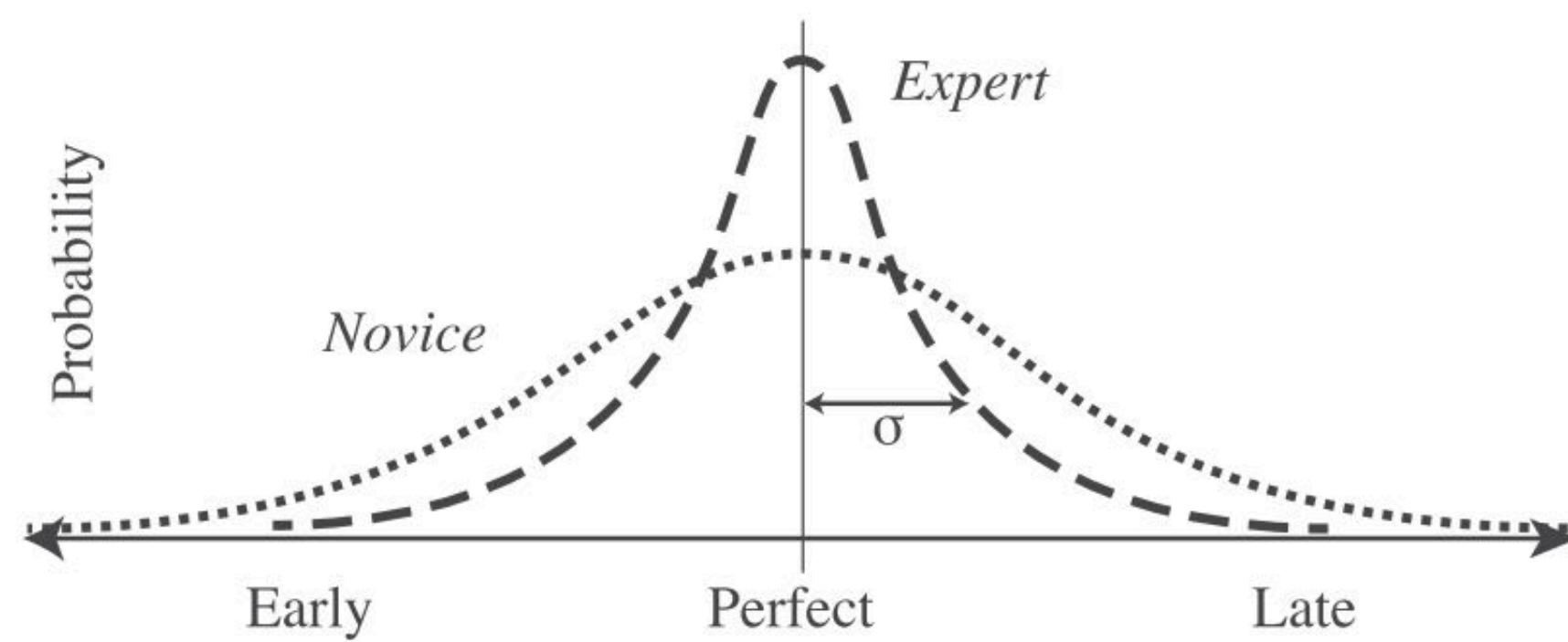
# As proxies for predicting future behavior of real humans

How difficult will future players find a game? And can we adjust difficulty to meet certain experience goals?

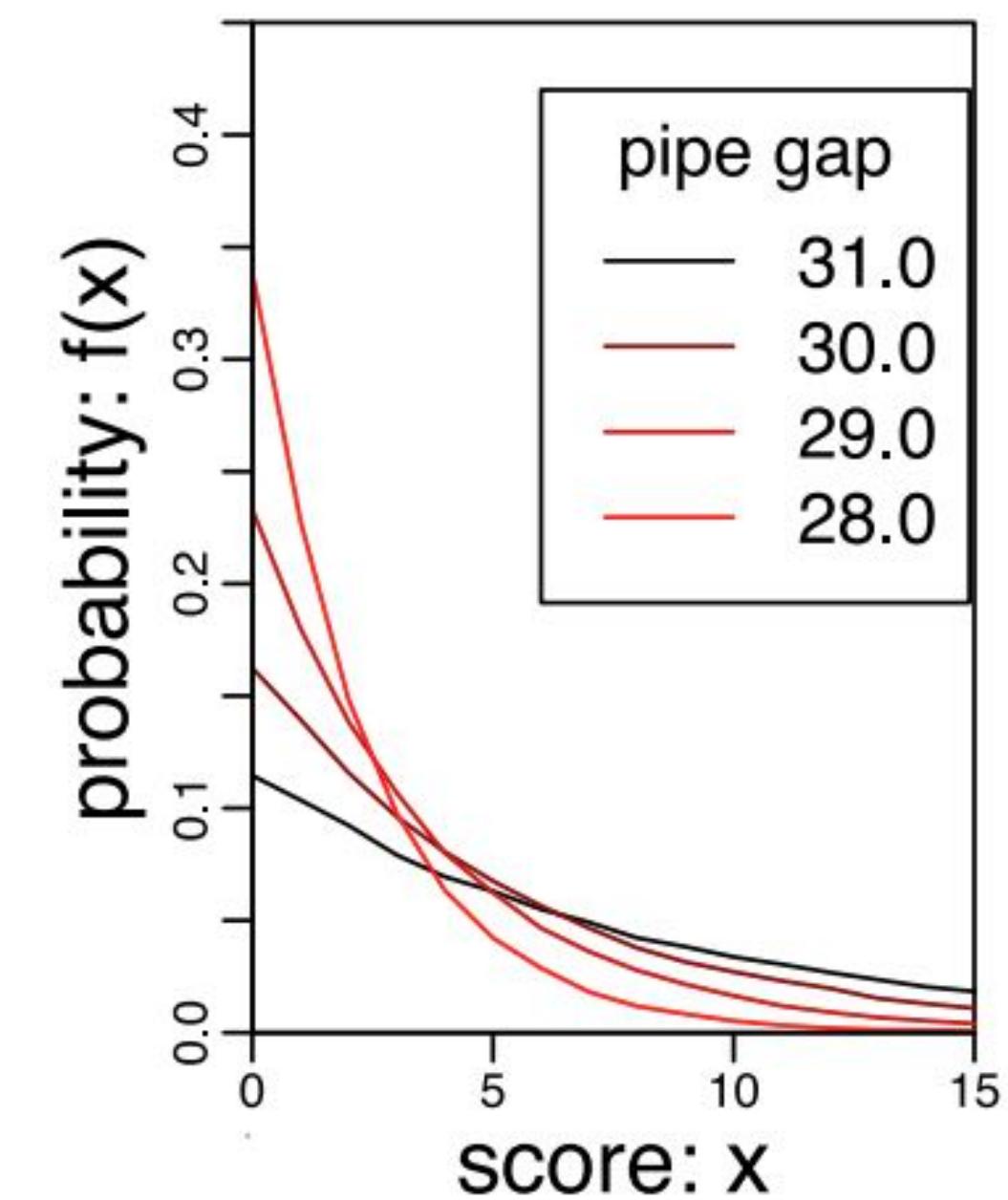
Example from tonight's reading: [Isaksen et al. 2018]



A parameterized game



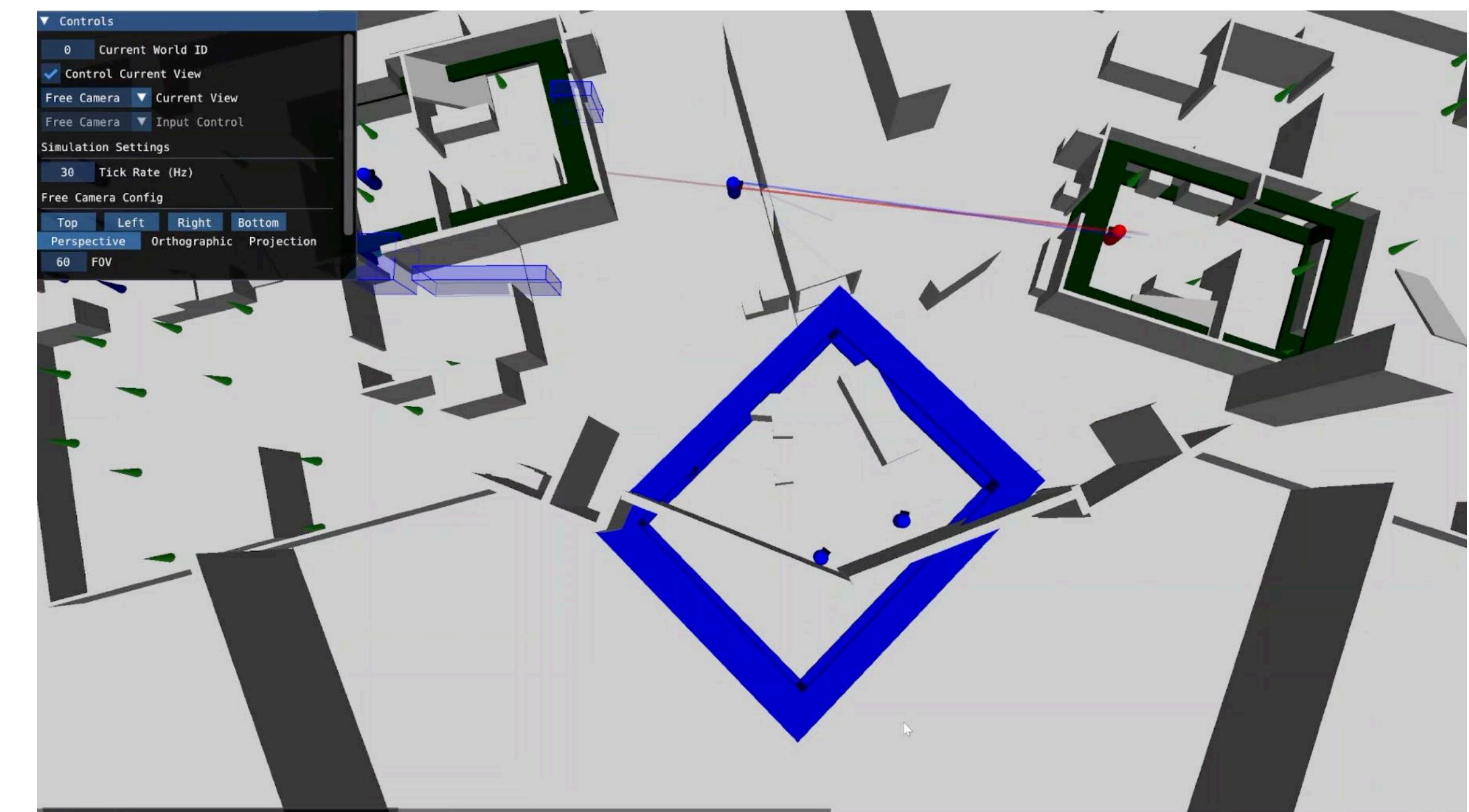
A model of player skill  
(Deviation from optimal play)



Running agent in game generates  
statistics of play (expected score)

# In an area of generative AI, many interesting possibilities for using AI agents to “verify” created content

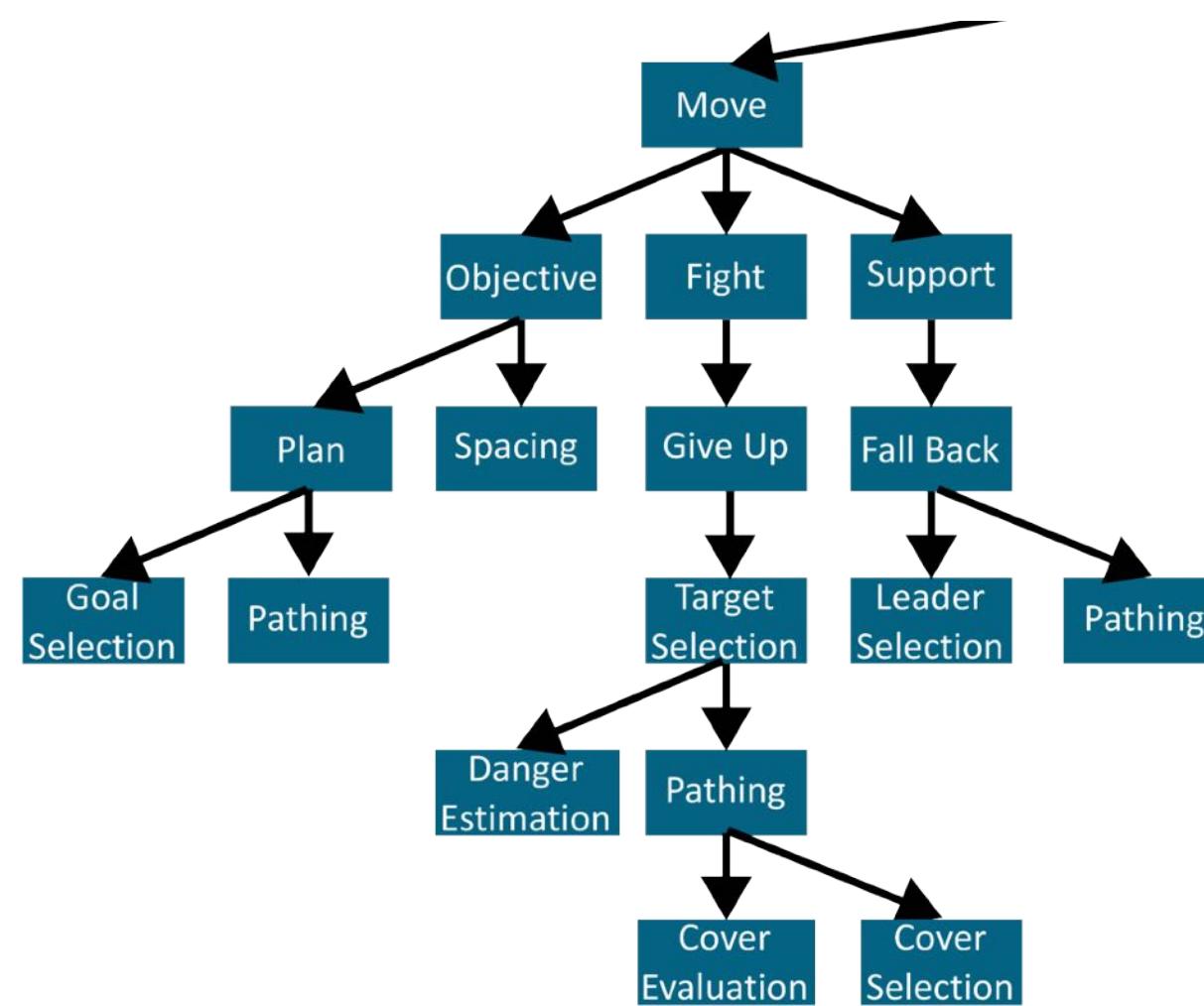
- Is a map for a FPS game fair?
- Does a puzzle have a solution?
- How does changing the damage done by a weapon change game strategy?



# Strategies for designing agents

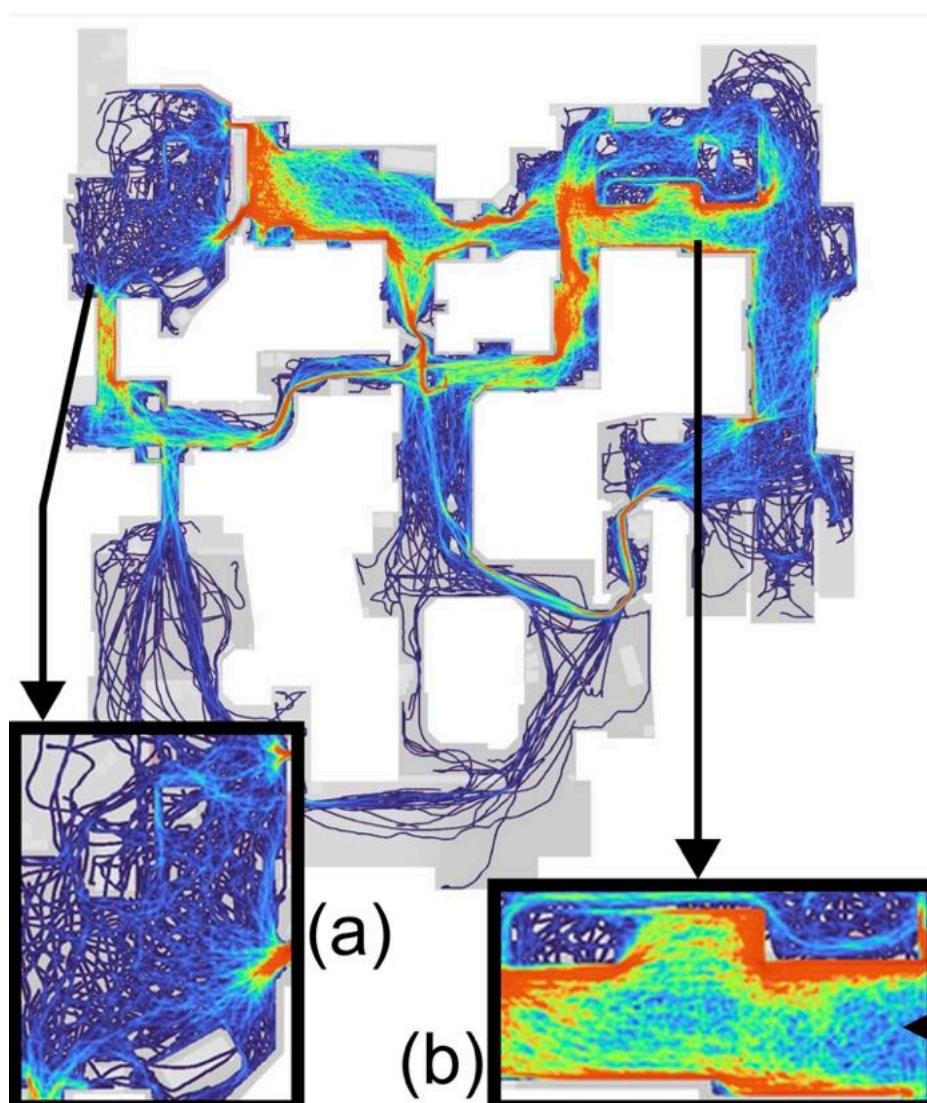
- Major theme of upcoming readings/lectures
- Pros/cons of each approach

**Behavior defined by human-crafted rules**



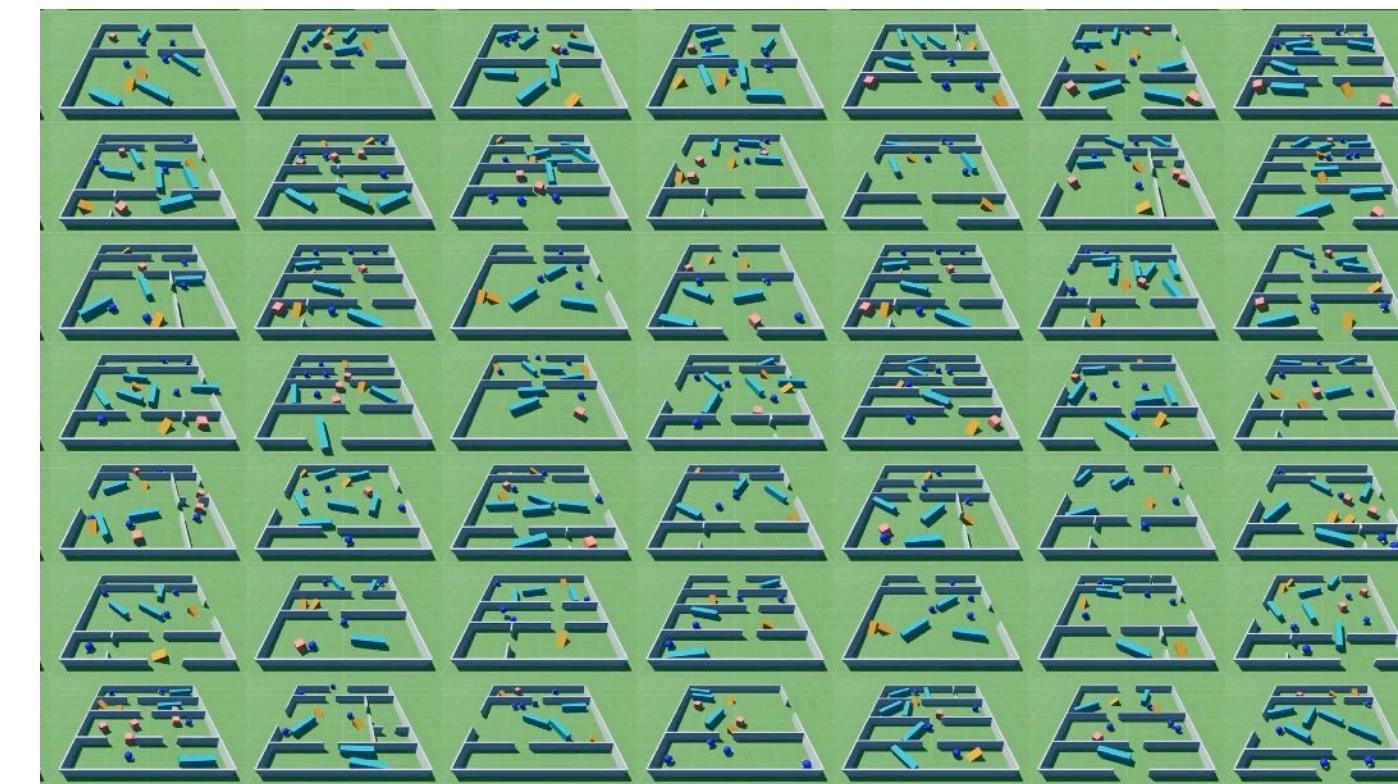
Good: controllable  
Bad: formulaic behavior,  
brittle, laborious to create

**Learn from data (traces of human play)**



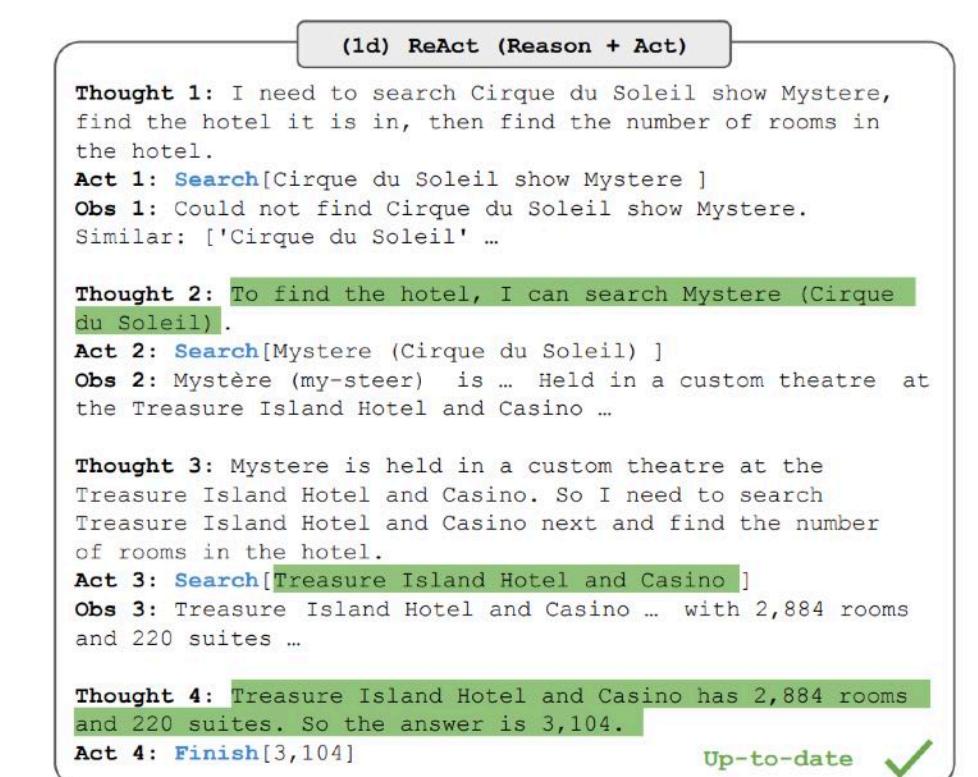
Good: “humanlike” by construction  
Bad: data collection challenges,  
Hard to generalize  
to unseen situations  
(need massive datasets)

**Learn from brute force trial-and-error (RL)**



Good: superhuman skill potential,  
Bad: high cost training,  
difficult to successfully train,  
hard to control behavior

**Leverage common sense embodied by LLM**



Good: low effort to create,  
surprising adept at many tasks  
Bad: lack of grounding in actual  
environment, high runtime cost,  
unpredictable failures

# Full-stack challenges

- **Agent design challenges**
- **Systems challenges**
  - **High-performance execution of training for millions/billions of trials**
  - **Large-scale logging of human traces, new data selection challenges**
- **Evaluation challenges**
  - **How do we design automated metrics of success beyond just “success on task”?**
  - **What is an agent that is “human like”? “Fun to play with?”, “Lacks this skill”**
  - **You’ll see an increasing emphasis on quality of evaluation in our in-class discussions, because evaluating this work is a challenge on its own!**

# Example thought experiment

- You are trying to train an agent to be “fun” to play with in your favorite FPS game
- What does “fun” mean, and how would you evaluate success?

